



## ON $\rho$ -CONTINUOUS FUNCTIONS

C. DEVAMANO HARAN\*

*Post Graduate and Research Department of Mathematics, V. O. Chidambaram College,  
Tuticorin – 628008, Tamil Nadu, INDIA  
E-mail: [kanchidev@gmail.com](mailto:kanchidev@gmail.com)*

S. PIOUS MISSIER

*Post Graduate and Research Department of Mathematics, V.O. Chidambaram College,  
Tuticorin – 628008, Tamil Nadu, INDIA  
E-mail: [smissier@yahoo.com](mailto:smissier@yahoo.com)*

(Received on: 27-02-12; Accepted on: 21-03-12)

### ABSTRACT

*In this paper, we introduce a new class of continuous functions called  $\rho$ -continuous functions by utilizing  $\rho$ -closed sets. Moreover, we study their properties in topological space. It turns out, among others, the  $\rho$ -continuous weaker than perfect continuity and stronger than both  $g\rho$ -continuity and  $\pi g\rho$ -continuity.*

**Keywords:**  $\rho$ -closed set,  $\rho$ -open set,  $\rho$ -continuous function,  $\rho$ -compact space,  $\rho$ -connected space.

**2000 AMS Classification:** 54A05, 54C05, 54C08.

### 1. INTRODUCTION AND PRELIMINARIES

Continuous functions in topology found a valuable place in the applications of mathematics as it has applications to engineering especially to digital signal processing and neural networks. Topologist studied weaker and stronger forms of continuous functions in topology using the sets stronger and weaker than open and closed sets. Balachandran et.al [4], Levine [13], Mashhour et.al [15], Rajesh et.al [21], Gnanambal et.al[10], Park et.al[19] have introduced  $g$  - continuity, semi-continuity, pre-continuity,  $\tilde{g}$ -continuity,  $g\rho$ -continuity and  $\pi g\rho$ -continuity respectively. As generalizations of closed sets,  $\rho$ -closed sets were introduced and studied by the same author[5]. The aim of this paper is to introduce new classes of functions called  $\rho$ -continuous functions. Moreover, the relationships and properties of  $\rho$ -continuous functions are obtained.

Throughout this paper  $(X, \tau)$ ,  $(Y, \sigma)$ ,  $(Z, \eta)$  represent non-empty topological spaces on which no separation axioms are assumed, unless otherwise mentioned.

We recall the following definitions in the sequel.

**Definition 1.1:** Let  $(X, \tau)$  be a topological space. A subset  $A$  of the space  $X$  is said to be

1. Preopen [15] if  $A \subseteq \text{cl}(A)$  and preclosed if  $\text{cl}(\text{int}(A)) \subseteq A$ .
2. Semi-open [13] if  $A \subseteq \text{int}(A)$  and semi-closed if  $\text{int}(\text{cl}(A)) \subseteq A$ .
3. Semi-preopen [1] if  $A \subseteq \text{int}(\text{cl}(A))$  and semi-preclosed if  $\text{int}(\text{cl}(\text{int}(A))) \subseteq A$ .
4. Regular open if  $A = \text{int}(\text{cl}(A))$  and regular closed if  $A = \text{cl}(\text{int}(A))$ .
5.  $\pi$ -open [32] if it a finite union of regular open sets.

Recall that the intersection of all semi-closed (resp. preclosed, semi-preclosed) sets containing  $A$  is called the semi-closure of  $A$  and is denoted by  $\text{scl}(A)$  (resp.  $\text{pcl}(A)$ ,  $\text{spcl}(A)$ ).

**Definition 1.2:** Let  $(X, \tau)$  be a topological space. A subset  $A \subseteq X$  is said to be

1. generalized closed (briefly  $g$ -closed)[ 14 ] if  $\text{cl}(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is open in  $X$ .
2. generalized preclosed (briefly  $gp$ -closed)[17] if  $\text{pcl}(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is open in  $X$ .
3. generalized preregular closed (briefly  $gpr$ -closed)[ 9 ] if  $\text{pcl}(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is regular open in  $X$ .
4. pregeneralized closed (briefly  $pg$ -closed)[ 17 ] if  $\text{pcl}(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is preopen in  $X$ .

\*Corresponding author: C. DEVAMANO HARAN\*, \*E-mail: [kanchidev@gmail.com](mailto:kanchidev@gmail.com)

5.  $g^*$ -preclosed (briefly  $g^*p$ -closed) [ 30 ] if  $pcl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is  $g$ -open in  $X$ .
6. generalized semi-preclosed (briefly  $gsp$ -closed) [ 6 ] if  $spcl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is open in  $X$ .
7. pre semi closed [ 31 ] if  $spcl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is  $g$ -open in  $X$ .
8.  $\hat{g}$ -closed [ 26 ] if  $cl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is semi open in  $X$ .
9.  $\pi gp$ -closed [ 18 ] if  $pcl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is  $\pi$ -open in  $X$ .
10.  $\omega$ -closed [24] if  $cl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is semi open in  $X$ .
11.  $*g$ -closed [ 29 ] if  $cl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is  $\hat{g}$ -open in  $X$ .
12.  $\#g$ - semi closed (briefly  $\#gs$ -closed) [ 28 ] if  $scl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is  $*g$ -open in  $X$ .
13.  $\tilde{g}$ -closed set [12] if  $cl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is  $\#gs$ -open in  $X$ .
14.  $\rho$ -closed set [5] if  $pcl(A) \subseteq (U)$  whenever  $A \subseteq U$  and  $U$  is  $\tilde{g}$ -open in  $X$ .
15.  $\rho_s$ -closed set [5] if  $pcl(A) \subseteq (cl(U))$  whenever  $A \subseteq U$  and  $U$  is  $\tilde{g}$ -open in  $X$ .

The complements of the above mentioned sets are called their respective open sets.

**Definition 1.3:** A function  $f: (X, \tau) \rightarrow (Y, \sigma)$  is called

1. Semi-continuous [13] if  $f^{-1}(V)$  is semi-open in  $(X, \tau)$  for every open set  $V$  in  $(Y, \sigma)$ .
2. Pre-continuous [15] if  $f^{-1}(V)$  is preclosed in  $(X, \tau)$  for every closed set  $V$  in  $(Y, \sigma)$ .
3.  $g$ -continuous [4] if  $f^{-1}(V)$  is  $g$ -closed in  $(X, \tau)$  for every closed set  $V$  in  $(Y, \sigma)$ .
4.  $\omega$ -continuous [23] if  $f^{-1}(V)$  is  $\omega$ -closed in  $(X, \tau)$  for every closed set  $V$  in  $(Y, \sigma)$ .
5.  $gsp$ -continuous [6] if  $f^{-1}(V)$  is  $gsp$ -closed in  $(X, \tau)$  for every closed set  $V$  in  $(Y, \sigma)$ .
6.  $gp$ -continuous [2] if  $f^{-1}(V)$  is  $gp$ -closed in  $(X, \tau)$  for every closed set  $V$  in  $(Y, \sigma)$ .
7.  $gpr$ -continuous [10] if  $f^{-1}(V)$  is  $gpr$ -closed in  $(X, \tau)$  for every closed set  $V$  in  $(Y, \sigma)$ .
8. Semi-Pre-continuous [1] if  $f^{-1}(V)$  is semi-preopen in  $(X, \tau)$  for every open set  $V$  in  $(Y, \sigma)$ .
9. Pre-semi-continuous [31] if  $f^{-1}(V)$  is Pre-semiclosed in  $(X, \tau)$  for every closed set  $V$  in  $(Y, \sigma)$ .
10.  $\pi gp$ -continuous [19] if  $f^{-1}(V)$  is  $\pi gp$ -closed in  $(X, \tau)$  for every closed set  $V$  in  $(Y, \sigma)$ .
11.  $pg$ -continuous [17] if  $f^{-1}(V)$  is  $pg$ -closed in  $(X, \tau)$  for every closed set  $V$  in  $(Y, \sigma)$ .
12.  $g^*p$ -continuous [30] if  $f^{-1}(V)$  is  $g^*p$ -closed in  $(X, \tau)$  for every closed set  $V$  in  $(Y, \sigma)$ .
13.  $\#g$ -semi-continuous [28] if  $f^{-1}(V)$  is  $\#gs$ -closed in  $(X, \tau)$  for every closed set  $V$  in  $(Y, \sigma)$ .
14.  $\tilde{g}$ -continuous [21] if  $f^{-1}(V)$  is  $\tilde{g}$ -closed in  $(X, \tau)$  for every closed set  $V$  in  $(Y, \sigma)$ .
15. Contra-continuous [7] if  $f^{-1}(V)$  is closed in  $(X, \tau)$  for every open set  $V$  in  $(Y, \sigma)$ .
16. Perfectly-continuous [3] if  $f^{-1}(V)$  is both open and closed in  $(X, \tau)$  for every open set  $V$  in  $(Y, \sigma)$ .
17. Contra-Pre-continuous [11] if  $f^{-1}(V)$  is Preclosed in  $(X, \tau)$  for every open set  $V$  in  $(Y, \sigma)$ .
18.  $\tilde{g}$ -irresolute [22] if  $f^{-1}(V)$  is  $\tilde{g}$ -closed in  $(X, \tau)$  for every  $\tilde{g}$ -closed set  $V$  in  $(Y, \sigma)$ .
19.  $M$ -Preclosed [16] if  $f(V)$  is preclosed in  $(Y, \sigma)$  for every preclosed set  $V$  in  $(X, \tau)$ .
20.  $RC$ -continuous [8] if  $f^{-1}(V)$  is regular closed in  $(X, \tau)$  for every open set  $V$  in  $(Y, \sigma)$ .

**Definition 1.4:** A space  $(X, \tau)$  is called

1. a  $T_{1/2}$  space [14] if every  $g$ -closed set is closed.
2. a  $T_\omega$  space [23] if every  $\omega$ -closed set is closed.
3. a  $g_s T_{1/2}^\#$  space [28] if every  $\#g$ -semi-closed set is closed.
4. a  $T_g$  -space [30] if every  $g$ -closed set is closed.

