

A GENERALIZED COMMON FIXED POINT THEOREM FOR SET VALUED MAPPINGS

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ABSTRACT

In this paper we generalize a common fixed point theorem which properly generalized the theorem of Ahmed [1], and theorem of Itoh and Takahashi [3], and extend the theorems of Kasahara and Rhoades [7], Tas, Telei and Fisher [9] and Telei, Tas and Fisher [10] of the set valued mapping.

KEY WORDS: Common Fixed Point, Compact Metric Space, Weakly Compatible Mappings, Set Valued Mapping.

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1. INTRODUCTION

Let (X, d) be a metric space and B(X) the set of all non empty bounded subsets of X. Let for all A, $B \in B(X)$, $\delta(A, B)$ and D (A, B) be the functions defined by

 $\delta(A, B) = \sup \{ d(a, b) : a \in A, b \in B \}$ D(A, B) = inf {d(a, b) : a \in A, b \in B}

If $A = \{a\}, \quad \delta(A, B) = \delta(a, B).$

If $B = \{b\}$ also, $\delta(A, B) = d(A, b)$.

For all A, B, C \in B(X), it follows immediately from the definition that

$$\begin{split} \delta(A, B) &= \delta(B, A) \geq 0\\ \delta(A, B) &\leq \delta(A, C) + \delta(C, B)\\ \delta(A, B) &= 0 \text{ iff } A = B = \{a\},\\ \delta(A, A) &= \text{diam } A, \end{split}$$

Definition 1.1 [2]: A sequence $\{A_n\}$ of subsets of X is said to be convergent to a subset A of X if

- (i) given $a \in A$, there is a sequence $\{a_n\}$ in X such that $a_n \in A_n$ for $n = 1, 2, \dots$, and $\{a_n\}$ converges to a
- (ii) given $\varepsilon > 0$, there exists a positive integer N such that $A_n \subseteq A_{\varepsilon}$ for n > N where A_{ε} is the union of all open spheres with centers in A and radius ε .

Definition 1.2 [2] : A set valued mapping F of X into B(X) is said to be continuous at $x \in X$ if the sequence $\{Fx_n\}$ in B(X) converges to Fx whenever $\{x_n\}$ is a sequence in X converging to x in X, F is said to be continuous on X if it is continuous at every point X.

Let I: $X \to X$ be self mapping and $f : X \to B(X)$ a set valued mapping. Sessa et al. [7] defines I and f to be weakly commuting if If $x \in B(X)$ and

 $\delta(Ifx, fIx) \leq Max \{ d(Ix, fx), diam Ifx \}$

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Jungck and Rhoades [3] defines I and f to be δ – compatible if

$$\lim_{n\to\infty} \delta(fIx_n, Ifx_n) = 0$$

whenever $\{x_n\}$ is a sequence in X such that

 $\lim_{n\to\infty} fx_n = \{t\}$ and $\lim_{n\to\infty} Ix_n = t$

for some $t \in X$. Clearly, commuting mappings are weakly commuting and weakly commuting are δ compatible but neither implication is reversible as shown by example in [7] and [3] respectively.

Recently Jungck and Rhoades [3] defines I and f to be weakly compatible if for each point u in X such that fu = {Iu}, we have flu = Ifu. In [3], it is shown that δ – compatible mappings are weakly compatible but the converse need not to be true.

IMPLICIT RELATIONS: Let F^* be the collection of real functions $F(t_1,...,t_6): (R_+)^6 \to R$ satisfying the following conditions:

 $\begin{array}{l} (F_1): \ f \ is \ non \ increasing \ in \ each \ co- \ ordinate \ variable \ except \ t_1, \\ (F_2): \ F \ (u, \ v, \ v, \ u, \ u+v, \ 0) < 0 \ or \ F(u, \ v, \ u, \ v, \ 0, \ u+v) < 0 \ implies \ u < v. \\ (F_3): \ F \ (u, \ u, \ 0, \ 0, \ u, \ u) \geq 0 \ \ for \ \ all \ \ u > 0. \end{array}$

Example 1.1: F $(t_1, \ldots, t_6) = t_1 - \max\{t_2, t_3, t_4\}.$

 $(F_1): obviously \\ (F_2): Let F(u, v, v, u, u + v, 0) = u - max\{v, v, u\} < 0, \ \ if \ u \geq v \ then \ u < u \ a \ contradiction.$

Thus u < v. Similarly if F(u, v, u, v, 0, u + v) < 0 then u < v.

