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On b*g - continuous functions and b*g - open maps in Topological Spaces

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ABSTRACT

In this paper, we define new class of functions namely $b*\hat{g}$ -continuous functions and $b*\hat{g}$ -open maps and we prove some of their basic properties. Also, we introduce a new class of $b*\hat{g}$ -homeomorphisms and we prove some of their relationship among other homeomorphisms. Throughout this paper $f:(X,\tau)\to (Y,\sigma)$ is a function from a topological space (X,τ) to a topological space (Y,σ) .

Keywords: $b*\hat{g}$ -continuous functions, $b*\hat{g}$ -irresolute functions, $b*\hat{g}$ -open maps, $b*\hat{g}$ -closed maps.

AMS Mathematics Subject Classification (2010): 54A05.

1. INTRODUCTION

In 1996, D. Andrijevic[2] introduced b-open sets in topology and studied its properties. In 1970, N.Levine[9] introduced generalized closed sets and studied their basic properties. In 2003, M.K.R.S.Veerakumar[16] defined \hat{g} -closed sets in topological spaces and studied their properties. b*-closed sets have been introduced and investigated by Muthuvel[11] in 2012. In 2016, K.Bala Deepa Arasi and G.Subasini[4] introduced b* \hat{g} -closed sets and studied its properties. K.Balachandran et al introduced the concept of generalized continuous maps in Topological spaces.

These concepts motivate us to define a new version of maps $b*\hat{g}$ -continuous, $b*\hat{g}$ -irresolute and $b*\hat{g}$ -open maps. Also, we prove some properties of these functions and establish the relationships between $b*\hat{g}$ -continuous and other continuous functions.

2. PRELIMINARIES

Throughout this paper (X, τ) (or simply X) represents topological spaces on which no separation axioms are assumed unless otherwise mentioned. For a subset A of (X, τ) , Cl(A), Int(A) and A^c denote the closure of A, interior of A and the complement of A respectively. We are giving some basic definitions.

Definition: 2.1 A subset A of a topological space (X, τ) is called

- 1. a semi-open set[10] if $A\subseteq Cl(Int(A))$.
- 2. an α -open set[5] if $A\subseteq Int(Cl(Int(A)))$.
- 3. a b-open set [2] if $A \subseteq Cl(Int(A)) \cup Int(Cl(A))$.
- 4. a regular open set[14] if A=Int(Cl(A)).

The complement of semi-open (resp. α -open, regular open) set is called semi-closed (resp. α -closed, regular closed) set. The intersection of all semi-closed (resp. α -closed, regular closed) sets of X containing A is called the semi-closure (resp. α -closure, regular closure) of A and is denoted by sCl(A) (resp. α Cl(A), rCl(A)). The family of all b* \hat{g} -open (resp. α -open, semi-open, b-open, regular open) subsets of a space X is denoted by b* \hat{g} O(X) (resp. α O(X), sO(X), bO(X), rO(X)).

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Definition 2.2: A subset A of a topological space (X, τ) is called

- 1. a generalized closed set (briefly g-closed) [11] if $Cl(A) \subseteq U$ whenever $A \subseteq U$ and U is open in X.
- 2. a gs-closed set[3] if $sCl(A) \subseteq U$ whenever $A \subseteq U$ and U is open in X.
- 3. a gb-closed set[1] if $bCl(A) \subseteq U$ whenever $A \subseteq U$ and U is open in X.
- 4. a \hat{g} -closed set[17] if Cl(A) \subseteq U whenever A \subseteq U and U is semi-open in X.
- 5. a bĝ-closed set[16] if $bCl(A) \subseteq U$ whenever $A \subseteq U$ and U is \hat{g} -open in X.
- 6. a gr*-closed set[9] if $rCl(A) \subseteq U$ whenever $A \subseteq U$ and U is g-open in X.
- 7. a g*s-closed set[15] if $sCl(A) \subseteq U$ whenever $A \subseteq U$ and U is gs-open in X.
- 8. $a \text{ (gs)}^*$ -closed set[7] if $Cl(A) \subseteq U$ whenever $A \subseteq U$ and U is gs-open in X.
- 9. a b* \hat{g} -closed set[4] if b*Cl(A) \subseteq U whenever A \subseteq U and U is \hat{g} -open in X.