**Theorem 1.5:** [5] (1) Every open and preclosed subset of  $(X, \tau)$  is  $\rho$ -closed. Converse need not be true.

(2) Every  $\rho$ -closed set is  $\rho_s$ -closed (resp.  $gp$ -closed,  $gpr$ -closed,  $gsp$ -closed,  $\pi gp$ -closed) set. Converse need not be true.

(3) If  $D[A] \subseteq D_p[A]$  for each subset  $A$  of a space  $(X, \tau)$ , then the union of two  $\rho$ -closed sets is  $\rho$ -closed.

(4) A subset  $A$  of  $(X, \tau)$  is regular open if  $A$  is both open and  $\rho$ -closed.

## 2. $\rho$ -CONTINUOUS FUNCTIONS

**Definition 2.1:**

- i) A function  $f: (X, \tau) \rightarrow (Y, \sigma)$  is said to be  $\rho$ -continuous (resp.  $\rho_s$ -continuous) if  $f^{-1}(V)$  is  $\rho$ -closed (resp.  $\rho_s$ -closed) in  $(X, \tau)$  for every closed set  $V$  in  $(Y, \sigma)$ .
- ii) A function  $f: (X, \tau) \rightarrow (Y, \sigma)$  is said to be  $\rho$ -irresolute (resp.  $\rho_s$ -irresolute) if  $f^{-1}(V)$  is  $\rho$ -closed (resp.  $\rho_s$ -closed) in  $(X, \tau)$  for every  $\rho$ -closed (resp.  $\rho_s$ -closed)  $V$  in  $(Y, \sigma)$ .

**Example 2.2:** 1. Let  $X=Y=\{a, b, c, d\}$ ,  $\tau = \{\emptyset, \{b\}, \{c\}, \{b, c\}, \{b, c, d\}, X\}$  and  $\sigma = \{\emptyset, \{a, b\}, X\}$ . Define a function  $f: (X, \tau) \rightarrow (Y, \sigma)$  by  $f(a) = f(b) = c$ ,  $f(c) = d$ ,  $f(d) = a$ . Then  $f$  is  $\rho$ -continuous.

2. Let  $X=\{a, b, c\}$ ,  $\tau=\{\emptyset, \{c\}, \{a, b\}, X\}$  and  $\sigma=\{\emptyset, \{a, b\}, X\}$ . Define  $f: (X, \tau) \rightarrow (Y, \sigma)$  by  $f(a)=c$ ,  $f(b)=b$  and  $f(c)=a$ . Then the inverse image of every  $\rho$ -closed set is  $\rho$ -closed under  $f$ . Hence  $f$  is  $\rho$ -irresolute.

**Proposition 2.3:** Every Contra-continuous and Pre-continuous is  $\rho$ -continuous.

**Proof:** Let  $f: (X, \tau) \rightarrow (Y, \sigma)$  be Contra- continuous and pre-continuous. Let  $V$  be closed in  $(Y, \sigma)$ . Then  $f^{-1}(V)$  is preclosed and also open in  $(X, \tau)$ . Hence by Theorem 1.5(1),  $f^{-1}(V)$  is  $\rho$ -closed in  $(X, \tau)$ . Therefore  $f$  is  $\rho$ -continuous.

The converse of the above proposition need not be true as it is seen from the following example.

**Example 2.4:** Let  $X = \{a, b, c, d, e\}$ ,  $Y = \{a, b, c, d\}$ ,  $\tau = \{\emptyset, \{a, b\}, \{a, b, d\}, \{a, b, c, d\}, \{a, b, d, e\}, X\}$  and  $\sigma = \{\emptyset, \{b, c\}, \{a, b, c\}, \{b, c, d\}, Y\}$ . Define  $f: (X, \tau) \rightarrow (Y, \sigma)$  by  $f(a) = d$ ;  $f(b) = a$ ;  $f(c) = a$ ;  $f(d) = b$ ;  $f(e) = d$ . Then  $f$  is  $\rho$ -continuous but neither contra-continuous nor pre-continuous. Observe that for the closed set  $V = \{a, d\}$  in  $(Y, \sigma)$ ,  $f^{-1}(V) = \{a, b, c, e\}$  is  $\rho$ -closed and it is neither preclosed nor open in  $(X, \tau)$ .

**Proposition 2.5:** Every  $\rho$ -continuous is gp-continuous.

**Proof:** By Theorem 1.5(2), every  $\rho$ -closed set is gp-closed, the Proof follows.

The converse of the above proposition need not be true as it is seen from the following example.

**Example 2.6:** Let  $X = Y = \{a, b, c, d, e\}$ ,  $\tau = \{\emptyset, \{b, c, d\}, \{a, b, c, d\}, \{b, c, d, e\}, X\}$  and  $\sigma = \{\emptyset, \{a, b, e\}, X\}$ . Define  $f: (X, \tau) \rightarrow (X, \sigma)$  by  $f(a) = e$ ,  $f(b) = c$ ,  $f(c) = d$ ,  $f(d) = a$ ,  $f(e) = b$ . Then  $f$  is gp-continuous but not  $\rho$ -continuous. Observe that for the closed set  $V = \{c, d\}$  in  $(X, \sigma)$ ,  $f^{-1}(V) = \{b, c\}$  is gp-closed but not  $\rho$ -closed in  $(X, \tau)$ .

**Proposition 2.7:** Every  $\rho$ -continuous is gpr-continuous.

**Proof:** By Theorem 1.5(2), every  $\rho$ -closed set is gpr-closed, the proof follows.

The converse of the above proposition need not be true as it is seen from the following example.

**Example 2.8:** Let  $X = \{a, b, c, d, e\}$ ,  $Y = \{a, b, c, d\}$ ,  $\tau = \{\emptyset, \{c\}, \{e\}, \{a, b\}, \{c, e\}, \{a, b, c\}, \{a, b, e\}, \{a, b, c, e\}, X\}$  and  $\sigma = \{\emptyset, \{c, d\}, Y\}$ . Define  $f: (X, \tau) \rightarrow (Y, \sigma)$  by  $f(a) = f(c) = a$ ;  $f(b) = f(e) = b$ ;  $f(d) = c$ . Then  $f$  is gpr-continuous but not  $\rho$ -continuous. Observe that for the closed set  $V = \{a, b\}$  in  $(Y, \sigma)$ ,  $f^{-1}(V) = \{a, b, c, e\}$  is gpr-closed but not  $\rho$ -closed in  $(X, \tau)$ .

**Proposition 2.9:** Every  $\rho$ -continuous is gsp-continuous.

**Proof:** By Theorem 1.5(2), every  $\rho$ -closed set is gsp-closed, the proof follows.

The converse of the above proposition need not be true as it is seen from the following example.

**Example 2.10:** Let  $X = \{a, b, c, d, e\}$ ,  $Y = \{a, b, c\}$ ,  $\tau = \{\emptyset, \{a, b\}, \{c, d\}, \{a, b, c, d\}, X\}$  and  $\sigma = \{\emptyset, \{c\}, \{b, c\}, Y\}$ . Define  $f: (X, \tau) \rightarrow (Y, \sigma)$  by  $f(a) = b$ ;  $f(b) = a$ ;  $f(c) = a$ ;  $f(d) = c$ ;  $f(e) = c$ . Then  $f$  is gsp-continuous but not  $\rho$ -continuous. Observe that for the closed set  $V = \{a, b\}$  in  $(Y, \sigma)$ ,  $f^{-1}(V) = \{a, b, c\}$  is gsp-closed but not  $\rho$ -closed in  $(X, \tau)$ .

**Proposition 2.11:** Every  $\rho$ -continuous is  $\pi$ gp-continuous.

**Proof:** By Theorem 1.5(2), every  $\rho$ -closed set is  $\pi$ gp-closed, the proof follows.

The converse of the above proposition need not be true as it is seen from the following example.

**Example 2.12:** Let  $X = \{a, b, c, d, e\}$ ,  $Y = \{a, b, c, d\}$ ,  $\tau = \{\emptyset, \{a, b\}, \{c, d\}, \{a, b, c, d\}, X\}$  and  $\sigma = \{\emptyset, \{b, c\}, \{a, b, c\}, \{b, c, d\}, Y\}$ . Define  $f: (X, \tau) \rightarrow (Y, \sigma)$  by  $f(a) = d$ ;  $f(b) = c$ ;  $f(c) = c$ ;  $f(d) = a$ ;  $f(e) = b$ . Then  $f$  is  $\pi$ gp-continuous but not  $\rho$ -continuous. Observe that for the closed set  $V = \{a, d\}$  in  $(Y, \sigma)$ ,  $f^{-1}(V) = \{a, d\}$  is  $\pi$ gp-closed but not  $\rho$ -closed in  $(X, \tau)$ .

**Remark 2.13:**  $\rho$ -continuous and pre-continuous are independent concepts as we illustrate by means of the following examples.

**Example 2.14:**

1. Let  $X = \{a, b, c, d, e\}$ ,  $Y = \{a, b, c, d\}$ ,  $\tau = \{\emptyset, \{a, b\}, \{a, b, d\}, \{a, b, c, d\}, \{a, b, d, e\}, X\}$  and  $\sigma = \{\emptyset, \{b, c\}, \{a, b, c\}, \{b, c, d\}, Y\}$ . Define  $f: (X, \tau) \rightarrow (Y, \sigma)$  by  $f(a) = d$ ;  $f(b) = a$ ;  $f(c) = a$ ;  $f(d) = b$ ;  $f(e) = d$ . Then  $f$  is  $\rho$ -continuous but not pre-continuous. It is clear that for the closed set  $V = \{a, d\}$  in  $(Y, \sigma)$ ,  $f^{-1}(V) = \{a, b, c, e\}$  is  $\rho$ -closed but not preclosed in  $(X, \tau)$ .
2. Let  $X = \{a, b, c, d, e\}$ ,  $Y = \{a, b, c, d\}$ ,  $\tau = \{\emptyset, \{a, b\}, \{a, b, c\}, \{a, b, d\}, \{a, b, c, d\}, X\}$  and  $\sigma = \{\emptyset, \{a, b\}, \{a, b, c\}, Y\}$ . Define  $f: (X, \tau) \rightarrow (Y, \sigma)$  by  $f(a) = d$ ;  $f(b) = b$ ;  $f(c) = a$ ;  $f(d) = c$ ;  $f(e) = c$ . Then  $f$  is pre-continuous but not  $\rho$ -continuous. Observe that for the closed set  $V = \{d\}$  in  $(Y, \sigma)$ ,  $f^{-1}(V) = \{a\}$  is preclosed but not  $\rho$ -closed in  $(X, \tau)$ .