(F₃): F (u, u, 0, 0, u, u) = 0 for all u > 0.

Example 1.2: F (t₁,, t₆) = t₁ - max{t₂, t₃, t₄, $\frac{t_5 + t_6}{2}$, }.

 F_1 , F_2 and F_3 can be shown as in example 1.1.

Example 1.3: $F(t_1, ..., t_6) = t_1 - \max\{t_2, \frac{t_3 + t_4}{2}, \frac{t_5 + t_6}{2}\}.$ F₁, F₂ and F₃ can be shown as in example 1.1.

Example 1.4: $F(t_1, ..., t_6) = t_1^2 - c_1 \max\{t_2^2, t_3^2, t_4^2\} - c_2\{t_3t_4, t_4t_6\} - c_3\{t_5t_6\}, \text{ where } c_1 + 2c_2 \le 1,$

$$c_1 + c_3 \le 1$$
 and $c_1, c_2, c_3 \ge 0$.

(F₁): obviously

(F₂): Let F (u, v, v, u, u + v, 0) = $u^2 - max \{u^2, v^2\} < 0$, if $u \ge v$ then u < u, a contradiction.

Thus u < v. Similarly if F (u, v, u, v, 0, u + v) < 0 then u < v.

(F₃): F (u, u, 0, 0, u, u) = u^{2} {1- (c₁ + c₃)} \geq 0, for all u > 0.

Example 1.5: F (t₁, ..., t₆) = t₁- max {t₂, t₃, t₄, $\frac{t_5 + t_6}{2}$, b $\sqrt{(t_5 t_6)}$ }, where 0 < b < 1F₁ and F₂ can be shown as in example 1.1.

 $(F_3) {:} \ F \ (u, \, u, \, 0, \, 0, \, u, \, u) = u - Max \ \{u, \, bu \} \ \geq 0 \ for \ all \ \ u > 0.$

Example 1.6: F $(t_1, ..., t_6) = t_1 - \alpha .max \{t_2, t_3, t_4\} - (1 - \alpha) (at_5 + bt_6),$

where $0 \le \alpha < 1$,

$$\leq a \leq \frac{1}{2}$$
 and $0 \leq b \leq \frac{1}{2}$

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(F₁): obviously

 $(F_2): Let \ u > 0, \ v > 0 \ and \ F(u, \ v, \ u, \ u + v, \ 0) = u - \alpha.max\{v, \ v, \ u\} - (1 - \alpha)a(u + v) < 0.$

If $u \ge v$, then $(1 - \alpha) (1 - 2a)u < 0$ a contradiction. Thus u < v.

Similarly F(u, v, u, v, 0, u + v) < 0 implies u < v. If u = 0, v > 0 then u < v.

 (F_3) : F (u, u, 0, 0, u, u) = u(1 - α) (1 - (a + b)) ≥ 0 , for all u > 0.

Example 1.7: F $(t_1, \ldots, t_6) = t_1^3 - a t_1^2 t_2 - bt_1 t_3 t_4 - c t_5^2 t_6 - dt_5 t_6^2$ where a, b, c, $d \ge 0$ and a + b + c + d < 1.

(F₁): Obviously

(F₂): Let u > 0, v > 0 and F(u, v, v, u, u+v, 0) = $u^2 \{u - (a + b)v\} < 0$, which implies

u < (a + b) v < v. If u = 0, v > 0, then u < v.

Similarly F(u, v, u, v, 0, u + v) < 0 implies u < v.

(F₃): F (u, u, 0, 0, u, u) = $u^3 (1 - (a + b + c + d) \ge 0$ for all u > 0.