**Remark 2.15:**  $\rho$ -continuous is independent concept of semi-continuous and semi-pre-continuous as we illustrate by means of the following examples.

**Example 2.16:**

1. Let  $X = \{a, b, c, d\} = Y$ ,  $\tau = \{\phi, \{b\}, \{c\}, \{b, c\}, \{b, c, d\}, X\}$  and  $\sigma = \{\phi, \{a, b\}, X\}$ . Define  $f: (X, \tau) \rightarrow (X, \sigma)$  by  $f(a) = c = f(b)$ ;  $f(c) = d$ ;  $f(d) = a$ . Then  $f$  is  $\rho$ -continuous but neither semi-continuous nor semi-pre-continuous. Since for the closed set  $V = \{c, d\}$  in  $(X, \sigma)$ ,  $f^{-1}(V) = \{a, b, c\}$  is  $\rho$ -closed but neither semi-closed nor semi-pre-closed in  $(X, \tau)$ .
2. Let  $X = \{a, b, c, d\} = Y$ ,  $\tau = \{\phi, \{b\}, \{c\}, \{b, c\}, \{b, c, d\}, X\}$  and  $\sigma = \{\phi, \{c, d\}, X\}$ . Define  $f: (X, \tau) \rightarrow (X, \sigma)$  by  $f(a) = d$ ;  $f(b) = c$ ;  $f(c) = a$ ;  $f(d) = b$ . Then  $f$  is both semi-continuous and semi-pre-continuous but not  $\rho$ -continuous. Observe that for the closed set  $V = \{a, b\}$  in  $(X, \sigma)$ ,  $f^{-1}(V) = \{c, d\}$  is both semi-closed and semi-pre-closed but not  $\rho$ -closed in  $(X, \tau)$ .

**Remark 2.17:**  $\rho$ -continuous and pre-semi-continuous are independent concepts as we illustrate by means of the following examples.

**Example 2.18:**

1. Let  $X = \{a, b, c\} = Y$ ,  $\tau = \{\phi, \{a\}, \{c\}, \{c, a\}, X\}$  and  $\sigma = \{\phi, \{a, b\}, X\}$ . Define  $f: (X, \tau) \rightarrow (X, \sigma)$  by  $f(a) = c$ ;  $f(b) = a$ ;  $f(c) = b$ . Then  $f$  is pre-semi-continuous but not  $\rho$ -continuous. For the closed set  $V = \{c\}$  in  $(X, \sigma)$ ,  $f^{-1}(V) = \{a\}$  is pre-semi-closed but not  $\rho$ -closed in  $(X, \tau)$ .
2. Let  $X = \{a, b, c\} = Y$ ,  $\tau = \{\phi, \{c\}, X\}$  and  $\sigma = \{\phi, \{a, b\}, X\}$ . Define  $f: (X, \tau) \rightarrow (X, \sigma)$  by  $f(a) = a$ ;  $f(b) = f(c) = c$ . Then  $f$  is  $\rho$ -continuous but not pre-semi-continuous. Observe that for the closed set  $V = \{c\}$  in  $(X, \sigma)$ ,  $f^{-1}(V) = \{b, c\}$  is  $\rho$ -closed but not pre-semi-closed in  $(X, \tau)$ .

**Remark 2.19:**  $\rho$ -continuous and  $pg$ -continuous are independent concepts as we illustrate by means of the following examples.

**Example 2.20:**

1. Let  $X = \{a, b, c, d, e\} = Y$ ,  $\tau = \{\phi, \{a\}, \{d, e\}, \{a, d, e\}, X\}$  and  $\sigma = \{\phi, \{b\}, \{d, e\}, \{b, d, e\}, \{a, c, d, e\}, X\}$ . Define  $f: (X, \tau) \rightarrow (X, \sigma)$  by  $f(a) = d$ ;  $f(b) = b$ ;  $f(c) = a$ ;  $f(d) = e$ ;  $f(e) = c$ . Then  $f$  is  $\rho$ -continuous but not  $pg$ -continuous. So for the closed set  $V = \{a, c, d, e\}$  in  $(X, \sigma)$ ,  $f^{-1}(V) = \{a, c, d, e\}$  is  $\rho$ -closed but not  $pg$ -closed in  $(X, \tau)$ .
2. Let  $X = \{a, b, c, d, e\}$ ,  $Y = \{a, b, c, d\}$ ,  $\tau = \{\phi, \{a, b\}, \{c, d\}, \{a, b, c, d\}, X\}$  and  $\sigma = \{\phi, \{a, b\}, \{c, d\}, Y\}$ . Define  $f: (X, \tau) \rightarrow (Y, \sigma)$  by  $f(a) = c$ ;  $f(b) = b$ ;  $f(c) = a$ ;  $f(d) = d$ ;  $f(e) = a$ . Then  $f$  is  $pg$ -continuous but not  $\rho$ -continuous. Observe that for the closed set  $V = \{c, d\}$  in  $(Y, \sigma)$ ,  $f^{-1}(V) = \{a, d\}$  is  $pg$ -closed but not  $\rho$ -closed in  $(X, \tau)$ .

**Remark 2.21:**  $\rho$ -continuous and  $g^*p$ -continuous are independent concepts as we illustrate by means of the following examples.

**Example 2.22:**

1. Let  $X = \{a, b, c, d, e\} = Y$ ,  $\tau = \{\phi, \{b\}, \{d, e\}, \{b, d, e\}, \{a, c, d, e\}, X\}$  and  $\sigma = \{\phi, \{a\}, \{d, e\}, \{a, d, e\}, X\}$ . Define  $f: (X, \tau) \rightarrow (X, \sigma)$  by  $f(a) = b$ ;  $f(b) = c$ ;  $f(c) = a$ ;  $f(d) = e$ ;  $f(e) = d$ . Then  $f$  is  $\rho$ -continuous but not  $g^*p$ -continuous. Obviously for the closed set  $V = \{b, c, d, e\}$  in  $(X, \sigma)$ ,  $f^{-1}(V) = \{a, b, d, e\}$  is  $\rho$ -closed but not  $g^*p$ -closed in  $(X, \tau)$ .
2. Let  $X = \{a, b, c, d, e\}$ ,  $Y = \{a, b, c\}$ ,  $\tau = \{\phi, \{b\}, \{d, e\}, \{b, d, e\}, \{a, c, d, e\}, X\}$  and  $\sigma = \{\phi, \{a, b\}, Y\}$ . Define  $f: (X, \tau) \rightarrow (Y, \sigma)$  by  $f(a) = f(b) = a$ ;  $f(c) = f(e) = b$ ;  $f(d) = c$ . Then  $f$  is  $g^*p$ -continuous but not  $\rho$ -continuous. Observe that for the closed set  $V = \{c\}$  in  $(Y, \sigma)$ ,  $f^{-1}(V) = \{d\}$  is  $g^*p$ -closed but not  $\rho$ -closed in  $(X, \tau)$ .

**Remark 2.23:**  $\rho$ -continuous and  $g$ -continuous are independent concepts as we illustrate by means of the following examples.

**Example 2.24:**

1. Let  $X = \{a, b, c, d, e\} = Y$ ,  $\tau = \{\phi, \{a, b\}, \{a, b, d\}, \{a, b, c, d\}, \{a, b, d, e\}, X\}$  and  $\sigma = \{\phi, \{a, b\}, \{c, d\}, \{a, b, c, d\}, X\}$ . Define  $f: (X, \tau) \rightarrow (X, \sigma)$  by  $f(a) = a$ ;  $f(b) = c$ ;  $f(c) = b$ ;  $f(d) = d$ ;  $f(e) = e$ . Then  $f$  is  $\rho$ -continuous but not  $g$ -continuous. It is clear that for the closed set  $V = \{c, d, e\}$  in  $(X, \sigma)$ ,  $f^{-1}(V) = \{b, d, e\}$  is  $\rho$ -closed but not  $g$ -closed in  $(X, \tau)$ .
2. Let  $(X, \kappa)$  be digital topology and  $(X, \tau)$  be usual topology. Define  $f: (X, \kappa) \rightarrow (X, \tau)$  by  $f(x) = x$ . Let  $\{4\}$  be closed in  $(X, \tau)$ . Then  $f^{-1}(\{4\}) = \{4\}$  is closed in  $(X, \kappa)$  and thus  $g$ -closed but not  $\rho$ -closed in  $(X, \kappa)$ . Because there is a  $\tilde{g}$ -open set  $U = \{1, 2, 3, 4\}$  containing  $\{4\}$ , is not open in  $(X, \kappa)$  such that  $\text{pcl}(\{4\}) = \{4\} \not\subseteq \text{int}(U) = \{1, 2, 3\}$ . Hence  $f$  is  $g$ -continuous but not  $\rho$ -continuous.

**Remark 2.25:**  $\rho$ -continuous and continuous are independent concepts as we illustrate by means of the following examples.

**Example 2.26:** By Example 2.16(1),  $f$  is  $\rho$ -continuous but not continuous. Since for the closed set  $V = \{c, d\}$  in  $(X, \sigma)$ ,  $f^{-1}(V) = \{a, b, c\}$  is  $\rho$ -closed but not closed in  $(X, \tau)$  and by Example 2.24(2),  $f$  is continuous but not  $\rho$ -continuous. Since for the closed set  $V = \{4\}$  in  $(X, \tau)$ ,  $f^{-1}(V) = \{4\}$  is closed but not  $\rho$ -closed in  $(X, \kappa)$ .

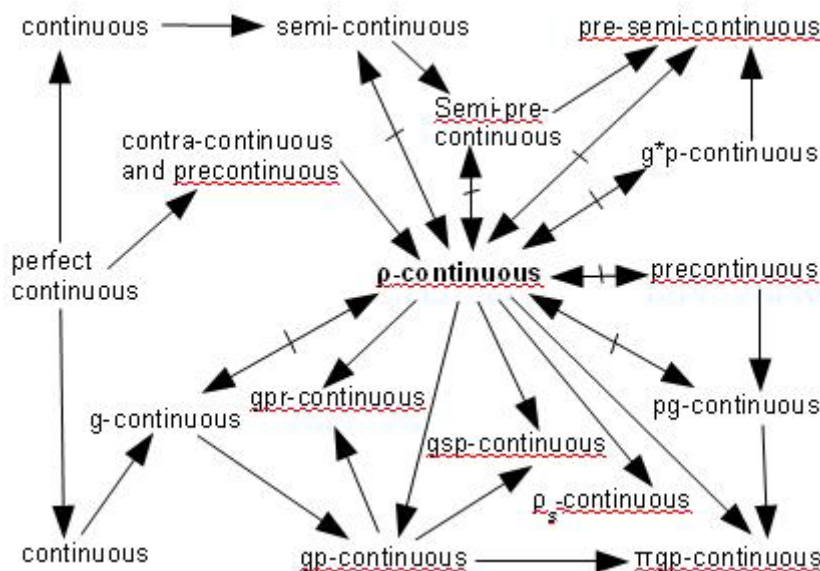
**Proposition 2.27:** Every  $\rho$ -continuous is  $\rho_s$ -continuous.

**Proof:** By Theorem 1.5(2), every  $\rho$ -closed set is  $\rho_s$ -closed, the proof follows.

The converse of the above proposition need not be true as it is seen from the following example.

**Example 2.28:** Let  $X = \{a, b, c, d, e\}$ ,  $Y = \{a, b, c, d\}$ ,  $\tau = \{\emptyset, \{a, b\}, \{c, d\}, \{a, b, c, d\}, X\}$  and  $\sigma = \{\emptyset, \{b, c\}, \{a, b, c\}, \{b, c, d\}, Y\}$ . Define  $f: (X, \tau) \rightarrow (Y, \sigma)$  by  $f(a) = d$ ;  $f(b) = c$ ;  $f(c) = e$ ;  $f(d) = a$ ;  $f(e) = b$ . Then  $f$  is  $\rho_s$ -continuous but not  $\rho$ -continuous. For the closed set  $V = \{a, d\}$  in  $(Y, \sigma)$ ,  $f^{-1}(V) = \{a, d\}$  is  $\rho_s$ -closed but not  $\rho$ -closed in  $(X, \tau)$ .

**Remark 2.29:** We have the following relationship between  $\rho$ -continuous and other related generalized continuous.  $A \rightarrow B$  ( $A \nleftrightarrow B$ ) represent  $A$  implies  $B$  but not conversely ( $A$  and  $B$  are independent of each other).



### 3. CHARACTERIZATION OF $\rho$ -CONTINUOUS FUNCTIONS

Now we shall obtain characterization of  $\rho$ -continuous functions in the sense of Definition 2.1.

**Theorem 3.1:** A function  $f: (X, \tau) \rightarrow (Y, \sigma)$  is  $\rho$ -continuous if and only if  $f^{-1}(U)$  is  $\rho$ -open in  $(X, \tau)$ , for every open set  $U$  in  $(Y, \sigma)$ .

**Proof:** Let  $f: (X, \tau) \rightarrow (Y, \sigma)$  be  $\rho$ -continuous and  $U$  an open set in  $(Y, \sigma)$ . Then  $f^{-1}(U^c)$  is  $\rho$ -closed in  $(X, \tau)$ . But  $f^{-1}(U^c) = (f^{-1}(U))^c$  and so  $f^{-1}(U)$  is  $\rho$ -open in  $(X, \tau)$ . The converse is analogous.

**Remark 3.2:** The composition of two  $\rho$ -continuous function need not be  $\rho$ -continuous and this is shown by the following example.

**Example 3.3:** Let  $X = \{a, b, c\}$ ,  $\tau = \{\emptyset, \{b\}, X\}$ ,  $\sigma = \{\emptyset, \{a, b\}, X\}$  and  $\eta = \{\emptyset, \{a\}, \{a, b\}, X\}$ . Define  $f: (X, \tau) \rightarrow (X, \sigma)$  by  $f(a)=c$ ;  $f(b)=a$ ;  $f(c)=b$  and define  $g: (X, \sigma) \rightarrow (X, \eta)$  by  $g(a)=c$ ;  $g(b)=a$  and  $g(c)=b$ . Then  $f$  and  $g$  are  $\rho$ -continuous but  $g \circ f$  is not  $\rho$ -continuous. Since  $\{c\}$  is closed in  $(X, \eta)$ ,  $(g \circ f)^{-1}(\{c\}) = f^{-1}(g^{-1}(\{c\})) = f^{-1}(\{a\}) = \{b\}$  which is not  $\rho$ -closed in  $(X, \tau)$ .

#### Definition 3.4:

- 1) A space  $(X, \tau)$  is said to be  $\rho$ - $T_s$  space if every  $\rho_s$ -closed set is closed.
- 2) A space  $(X, \tau)$  is said to be  $\rho$ - $T_{1/2}$  space if every  $\rho_s$ -closed set is preclosed.

**Theorem 3.5:** If  $(X, \tau)$  and  $(Z, \eta)$  be topological spaces and  $(Y, \sigma)$  be  $\rho$ - $T_s$  space then the composition  $g \circ f: (X, \tau) \rightarrow (Z, \eta)$  of  $\rho$ -continuous (resp. continuous) function  $f: (X, \tau) \rightarrow (Y, \sigma)$  and the  $\rho_s$ -continuous function  $g: (Y, \sigma) \rightarrow (Z, \eta)$  is  $\rho$ -continuous (resp. continuous).

**Proof:** Let  $G$  be any closed set of  $(Z, \eta)$ . Then by assumption  $g^{-1}(G)$  is closed in  $(Y, \sigma)$ . Since  $f$  is  $\rho$ -continuous, then  $f^{-1}(g^{-1}(G)) = (g \circ f)^{-1}(G)$  is  $\rho$ -closed (resp. closed) in  $(X, \tau)$ . Thus  $g \circ f$  is  $\rho$ -continuous (resp. continuous).

**Theorem 3.6:** Let  $(X, \tau)$  and  $(Z, \eta)$  be any topological spaces and  $(Y, \sigma)$  be  $T_{1/2}$  space (resp.  $T_\omega$  space,  $T_g$  space,  $g_s T_{1/2}$  space). Then the composition  $g \circ f: (X, \tau) \rightarrow (Z, \eta)$  of  $\rho$ -continuous function  $f: (X, \tau) \rightarrow (Y, \sigma)$  and the  $g$ -continuous (resp.  $\omega$ -continuous,  $\tilde{g}$ -continuous,  $\#g_s$ -continuous) function  $g: (Y, \sigma) \rightarrow (Z, \eta)$  is  $\rho$ -continuous.

**Proof:** Let  $G$  be any closed set of  $(Z, \eta)$ . Then  $g^{-1}(G)$  is  $g$ -closed (resp.  $\omega$ -closed,  $\tilde{g}$ -closed,  $\#g_s$ -closed) in  $(Y, \sigma)$  and by assumption,  $g^{-1}(G)$  is closed in  $(Y, \sigma)$ . Since  $f$  is  $\rho$ -continuous,  $f^{-1}(g^{-1}(G)) = (g \circ f)^{-1}(G)$  is  $\rho$ -closed in  $(X, \tau)$ . Thus  $g \circ f$  is  $\rho$ -continuous.

**Theorem 3.7:** If  $f: (X, \tau) \rightarrow (Y, \sigma)$  is  $\rho$ -continuous and  $g: (Y, \sigma) \rightarrow (Z, \eta)$  is continuous. Then their composition  $g \circ f: (X, \tau) \rightarrow (Z, \eta)$  is  $\rho$ -continuous.

**Proof:** Let  $G$  be any closed set of  $(Z, \eta)$ . Then  $g^{-1}(G)$  is closed in  $(Y, \sigma)$ . Since  $f$  is  $\rho$ -continuous,  $f^{-1}(g^{-1}(G)) = (g \circ f)^{-1}(G)$  is  $\rho$ -closed in  $(X, \tau)$ . Thus  $g \circ f$  is  $\rho$ -continuous.

**Theorem 3.8:** If  $f: (X, \tau) \rightarrow (Y, \sigma)$  is continuous and contra-pre-continuous and  $g: (Y, \sigma) \rightarrow (Z, \eta)$  is contra-continuous. Then their composition  $g \circ f: (X, \tau) \rightarrow (Z, \eta)$  is  $\rho$ -continuous.

**Proof:** Let  $G$  be any closed set of  $(Z, \eta)$ . Since  $g$  is contra-continuity, then  $g^{-1}(G)$  is open in  $(Y, \sigma)$ . Since  $f$  is continuity and contra-pre-continuity,  $f^{-1}(g^{-1}(G)) = (g \circ f)^{-1}(G)$  is open and preclosed in  $(X, \tau)$ . Then by Theorem 1.5(1),  $(g \circ f)^{-1}(G)$  is  $\rho$ -closed in  $(X, \tau)$ . Then  $g \circ f$  is  $\rho$ -continuous.

**Theorem 3.9:** If  $f: (X, \tau) \rightarrow (Y, \sigma)$  is  $\rho$ -irresolute and  $g: (Y, \sigma) \rightarrow (Z, \eta)$  is  $\rho$ -continuous then  $g \circ f: (X, \tau) \rightarrow (Z, \eta)$  is  $\rho$ -continuous.

**Proof:** Let  $G$  be any closed set of  $(Z, \eta)$ . Since  $g$  is  $\rho$ -continuous,  $g^{-1}(G)$  is  $\rho$ -closed in  $(Y, \sigma)$ . Since  $f$  is irresolute,  $f^{-1}(g^{-1}(G)) = (g \circ f)^{-1}(G)$  is  $\rho$ -closed in  $(X, \tau)$ . Thus  $g \circ f$  is  $\rho$ -continuous.