2. PRELIMINARIES

The following theorems are proved in [1], [2], [5], [7], [9] and [10]:

Theorem 2.1 [2]: Let F, G be continuous mappings of a compact metric space (X, d) into B(X) and I, J continuous mappings of X into itself satisfying the inequality

$$d(Fx, Gy) < \max \{ d(Ix, Jy), \delta(Ix, Fx), \delta(Jy, Gy) \},$$

$$(2.1)$$

for all x, $y \in X$ for which the righthand side of the inequality (2.1) is positive. If the mapping F and I commute and G and J commute and $G(X) \subset J(X)$, $F(X) \subset J(X)$, then there is a unique point u in X such that

$$Fu = Gu = \{u\} = \{Iu\} = \{Ju\}.$$

Theorem 2.2 [1]: Let I, J be functions of a compact metric space (X, d) into itself and F, G: $X \rightarrow B(X)$ two set-valued functions with $\cup F(X) \subseteq J(X)$ and $\cup G(X) \subseteq I(X)$. Suppose that the inequality

$$\delta(Fx, Gy) < \alpha.max\{d(Ix, Jy), \delta(Ix, Fx), \delta(Jy, Gy)\} + (1 - \alpha) [aD(Ix, Gy) + bD(Jy, Fx)],$$

$$(2.2)$$

for all x, $y \in X$, where $0 \le \alpha < 1$, $a \ge 0$, $b \ge 0$, $a \le \frac{1}{2}$, $b < \frac{1}{2}$, $\alpha | a - b | < 1 - (a + b)$, holds whenever the

righthand side of (2.2) is positive. If the pairs $\{F, I\}$ and $\{G, J\}$ are weakly compatible, and if the functions F and I are continuous, then there is a unique point u in X such that

$$Fu = Gu = \{u\} = \{Iu\} = \{Ju\}.$$

Theorem 2.3 [4] : Let A, B, S, T be continuous self mappings of a compact metric space with $A(X) \subset T(X)$ and $B(X) \subset S(X)$. If {A, S} and {B, T} are compatible pairs and

$$d(Ax, By) < \max\{d(Sx, Ty), d(Ax, Sx), d(By, Ty), \frac{1}{2}(d(Ax, Ty) + d(By, Sx))\}$$
(2.3)

for all x, y in X for which the right hand side of (7.4.4) is positive. Than A, B, S, T have a unique common fixed point.

Theorem 2.4 [7]: Let S and I be self mappings of a non empty compact metric space (X, d) satisfying

$$d(Sx, Ty) < \max\{d(x, y), \frac{1}{2}(d(x, Sx) + d(y, Ty)), \frac{1}{2}(d(x, Ty) + d(y, Tx))\}$$
(2.4)

If S or T is continuous then S and T has a unique common fixed point.

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Theorem 2.5 [9] : Let A, B, S and T be continuous self maps of a compact metric space (X, d) with $A(X) \subset T(X)$ and $B(X) \subset S(X)$. If {A, S} and {B, T} are compatible pairs and

$$d^{2}(Ax, By) < c.max \{ d^{2}(Sx, Ax), d^{2}(Ty, By), d^{2}(Sx, Ty) \} + \frac{1}{2} (1-c).max \{ d(Sx, Ax) d(Sx, By), d(Ax, Ty), d(By, Ty) \} + (1-c) d(Sx, By).d(Ty, Ax)$$
(2.5)

for all x, y in X for which the right hand side of (2.5) is positive, where $c \in (0, 1)$. Then A, B, S and T have a common fixed point z. Further, z is the unique common fixed point of A and S and of B and T.

Theorem 2.6 [10]: Let S and T be continuous self mappings of a compact metric space (X, d) satisfying inequality

$$d(Sx, Ty) < \max\{d(x, y), d(x, Sx), d(y, Ty), \frac{1}{2}\{d(x, Ty) + d(y, Sx)\}, b\sqrt{d(x, Ty)}.d(y, Sx)\}$$
(2.6)

for all x, y in X for which the right hand side of (2.6) is positive, where b > 0. Then S and T have a common fixed point. Further, if b < 1, then the common fixed point is unique.