**Theorem 3.10:** Let  $f: (X, \tau) \rightarrow (Y, \sigma)$  be a  $\rho_s$ -continuous function. Then  $f$  is continuous if  $(X, \tau)$  is  $\rho$ - $T_s$ .

**Proof:** Let  $G$  be any closed set of  $(Y, \sigma)$ . Since  $f$  is  $\rho_s$ -continuous and by assumption  $f^{-1}(G)$  is closed in  $(X, \tau)$ . Thus  $f$  is continuous.

### Definition 3.11:

1. Let  $x$  be a point of  $(X, \tau)$  and  $V$  be a subset of  $X$ . Then  $V$  is called a  $\rho$ -neighbourhood of  $x$  in  $(X, \tau)$  if there exists a  $\rho$ -open set  $U$  of  $(X, \tau)$  such that  $x \in U \subseteq V$ .
2. [5] The intersection of all  $\rho$ -closed sets each containing a set  $A$  in a topological space  $X$  is called the  $\rho$ -closure of  $A$  and is denoted by  $\rho\text{-cl}(A)$ .

**Theorem 3.12:** Let  $A$  be a subset of  $(X, \tau)$ . Then  $x \in \rho\text{-cl}(A)$  if and only if for any  $\rho$ -neighbourhood  $N_x$  of  $x$  in  $(X, \tau)$ ,  $A \cap N_x \neq \emptyset$ .

**Proof: Necessity-** Assume that  $x \in \rho\text{-cl}(A)$ . Suppose that there exists a  $\rho$ -neighbourhood  $N_x$  of  $x$  such that  $A \cap N_x = \emptyset$ . Since  $N_x$  is a  $\rho$ -neighbourhood of  $x$  in  $(X, \tau)$ , by Definition 3.11, there exists a  $\rho$ -open set  $V_x$  such that  $x \in V_x \subseteq N_x$ . Therefore, we have  $A \cap V_x = \emptyset$  and so  $A \subseteq (V_x)^c$ . Since  $(V_x)^c$  is a  $\rho$ -closed set containing  $A$ , we have  $\rho\text{-cl}(A) \subseteq (V_x)^c$  and therefore  $x \notin \rho\text{-cl}(A)$ , which is a contradiction.

**Sufficiency-** Assume that for each  $\rho$ -neighbourhood  $N_x$  of  $x$  in  $(X, \tau)$ ,  $A \cap N_x \neq \emptyset$ . Suppose  $x \notin \rho\text{-cl}(A)$ . Then there exists a  $\rho$ -closed set  $V$  of  $(X, \tau)$  such that  $A \subseteq V$  and  $x \notin V$ . Thus,  $x \in V^c$  and  $V^c$  is  $\rho$ -open in  $(X, \tau)$ . But  $A \cap V^c = \emptyset$  which is a contradiction.

**Theorem 3.13:** Let  $f: (X, \tau) \rightarrow (Y, \sigma)$  be a function. Then the following statements are equivalent.

1. The function  $f$  is  $\rho$ -continuous.
2. The inverse of each open set in  $(Y, \sigma)$  is  $\rho$ -open in  $(X, \tau)$ .
3. The inverse of each closed set in  $(Y, \sigma)$  is  $\rho$ -closed in  $(X, \tau)$ .
4. For each  $x$  in  $(X, \tau)$ , the inverse of every neighbourhood of  $f(x)$  is a  $\rho$ -neighbourhood of  $x$ .
5. For each  $x$  in  $(X, \tau)$  and each neighbourhood  $N$  of  $f(x)$ , there is a  $\rho$ -neighbourhood  $W$  of  $x$  such that  $f(W) \subseteq N$ .
6. For each subset  $A$  of  $(X, \tau)$ ,  $f(\rho\text{-cl}(A)) \subseteq \text{cl}(f(A))$ .
7. For each subset  $B$  of  $(Y, \sigma)$ ,  $\rho\text{-cl}(f^{-1}(B)) \subseteq f^{-1}(\text{cl}(B))$ .

### Proof:

(1)  $\leftrightarrow$  (2) This follows from Theorem 3.1.

(2)  $\leftrightarrow$  (3) The Proof is clear from the result  $f^{-1}(A^c) = (f^{-1}(A))^c$ .

(2) $\leftrightarrow$  (4) For  $x$  in  $(X, \tau)$ , Let  $N$  be a neighbourhood of  $f(x)$ . Then there exists an open set  $V$  in  $(Y, \sigma)$  such that  $f(x) \in V \subseteq N$ . Consequently,  $f^{-1}(V)$  is  $\rho$ -open set in  $(X, \tau)$  and  $x \in f^{-1}(V) \subseteq f^{-1}(N)$ . Thus,  $f^{-1}(N)$  is a  $\rho$ -neighbourhood of  $x$ .

(4) $\leftrightarrow$  (5) Let  $x \in X$  and let  $N$  be a neighbourhood of  $f(x)$ . Then by assumption,  $W = f^{-1}(N)$  is a  $\rho$ -neighbourhood of  $x$  and  $f(W) = f(f^{-1}(N)) \subseteq N$ .

(5) $\leftrightarrow$  (6) Suppose that (5) holds and let  $y \in f(\rho\text{-cl}(A))$  and let  $N$  be any neighbourhood of  $y$ . Then there exists a  $x \in X$  and a  $\rho$ -neighbourhood  $W$  of  $x$ , such that  $f(x) = y$ ,  $x \in W$ ,  $x \in \rho\text{-cl}(A)$  and  $f(W) \subseteq N$ .

By Theorem 3.12,  $fW \cap A \neq \emptyset$  and hence  $f(A) \cap N \neq \emptyset$ . Hence  $y = f(x) \in \text{cl}(f(A))$ . Therefore,  $f(\rho\text{-cl}(A)) \subseteq \text{cl}(f(A))$ . Conversely, suppose that (6) holds and let  $x \in X$  and  $N$  be any neighbourhood of  $f(x)$ . Let  $A = f^{-1}(Y \setminus N)$ , since  $f(\rho\text{-cl}(A)) \subseteq \text{cl}(f(A)) \subseteq Y \setminus N$ ,  $\rho\text{-cl}(A) \subseteq A$ . Then  $\rho\text{-cl}(A) = A$ . Since  $x \notin \rho\text{-cl}(A)$ , there exists a  $\rho$ -neighbourhood  $W$  of  $x$  such that  $W \cap A = \emptyset$  and hence  $f(W) \subseteq f(X - A) \subseteq N$ .

(6) $\leftrightarrow$  (7) Suppose that (6) holds and  $B$  be any subset of  $(Y, \sigma)$ , Then replacing  $A$  by  $f^{-1}(B)$  in (vi), We obtain  $f(\rho\text{-cl}(f^{-1}(B))) \subseteq \text{cl}(f(f^{-1}(B))) \subseteq \text{cl}(B)$ . That is  $\rho\text{-cl}(f^{-1}(B)) \subseteq f^{-1}(\text{cl}(B))$ . Conversely, suppose that (7) holds, let  $B = f(A)$ . Where  $A$  is a subset of  $(X, \tau)$ . Then we have,  $\rho\text{-cl}(A) \subseteq \rho\text{-cl}(f^{-1}(B)) \subseteq f^{-1}(\text{cl}(f(A)))$  and so  $f(\rho\text{-cl}(A)) \subseteq \text{cl}(f(A))$ . This completes the Proof of the theorem.

**Definition 3.14:[22]** A function  $f : (X, \tau) \rightarrow (Y, \sigma)$  is called  $\tilde{g}$ -irresolute if  $f^{-1}(V)$  is a  $\tilde{g}$ -closed set of  $(X, \tau)$  for every  $\tilde{g}$ -closed set  $V$  of  $(Y, \sigma)$ .

**Proposition 3.15:** If  $f : (X, \tau) \rightarrow (Y, \sigma)$  is  $\tilde{g}$ -irresolute and  $M$ -preclosed function, then  $f(A)$  is  $\rho$ -closed in  $(Y, \sigma)$  for every  $\rho$ -closed set  $A$  of  $(X, \tau)$ .

**Proof:** Let  $U$  be any  $\tilde{g}$ -open in  $(Y, \sigma)$  such that  $f(A) \subseteq U$ . Then  $A \subseteq f^{-1}(U)$ . Since  $f$  is  $\tilde{g}$ -irresolute then  $f^{-1}(U)$  is  $\tilde{g}$ -open in  $(X, \tau)$  and  $A$  is  $\rho$ -closed in  $(X, \tau)$ , we have  $\text{pcl}(A) \subseteq \text{Int}(f^{-1}(U))$ . Thus  $f(\text{pcl}(A)) \subseteq \text{Int}(U)$ . Since  $f$  is  $M$ -preclosed and  $\text{pcl}(A)$  is preclosed in  $(X, \tau)$  then  $f(\text{pcl}(A))$  is a Preclosed set in  $(Y, \sigma)$ . Now  $\text{pcl}(f(A)) \subseteq \text{pcl}(f(\text{pcl}(A))) = f(\text{pcl}(A)) \subseteq \text{Int}(U)$  and so  $f(A)$  is  $\rho$ -closed in  $(Y, \sigma)$ .

**Theorem 3.16:** If the bijective function  $f : (X, \tau) \rightarrow (Y, \sigma)$  is pre-irresolute and  $\tilde{g}$ -open mappings, then  $f$  is  $\rho$ -irresolute.

**Proof:** Let  $A$  be  $\rho$ -closed in  $(Y, \sigma)$  and let  $U$  be any  $\tilde{g}$ -open in  $(X, \tau)$  such that  $f^{-1}(A) \subseteq U$ . Then  $A \subseteq f(U)$ . Since  $f$  is  $\tilde{g}$ -open then  $f(U)$  is  $\tilde{g}$ -open in  $(Y, \sigma)$  and  $A$  is  $\rho$ -closed in  $(Y, \sigma)$ , we have  $\text{pcl}(A) \subseteq \text{Int}(f(U))$  and thus  $f^{-1}(\text{pcl}(A)) \subseteq f^{-1}(\text{Int}(f(U))) \subseteq \text{Int}(f^{-1}(f(U))) = \text{Int}(U)$ . Since  $f$  is pre-irresolute and  $\text{pcl}(A)$  is preclosed in  $(Y, \sigma)$  then  $f^{-1}(\text{pcl}(A))$  is a Preclosed set in  $(X, \tau)$ . Now  $\text{pcl}(f^{-1}(A)) \subseteq \text{pcl}(f^{-1}(\text{pcl}(A))) = f^{-1}(\text{pcl}(A)) \subseteq \text{Int}(U)$ . Hence  $f^{-1}(A)$  is  $\rho$ -closed in  $(X, \tau)$  and  $f$  is  $\rho$ -irresolute.

**Theorem 3.17:**

1. If  $f : (X, \tau) \rightarrow (Y, \sigma)$  is  $gp$ -continuous and contra-continuous then  $f$  is  $\rho$ -continuous.
2. If  $f : (X, \tau) \rightarrow (Y, \sigma)$  is  $gpr$ -continuous (resp.  $\pi gp$ -continuous) and  $RC$ -continuous then  $f$  is  $\rho$ -continuous.

**Proof:**

- (1) Let  $V$  be any closed set in  $(Y, \sigma)$ . Since  $f$  is  $gp$ -continuous and contra-continuous,  $f^{-1}(V)$  is  $gp$ -closed and open in  $(X, \tau)$ . By Proposition 2.2[20],  $f^{-1}(V)$  is Preclosed in  $(X, \tau)$  and by Theorem 1.5(2),  $f^{-1}(V)$  is  $\rho$ -closed in  $(X, \tau)$  and so  $f$  is  $\rho$ -continuous.
- (2) Let  $V$  be any closed set in  $(Y, \sigma)$ . Since  $f$  is  $gpr$ -continuous (resp.  $\pi gp$ -continuous) and  $RC$ -continuous,  $f^{-1}(V)$  is  $gpr$ -closed (resp.  $\pi gp$ -closed) and regular open (resp. regular open is  $\pi$ -open) in  $(X, \tau)$ . By Theorem 3.10[9],  $f^{-1}(V)$  is Preclosed in  $(X, \tau)$ . (resp. By Theorem 2.4[18],  $f^{-1}(V)$  is preclosed in  $(X, \tau)$ ). Since regular open is open, by Theorem 1.5(1),  $f^{-1}(V)$  is  $\rho$ -closed in  $(X, \tau)$  and so  $f$  is  $\rho$ -continuous.

**Theorem 3.18:** If  $f : (X, \tau) \rightarrow (Y, \sigma)$  is  $\rho$ -irresolute and  $g : (Y, \sigma) \rightarrow (Z, \eta)$  is  $\rho$ -irresolute then  $g \circ f : (X, \tau) \rightarrow (Z, \eta)$  is  $\rho$ -irresolute.

**Proof:** Let  $G$  be any  $\rho$ -closed in  $(Z, \eta)$ . Since  $g$  is  $\rho$ -irresolute,  $g^{-1}(G)$  is  $\rho$ -closed in  $(Y, \sigma)$ , since  $f$  is  $\rho$ -irresolute,  $f^{-1}(g^{-1}(G)) = (g \circ f)^{-1}(G)$  is  $\rho$ -closed in  $(X, \tau)$ . Thus  $g \circ f$  is  $\rho$ -irresolute.

Regarding the restriction of a  $\rho$ -continuous function, we have the following.

- Lemma 3.19[12]:**
1. Let  $A$  be a  $\tilde{g}$ -closed set of  $(X, \tau)$ . If  $A$  is regular closed, then  $\text{pcl}(A)$  is also  $\tilde{g}$ -closed.
  2. If  $A \subseteq Y \subseteq X$  where  $A$  is  $\tilde{g}$ -open in  $Y$  and  $Y$  is  $\tilde{g}$ -open in  $X$  then  $A$  is  $\tilde{g}$ -open in  $X$ .
  3. Let  $A \subseteq Y \subseteq X$  and suppose that  $A$  is  $\tilde{g}$ -closed in  $X$  then  $A$  is  $\tilde{g}$ -closed in  $Y$ .

**Theorem 3.20:** Let  $f: (X, \tau) \rightarrow (Y, \sigma)$  be a  $\rho$ -continuous function and  $H$  be an open  $\rho$ -closed subset of  $X$ . Assume that  $\rho C(X, \tau)$  (the class of all  $\rho$ -closed sets of  $(X, \tau)$ ) be closed under finite intersections. Then the restriction  $f|_H: (H, \tau|_H) \rightarrow (Y, \sigma)$  is  $\rho$ -continuous.

**Proof:** Let  $F$  be a closed subset of  $Y$ . By hypothesis and assumption,  $f^{-1}(F) \cap H = H_1$  (say) is  $\rho$ -closed in  $X$ . since  $(f|_H)^{-1}(F) = H_1$ , it is sufficient to show that  $H_1$  is  $\rho$ -closed in  $H$ . Let  $G_1$  be  $\tilde{g}$ -open set in  $H$  such that  $H_1 \subseteq G_1$ . Then by hypothesis and by Lemma 3.19(2),  $G_1$  is  $\tilde{g}$ -open in  $X$ . Since  $H_1$  is  $\rho$ -closed in  $X$ ,  $\text{pcl}_X(H_1) \subseteq \text{Int}(G_1)$ . Since  $H$  is open and By Lemma 2.10[10],  $\text{pcl}_H(H_1) = \text{pcl}_X(H_1) \cap H \subseteq \text{Int}(G_1) \cap H = \text{Int}(G_1) \cap \text{Int}(H) = \text{Int}(G_1 \cap H) \subseteq \text{Int}(G_1)$  and so  $H_1 = (f|_H)^{-1}(F)$  is  $\rho$ -closed in  $H$ . Thus  $f|_H$  is  $\rho$ -continuous.

**Theorem 3.21:** Let  $A$  and  $Y$  be subsets of  $(X, \tau)$  such that  $A \subseteq Y \subseteq X$ . Let  $A$  be  $\tilde{g}$ -closed and regular closed in  $(X, \tau)$ . If  $A$  is an  $\rho$ -closed set in  $(Y, \sigma)$  and  $Y$  is open and  $\rho$ -closed set in  $(X, \tau)$  then  $A$  is  $\rho$ -closed in  $(X, \tau)$ .

**Proof:** Let  $U$  be  $\tilde{g}$ -open set of  $(X, \tau)$  such that  $A \subseteq U$ . since  $Y$  is open in  $(X, \tau)$  and  $A$  is  $\rho$ -closed set in  $(Y, \sigma)$ , then we have  $\text{pcl}_Y(A) \subseteq \text{Int}_Y(U \cap Y)$ . Thus we have,  $\text{pcl}(A) \cap Y \subseteq \text{pcl}_Y(A) \subseteq \text{Int}_Y(U \cap Y) = \text{Int}(U \cap Y)$ . By Lemma 3.19(1),  $X\text{-pcl}(A)$  is  $\tilde{g}$ -open in  $(X, \tau)$ . Hence  $\text{Int}(U \cap Y) \cup (X\text{-pcl}(A))$  is  $\tilde{g}$ -open in  $(X, \tau)$  and it contains  $Y$ . Since  $Y$  is  $\rho$ -closed in  $(X, \tau)$ , we have,  $\text{pcl}(A) \subseteq \text{pcl}(Y) \subseteq \text{Int}[\text{Int}(U \cap Y) \cup (X\text{-pcl}(A))] \subseteq \text{Int}(U) \cup (X\text{-pcl}(A))$ . Thus  $\text{pcl}(A) \subseteq \text{Int}(U)$  and so  $A$  is  $\rho$ -closed in  $(X, \tau)$ .

Now we have the following results which concerns pasting Lemma for  $\rho$ -continuous functions.

**Theorem 3.22:** Let  $X = G \cup H$  be a topological space with topology  $\tau$  and  $Y$  be a topological space with topology  $\sigma$ . Let  $f: (G, \tau|_G) \rightarrow (Y, \sigma)$  and  $g: (H, \tau|_H) \rightarrow (Y, \sigma)$  be  $\rho$ -continuous functions such that  $f(x) = g(x)$  for every  $x \in G \cap H$ . Assume that  $D[E] \subseteq Dp[E]$ , for any  $E \subseteq X$ . Suppose that both  $G$  and  $H$  are open and  $\rho$ -closed in  $(X, \tau)$ . Then their combination  $f \Delta g: (X, \tau) \rightarrow (Y, \sigma)$ , defined by  $(f \Delta g)(x) = f(x)$  if  $x \in G$  and  $(f \Delta g)(x) = g(x)$  if  $x \in H$ , is  $\rho$ -continuous.

**Proof:** Let  $F$  be a closed subset of  $(Y, \sigma)$ . Then  $f^{-1}(F)$  is  $\rho$ -closed in  $(G, \tau|_G)$  and  $g^{-1}(F)$  is closed set in  $(H, \tau|_H)$ . Since  $G, H$  are both open and  $\rho$ -closed subsets of  $(X, \tau)$ . By Theorem 3.19,  $f^{-1}(F)$  and  $g^{-1}(F)$  are both  $\rho$ -closed sets in  $(X, \tau)$ . By Theorem 1.5(3),  $f^{-1}(F) \cup g^{-1}(F)$  is  $\rho$ -closed in  $(X, \tau)$ . By definition  $(f \Delta g)^{-1}(F) = f^{-1}(F) \cup g^{-1}(F)$ , is  $\rho$ -closed in  $(X, \tau)$ . Hence,  $f \Delta g$  is  $\rho$ -continuous.