3. MAIN RESULT

We prove the following theorem

Theorem 3.1: Let I, J be self mappings of a compact metric space (X, d) and f, g: $X \rightarrow B(X)$ two set valued mappings satisfying

- (i) \cup f (X) \subset J(X) and \cup g(X) \subset I(X),
- (ii) $F{\delta(fx, gy), d(Ix, Jy), \delta(Ix, fx), \delta(Jy, gy), D(Ix, gy), D(Jy, fx)} < 0$ for all x, y in X for which at least one of d(Ix, Jy), $\delta(Ix, fx), \delta(Jy, gy)$ is positive, where $F \in F^*$.
- (iii) The pair $\{f, I\}$ and $\{g, J\}$ are weakly compatible,
- (iv) The mapping f and I are continuous.

Then there exists a unique point $u \in X$ such that $fu = gu = \{u\} = \{Iu\} = \{Ju\}$.

Proof: Let $\varepsilon = Inf \{\delta(Ix, fx): x \in X\}$. Since X is compact space, there is a convergent sequence $\{x_n\}$ with limit x_0 in X such that

$$\lim_{n\to\infty} \delta(Ix_n, fx_n) = \varepsilon.$$

Since $\delta(Ix_0, fx_0) \le d(Ix_0, Ix_n) + \delta(Ix_n, fx_n) + \delta(fx_n, fx_0)$,

therefore by the continuity of f and I and $\lim_{n\to\infty} x_n = x_0$, we get $\delta(Ix_0, fx_0) \le \varepsilon$ and that $\delta(Ix_0, fx_0) = \varepsilon$.

Since $\cup f(X) \subseteq J(X)$, there exists a point $y_0 \in X$ such that $Jy_0 \in fx_0$ and $d(Ix_0, Jy_0) \le \epsilon$.

If $\varepsilon > 0$, then, by (ii) we have

 $F \{\delta(fx_0, gy_0), \delta(Ix_0, Jy_0), \delta(Ix_0, fx_0), \delta(Jy_0, gy_0), D(Ix_0, gy_0), D(Jy_0, fx_0)\} < 0$

 $\Rightarrow F \{\delta(fx_0, gy_0), \varepsilon, \varepsilon, \delta(fx_0, gy_0), \delta(fx_0, gy_0) + \varepsilon, 0\} < 0.$

By (F₂) it implies

$$\delta(fx_0, gy_0) < \varepsilon$$
 and hence $\delta(Jy_0, gy_0) \le \delta(fx_0, gy_0) < \varepsilon$.

Since $\cup g(X) \subset I(X)$, then there exists a point z_0 in X such that $Iz_0 \in gy_0$ and $d(Iz_0, Jy_0) < \epsilon$.

Now, since $\delta(Iz_0, Jy_0) \ge \varepsilon > 0$. Then, we have,

 $F \{\delta(fz_0, gy_0), \delta(Iz_0, Jy_0), \delta(Iz_0, fz_0), \delta(Jy_0, gy_0), D(Iz_0, gy_0), D(Jy_0, fz_0)\} < 0$

F { $\delta(fz_0, gy_0), \delta(Jy_0, gy_0), \delta(fz_0, gy_0), \delta(Jy_0, gy_0), 0, \delta(fz_0, gy_0) + \delta(Jy_0, gy_0)$ } < 0

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which by (F_2) yields $\delta(fz_0, gy_0) < \delta(Jy_0, gy_0)$, but then,

$$\epsilon \leq \delta(Iz_0, fz_0) \leq \delta(fz_0, gy_0) < \delta(Jy_0, gy_0) < \epsilon.$$

a contradiction. Thus $\epsilon=0.$ Then we get $\{Ix_0\}=\{Jy_0\}=fx_0.$

If $\delta(Jy_0, gy_0) > 0$ then by (ii), we have

 $F \{\delta(fx_0, gy_0), d(Ix_0, Jy_0), \delta(Ix_0, fx_0), \delta(Jy_0, gy_0), D(Ix_0, gy_0), D(Jy_0, fx_0)\} < 0$

 $F \{ \delta(Jy_0, \, gy_0), \, 0, \, 0, \, \delta(Jy_0, \, gy_0), \, \delta(Jy_0, \, gy_0), \, 0 \} < 0$

which, by (F₂), implies that $\delta(Jy_0, gy_0) < 0$, a contradiction. Thus $\delta(Jy_0, gy_0) = 0$ and so $gy_0 = \{Jy_0\}$.