#### 4. STRONGLY $\rho$ -CONTINUOUS AND PERFECTLY $\rho$ -CONTINUOUS FUNCTIONS

**Definition 4.1:** A function  $f: (X, \tau) \rightarrow (Y, \sigma)$  is called

1. Strongly gp-continuous [20] if  $f^{-1}(V)$  is closed (resp. open) in  $(X, \tau)$  for every gp-closed set (resp. gp-open set)  $V$  of  $(Y, \sigma)$ .
2. Strongly  $\pi$ gp-continuous [19] if  $f^{-1}(V)$  is closed (resp. open) in  $(X, \tau)$  for every  $\pi$ gp-closed set (resp.  $\pi$ gp-open set)  $V$  of  $(Y, \sigma)$ .
3. Strongly  $\rho$ -continuous if  $f^{-1}(V)$  is closed (resp. open) in  $(X, \tau)$  for every  $\rho$ -closed set (resp.  $\rho$ -open set)  $V$  of  $(Y, \sigma)$ .
4. Perfectly  $\rho$ -continuous if  $f^{-1}(V)$  is clopen in  $(X, \tau)$  for every  $\rho$ -closed set (resp.  $\rho$ -open set)  $V$  of  $(Y, \sigma)$ .
5. Pre- $\rho$ -continuous if  $f^{-1}(V)$  is  $\rho$ -closed in  $(X, \tau)$  for every preclosed set  $V$  of  $(Y, \sigma)$ .

**Remark 4.2:** From the above definition and  $\rho$ -closed  $\rightarrow$  gp-closed (resp.  $\pi$ gp-closed) we have

Strongly gp-continuous  $\searrow$   
 Perfectly  $\rho$ -continuous  $\rightarrow$  Strongly  $\rho$ -continuous  
 Strongly  $\pi$ gp-continuous  $\nearrow$

**Theorem 4.3:**

1. If  $f: (X, \tau) \rightarrow (Y, \sigma)$  is perfectly  $\rho$ -continuous then  $f$  is strongly  $\rho$ -continuous and also  $\rho$ -irresolute.
2. If  $f: (X, \tau) \rightarrow (Y, \sigma)$  is pre- $\rho$ -continuous then  $f$  is  $\rho$ -continuous.
3. If  $f: (X, \tau) \rightarrow (Y, \sigma)$  is strongly  $\rho$ -continuous and  $g: (Y, \sigma) \rightarrow (Z, \eta)$  is  $\rho$ -continuous  $g \circ f: (X, \tau) \rightarrow (Z, \eta)$  is continuous.
4. If  $f: (X, \tau) \rightarrow (Y, \sigma)$  is strongly  $\rho$ -continuous and  $g: (Y, \sigma) \rightarrow (Z, \eta)$  is perfectly  $\rho$ -continuous, then  $g \circ f: (X, \tau) \rightarrow (Z, \eta)$  is strongly  $\rho$ -continuous.
5. If  $f: (X, \tau) \rightarrow (Y, \sigma)$  is perfectly  $\rho$ -continuous and  $g: (Y, \sigma) \rightarrow (Z, \eta)$  is pre  $\rho$ -continuous, then  $g \circ f: (X, \tau) \rightarrow (Z, \eta)$  is  $\rho$ -continuous.

**Proof:**

1. Let  $V$  be  $\rho$ -closed in  $(Y, \sigma)$ . Then  $f^{-1}(V)$  is clopen in  $(X, \tau)$  and hence  $f^{-1}(V)$  is closed in  $(X, \tau)$  and so  $f$  is strongly  $\rho$ -continuous. Since closed set implies preclosed set and by Theorem 1.5(1),  $f^{-1}(V)$  is  $\rho$ -closed in  $(X, \tau)$ . Thus  $f$  is  $\rho$ -irresolute.
2. Closed set implies preclosed set and the proof is obvious.



3. Let  $V$  be closed in  $(Z, \eta)$ . Then  $g^{-1}(V)$  is  $\rho$ -closed in  $(Y, \sigma)$  and  $f^{-1}(g^{-1}(V)) = (g \circ f)^{-1}(V)$  is closed in  $(X, \tau)$ . Thus  $g \circ f$  is continuous.
4. Let  $V$  be  $\rho$ -closed in  $(Z, \eta)$ . Then  $g^{-1}(V)$  is clopen in  $(Y, \sigma)$ . since closed implies preclosed and by Theorem 1.5(1),  $g^{-1}(V)$  is  $\rho$ -closed in  $(Y, \sigma)$  and hence  $f^{-1}(g^{-1}(V)) = (g \circ f)^{-1}(V)$  is closed in  $(X, \tau)$ . Thus  $g \circ f$  is strongly  $\rho$ -continuous.
5. Let  $V$  be closed in  $(Z, \eta)$ . since closed implies preclosed. Then  $g^{-1}(V)$  is  $\rho$ -closed in  $(Y, \sigma)$ . Hence  $f^{-1}(g^{-1}(V)) = (g \circ f)^{-1}(V)$  is clopen in  $(X, \tau)$  and so  $(g \circ f)^{-1}(V)$  is  $\rho$ -closed in  $(X, \tau)$ . Therefore  $g \circ f$  is  $\rho$ -continuous.

**Theorem 4.4:** Let  $f: (X, \tau) \rightarrow (Y, \sigma)$  be a surjective,  $\rho$ -irresolute and  $M$ -preclosed. If  $(X, \tau)$  is a  $\rho$ - $T_{1/2}$  space, then  $(Y, \sigma)$  is also  $\rho$ - $T_{1/2}$  space.

**Proof:** Let  $A$  be  $\rho$ -closed in  $(Y, \sigma)$ . Since  $f$  is  $\rho$ -irresolute, then  $f^{-1}(A)$  is  $\rho$ -closed in  $(X, \tau)$ . Since  $(X, \tau)$  is a  $\rho$ - $T_{1/2}$  space and by Theorem 1.5(2),  $f^{-1}(A)$  is preclosed in  $(X, \tau)$ . Since  $f$  is  $M$ -preclosed, then  $f(f^{-1}(A)) = A$  is preclosed in  $(Y, \sigma)$ . Hence by Theorem 1.5(2),  $A$  is  $\rho_s$ -closed in  $(Y, \sigma)$  which is preclosed in  $(Y, \sigma)$ . Therefore  $(Y, \sigma)$  is  $\rho$ - $T_{1/2}$  space.

## 5 $\rho$ -Compact and $\rho$ -Connected

**Definition 5.1:** A topological space  $(X, \tau)$  is  $\rho$ -compact if every  $\rho$ -open cover of  $X$  has a finite subcover.

A subset  $A$  of  $(X, \tau)$  is regular open if  $A$  is open and  $\rho$ -closed [Theorem 1.5[4]]. This suggest that a space is  $S$ -closed if it is strongly  $S$ -closed and  $\rho$ -compact. A space  $(X, \tau)$  is  $S$ -closed[25] if every regular closed cover of  $X$  has a finite subcover. A space  $(X, \tau)$  is strongly  $S$ -closed[7] if every cover of  $(X, \tau)$  by closed sets has a finite subcover.

**Definition 5.2:** A topological space  $(X, \tau)$  is  $\rho$ -connected if  $X$  cannot be written as the disjoint union of two non-empty  $\rho$ -open sets.

**Theorem 5.3:** Let  $f: (X, \tau) \rightarrow (Y, \sigma)$  be a surjective,  $\rho$ -continuous function. If  $X$  is  $\rho$ -compact, then  $Y$  is compact.

**Proof:** Let  $\{A_i : i \in I\}$  be an open cover of  $Y$ . Then  $\{f^{-1}(A_i) : i \in I\}$  is a  $\rho$ -open cover of  $X$ . Since  $X$  is  $\rho$ -compact, it has a finite sub cover, say  $\{f^{-1}(A_1), f^{-1}(A_2), \dots, f^{-1}(A_n)\}$ . The Surjectiveness of  $f$  implies  $\{A_1, A_2, \dots, A_n\}$  is a finite sub cover of  $Y$  and hence  $Y$  is compact.

**Theorem 5.4:** Let  $f: (X, \tau) \rightarrow (Y, \sigma)$  be a surjective,  $\rho$ -continuous (resp.  $\rho$ -irresolute) function. If  $X$  is  $\rho$ -connected, then  $Y$  is connected (resp.  $\rho$ -connected).

**Proof:** Suppose  $Y$  is not connected (resp. not  $\rho$ -connected) Then  $Y = A \cup B$ . Where  $A \cap B = \emptyset$ ,  $A \neq \emptyset$ ,  $B \neq \emptyset$  and  $A, B$  are open (resp.  $\rho$ -open) sets in  $Y$ . Since  $f$  is surjective,  $f(X) = Y$  since  $f$  is  $\rho$ -continuous (resp.  $\rho$ -irresolute),  $X = f^{-1}(A) \cup f^{-1}(B)$ , is the disjoint union of two non-empty  $\rho$ -open sets. This contradicts the fact that  $X$  is  $\rho$ -connected.

**Definition 5.5:** A subset  $A$  of a space  $X$  is called  $\rho$ -compact relative to  $X$  if every collection  $\{U_i : i \in I\}$  of  $\rho$ -open subsets of  $X$  such that  $A \subseteq \bigcup \{U_i : i \in I\}$ , there exists a finite subset  $I_0$  of  $I$  such that  $A \subseteq \bigcup \{U_i : i \in I_0\}$ .

**Theorem 5.6:** Every  $\rho$ -closed subset of a  $\rho$ -compact space  $X$  is  $\rho$ -compact relative to  $X$ .

**Proof:** Let  $A$  be a  $\rho$ -closed subset of a  $\rho$ -compact space  $X$ . Let  $\{U_i : i \in I\}$  be a cover of  $A$  by  $\rho$ -open subsets of  $X$ . So  $A \subseteq \bigcup \{U_i : i \in I\}$  and then  $(X \setminus A) \cup (\bigcup \{U_i : i \in I\}) = X$ . since  $X$  is  $\rho$ -compact there exists a finite subset  $I_0$  of  $I$  such that  $(X \setminus A) \cup (\bigcup \{U_i : i \in I_0\}) = X$ . Then  $A \subseteq \bigcup \{U_i : i \in I_0\}$  and hence  $A$  is  $\rho$ -compact relative to  $X$ .

**Theorem 5.7:** If  $f: (X, \tau) \rightarrow (Y, \sigma)$  is  $\rho$ -irresolute and a subset  $A$  of  $X$  is  $\rho$ -compact relative to  $X$  then its image  $f(A)$  is  $\rho$ -compact relative to  $Y$ .

**Proof:** Let  $\{f(U_i) : i \in I\}$  be a cover of  $f(A)$  by  $\rho$ -open subset of  $(Y, \sigma)$ . Since  $f$  is  $\rho$ -irresolute, then  $\{U_i : i \in I\}$  is a cover of  $A$  by  $\rho$ -open subsets of  $(X, \tau)$ . Since  $A$  is compact relative to  $X$ , there exists a finite subcover  $I_0$  of  $I$  such that  $A \subseteq \bigcup \{U_i : i \in I_0\}$ . Hence  $f(A) \subseteq \bigcup \{f(U_i) : i \in I_0\}$  and so  $f(A)$  is compact relative to  $Y$ .

**Theorem 5.8:** If  $P: X \times Y \rightarrow X$  be a projection. Then  $p$  is irresolute.

**Proof:** Let  $A$  be a  $\rho$ -closed subset  $X$ . since  $p$  is a Projection, then  $p^{-1}(A) = A \times Y$  is subset of  $X \times Y$ .

Now to show  $p^{-1}(A) = A \times Y$  is  $\rho$ -closed in  $X \times Y$ . Let  $U$  be  $\tilde{g}$ -open subset of  $X \times Y$  such that  $A \times Y \subseteq U$ .

Then  $V \times Y = U$ , for some open subset  $V$  of  $X$  containing  $A$ . Since  $A$  is  $\rho$ -closed in  $X$ , We have,  $\text{pcl}_X(A) \subseteq \text{Int}(V)$  and  $\text{pcl}_X(A) \times Y \subseteq \text{Int}(V) \times Y$ , i.e.,  $\text{pcl}_{X \times Y}(A \times Y) \subseteq \text{Int}(V \times Y) = \text{Int}(U)$ . Hence  $p^{-1}(A) = A \times Y$  is  $\rho$ -closed in  $X \times Y$ .

□

**Theorem 5.9:** *If the Product space  $X \times Y$  is  $\rho$ -compact then each of the spaces  $X$  and  $Y$  is  $\rho$ -compact.*

**Proof:** Let  $X \times Y$  be  $\rho$ -compact. By Theorem 5.8, the projection  $p : X \times Y \rightarrow X$  is  $\rho$ -irresolute and then by Theorem 5.7,  $p(X \times Y) = X$  is  $\rho$ -compact. The proof for the space  $Y$  is similar to the case of  $X$ .  $\square$

**Lemma 5.10:** (The tube lemma) consider the product space  $X \times Y$ , where  $Y$  is compact. If  $N$  is an open set of  $X \times Y$  containing the slice  $x_0 \times Y$  of  $X \times Y$ , then  $N$  contains some tube  $W \times Y$  about  $x_0 \times Y$ , where  $W$  is a neighbourhood of  $x_0$  in  $X$ .

**Theorem 5.11:** *Let  $A$  be any subset of  $Y$ .*

1. *If  $X \times A$  is  $\rho$ -closed in the Product space  $X \times Y$  and  $Y$  is  $T_g$  space then  $A$  is  $\rho$ -closed in  $Y$ .*

2. *If  $X$  is compact and  $A$  is  $\rho$ -closed in  $Y$  and  $X \times Y$  is  $T_g$  space then  $X \times A$  is  $\rho$ -closed in  $X \times Y$ .*

**Proof:**

- Let  $U$  be  $\tilde{g}$ -open set of  $Y$  such that  $A \subseteq U$ . Then  $X \times A \subseteq X \times U$ . Since  $Y$  is  $T_g$ , therefore  $U$  is open in  $Y$  and  $X \times U$  is open in  $X \times Y$ , hence  $X \times U$  is  $\tilde{g}$ -open in  $X \times Y$ . Since  $X \times A$  is  $\rho$ -closed in  $X \times Y$ , Therefore  $\text{pcl}(X \times A) \subseteq \text{Int}(X \times U) = X \times U$ . By proposition 2.8[20],  $X \times \text{pcl}(A) \subseteq X \times \text{Int}(U)$ . Thus  $\text{pcl}(A) \subseteq \text{Int}(U)$  and so  $A$  is  $\rho$ -closed in  $Y$ .
- Let  $U$  be  $\tilde{g}$ -open set of  $X \times Y$  such that  $X \times A \subseteq U$ . since  $X$  is compact and  $X \times Y$  is  $T_g$  and by the generalization of lemma 5.10, there exists an open set  $V$  in  $Y$  containing  $A$  such that  $X \times V \subseteq U$ . Since  $A$  is  $\rho$ -closed in  $Y$ ,  $\text{pcl}(A) \subseteq \text{Int}(V)$ ,  $X \times \text{pcl}(A) \subseteq X \times \text{Int}(V) = \text{Int}(X) \times \text{Int}(V) \subseteq \text{Int}(X \times V)$ , By proposition 2.8[20],  $\text{pcl}(X \times A) \subseteq \text{Int}(X \times V) \subseteq \text{Int}(U)$ . Therefore  $X \times A$  is  $\rho$ -closed in  $X \times Y$ .

**Theorem 5.12:** *If the Product space  $X \times Y$  is  $\rho$ -connected then each of the spaces  $X$  and  $Y$  is  $\rho$ -connected.*

**Proof:** Let  $X \times Y$  be  $\rho$ -connected. By Theorem 5.8, the projection  $p : X \times Y \rightarrow X$  is  $\rho$ -irresolute and then by Theorem 5.4,  $p(X \times Y) = X$  is  $\rho$ -connected. The proof for the space  $Y$  is similar to the case of  $X$ .

## REFERENCE

- Andrijevic.D, Semi-preopen sets, Mat. Vesnik, 38 (1) (1986), 24-32.
- Arokianani.L, Balachandran.K and Dontchev.J, Some characterization of gp-irresolute and gp-continuous maps between topological spaces, Mem. Fac. Sci., Kochi. univ. (math), 20(1999), 93-104.
- Arya.S.P and Gupta.R, On strongly continuous mappings, Kyungpook Math. J., (1974), 131-143.
- Balachandran.K, Sundaram.P and Maki.H, On generalized continuous maps in topological spaces, Mem Fac. Sci. Kochi Univ.ser. A. Math 12(1991) 5-13.
- Devamanoharan.C, Pious Missier.S and Jafari.S,  $\rho$ -closed sets in topological spaces (Submitted).
- Dontchev.J, On generalizing semi-Preopen sets, Mem. Fac.sci. Kochi Univ. Ser. A. Maths 16 (1995), 35-48.
- Dontchev.J, Contra-continuous functions and strongly S-closed spaces, Internat. J. Math. Math. Sci., 19(1996)303-310.
- Dontchev. J and Noiri.T, Contra-Semicontinuous functions, Math, Pannonica 10(1999), 159-168.
- Gnanambal.Y, Generalized Pre-regular closed sets in topological spaces, Indian J. Pure Appl. Maths., 28 (3) (1997), 351-360.
- Gnanambal.Y, Balachandran.K, On gpr-continuous functions in topological spaces, Indian J Pure Appl Math 1999,30(6):581-93.
- Jafari.S and Noiri.T, On Contra-Pre-continuous functions, Bulletin of the Malaysian Mathematical Society 25(1)(2002).
- Jafari.S, Noiri.T, Rajesh.N and Thivagar.M.L, Another generalization of closed sets, Kochi J. Math, 3(2008), 25-38.
- Levine.N, Semi-open sets, semi-continuity in topological spaces, Amer Math, Monthly, 70 (1963), 36-41.
- Levine.N, Generalized Closed sets in topology, Rend circ. Math Palermo, 19 (2) (1970) 89-96.

15. Mashour.A.S, Abd El-Monsef.M.E and El-Deep.S.N, On Precontinuous and weak precontinuous mappings, Proc. Math, Phys. Soc. Egypt., 53(1982), 47-53.
16. Mashour.A.S, Abd El-Monsef.M.E, Hasanein.I.A and Noiri.T, Strongly compact spaces, Delta J. Sci., 8 (1984), 30-46.
17. Noiri.T, Maki.H and Umehara.J, Generalised Preclosed functions, Mem. Fac. Sci. Kochi. Univ. Ser. A. Maths., 19 (1998), 13-20.
18. Park.J.H, On gp-closed sets in topological spaces, Indian J. Pure Appl. Math (to appear).
19. Park.J.H and Park.J.K, On  $\pi$ gp-continuous functions in topological spaces, chaos, solutions and Fractals, 20(2004), 467-477.
20. Park.J.H, Park.Y.B and Bu Young Lee, "On gp-closed sets and Pre-gp-continuous functions", Indian J. Pure appl.Math. 33(1):3-12, January 2002.
21. Rajesh.N and Ekici.E, On  $\tilde{g}$ -continuous function, Proc.Inst.Math.(Good.zb.Inst.Mat.), Skopje(to appear).
22. Rajesh.N and Ekici.E, On a new form of irresoluteness and weak forms of strong continuity (submitted).
23. Sundaram.P and Sheik John.M, Weakly closed sets and weak continuous functions in topological spaces, Proc. 82nd Indian sci.cong.calcutta, (1995), 49.
24. Sundaram.P and Sheik John.M, On  $\omega$ -closed sets in topology, Acta Ciencia Indica, Vol. XXVI M, No. 4, 389 (2000).
25. Thompson, T., S-closed spaces, Proc. Amer. Math. Soc., 60(1976), 335-338.
26. Veerakumar.M.K.R.S,  $\hat{g}$ -closed sets in topological spaces Bull Allahabad. Soc.18 (2003), 99-112.
27. Veerakumar.M.K.R.S,  $\#g$ -closed sets in topological spaces, reprint.
28. Veerakumar.M.K.R.S,  $\#g$ -semi-closed sets in topological spaces, Antarctica J. Maths 2 (2) (2005) 201-202.
29. Veerakumar.M.K.R.S, Between  $g^*$ -closed and  $g$ -closed sets Antarctica J. Maths (to appear).
30. Veerakumar.M.K.R.S,  $g^*$ -preclosed sets, Acta Ciencia Indica (mathematics) Meerut, XXVIII (M) (1) (2002), 51-60.
31. Veerakumar.M.K.R.S, Pre-semi-closed, Indian J. Math, 44(2) (2002), 165-181.
32. Zaitsev V., On certain classes of topological spaces and their bicompatifications, Dokl Akad Nauk SSSR 1968; 778-9.

\*\*\*\*\*