Therefore
$$\{Ix_0\} = fx_0 = \{Jy_0\} = gy_0 = \{p\},$$
 (say) (3.1)

Then, by weak compatibility of the pair {f, I} we have

$$fp = f(Ix_0) = \{Ifx_0\} = \{Ip\}$$
(3.2)

If $Ip \neq p = Jy_0$, then by an application of (ii), we have,

$$F \{\delta(fp, gy_0), d(Ip, Jy_0), \delta(Ip, fp), \delta(Jy_0, gy_0), D(Ip, gy_0), D(Jy_0, fp)\} < 0,$$
(3.3)

Now using, (3.1), (3.2) and (3.3), we get

which, by (F_3) , is a contradiction. Therefore d(fp, p) = 0 and hence $fp = \{p\}$ and so

$$fp = {Ip} = {p}.$$
 (3.4)

Now, since J and g are weakly compatible $\{Jp\} = \{Jgy_0\} = gJy_0 = gp$. Suppose $Ip \neq Jp$, then d(Ip, Jp) > 0 and so

F { $\delta(fp, gp), d(Ip, Jp), \delta(Ip, fp), \delta(Jp, gp), D(Ip, gp), D(Jp, fp)$ } < 0

F {d(Ip, Jp), d(Ip, Jp), 0, 0, d(Ip, Jp), d(Ip, Jp)} < 0

which by $\{F_3\}$, is a contradiction. Thus Ip = Jp and hence

 $fp = gp = \{Ip\} = \{Jp\} = \{p\}.$

Again suppose, q be a point such that, i.e. $fq = gq = {Iq} = {Jq} = {Jq}$. Then, by (ii) we have,

 $F \left\{ \delta(fp, gq), d(Ip, Jq), \delta(Ip, fp), \delta(Jq, gq), D(Ip, gq), D(Jq, fp) \right\} < 0$

F {d(p, q), d(p, q), 0, 0, d(p, q), d(p, q)} < 0

which by (F_3) , yields d (p, q) = 0 and so p = q.

Corollary 3.1: Let

(i), J: $X \rightarrow X$ be self mapping of compact metric spaces (X, d) and f, g set valued mappings satisfying (i), (iii), (iv) and (ii) $\delta(fx, gy) < \max\{d(Ix, Jy), \delta(Ix, fx), \delta(Jy, gy)\}$

for all x, $y \in X$ for which the right hand side of the inequality (ii)* is positive. Then f, g, I and J have a unique common fixed point.

Proof: Follows from theorem 3.1 and example 1.2.

Remark 3.1: The corollary 3.1 generalizes theorem 2.1.

Corollary 3.2: Theorem 2.2.

Proof: Follows from theorem 3.1 and example 1.6.

Remark 3.2: Theorem 2.2 holds, only for $0 \le a \le \frac{1}{2}$ and $0 \le b < \frac{1}{2}$ while the result obtained by theorem 3.1 and example 1.6. [Corollary 3.2] holds for $0 \le a \le \frac{1}{2}$ and $0 \le b \le \frac{1}{2}$. Thus theorem 3.1 is a proper generalization of theorem 2.2.

Remark 3.3: Theorem 3.1 and example 1.2 yields the extension of theorem 2.3 for self mappings, to set valued mappings with more weakened condition of weak compatibility.

- (B). Theorem 3.1 with I = J = identity mapping and example 1.3 provide the extension of theorem 2.4 for set valued mappings.
- (C) Theorem 3.1 and example 1.4 with $c_1 = c$, $c_2 = \frac{1}{2}(1-c)$ and $c_3 = (1-c)$ gives the extension of theorem 2.5.
- (D). Theorem 3.1 and example 1.5 with I = J identity mapping gives the extension of theorem 2.6.

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