Definition 2.3: A function $f:(X,\tau) \to (Y,\sigma)$ is called a

- 1. continuous [18] if $f^{-1}(V)$ is closed in X for every closed set V in Y.
- 2. semi-continuous [8] if $f^{-1}(V)$ is semi-closed in X for every closed set V in Y.
- 3. α -continuous [5] if $f^{-1}(V)$ is α -closed in X for every closed set V in Y.
- 4. regular continuous [13] if $f^{-1}(V)$ is regular closed in X for every closed set V in Y.
- gs-continuous [6] if $f^{-1}(V)$ is gs-closed in X for every closed set V in Y.
- gb-continuous [19] if $f^{-1}(V)$ is gb-closed in X for every closed set V in Y.
- b\hat{g}-continuous [17] if $f^{-1}(V)$ is b\hat{g}-closed in X for every closed set V in Y. g*s-continuous[15] if $f^{-1}(V)$ is g*s-closed in X for every closed set V in Y. gr*-continuous [9] if $f^{-1}(V)$ is gr*-closed in X for every closed set V in Y. 7.

- 10. (gs)*-continuous [7] if $f^{-1}(V)$ (gs)*-closed in X for every closed set V in Y.

Definition 2.4: A function $f:(X,\tau) \to (Y,\sigma)$ is called a

- 1. open map[18] if f(V) is open in Y for every open set V in X.
- 2. semi-open map[8] if f(V) is semi-open in Y for every open set V in X.
- 3. α -open map[5] if f(V) is α -open in Y for every open set V in X.
- 4. regular open map[13] if f(V) is regular open in Y for every open set V in X.
- 5. gs-open map [6] if f(V) is gs-open in Y for every open set V in X.
- gb-open map[19] if f(V) is gb-open in Y for every open set V in X.
- bĝ-open map[17] if f(V) is bĝ-open in Y for every open set V in X.
- g*s-open map[15] if f(V) is g*s-open in Y for every open set V in X.
- gr*-open map[9] if f(V) is gr*-open in Y for every open set V in X. 10. (gs)*-open map[7] if f(V) is (gs)*-open in Y for every open set V in X.

Definition 2.5: A space (X, τ) is called a

- 1. T_b-space [3], if every gs-closed set in it is closed.
- 2. T_{gs} -space [1], if every gb-closed set in it is b-closed.
- 3. $T_{b\hat{g}}$ -space [16], if every b \hat{g} -closed set in it is b-closed.
- 4. $T^*_{b\hat{g}}$ -space [16], if every b \hat{g} -closed set in it is closed.
- 5. $T_{b*\hat{a}}$ -space [4], if every $b*\hat{g}$ -closed set in it is closed.

Remark 2.6: The family of all b* \hat{g} -closed (resp. α -closed, semi-closed, b-closed, regular closed) subsets of a space X is denoted by $b*\hat{g}C(X)$ (resp. $\alpha C(X)$, sC(X), bC(X), rC(X)).

3. b*ĝ-CONTINUOUS AND b*ĝ-IRRESOLUTE FUNCTIONS

We introduce the following definitions.

Definition 3.1: A map $f:(X,\tau)\to (Y,\sigma)$ is said to be b* \hat{g} -continuous map if the inverse image of every closed set in (Y, σ) is b* \hat{g} -closed in (X, τ) .

That is, $f^{-1}(V)$ is b* \hat{g} -closed of (X, τ) for every closed set V of (Y, σ) .

Example 3.2: Let $X = Y = \{a,b,c\}$ with topologies $\tau = \{X,\phi,\{a\},\{b\},\{a,b\}\}$ and $\sigma = \{Y,\phi,\{a\},\{b,c\}\}$. Define a map $f:(X,\tau)\to (Y,\sigma)$ by f(a)=b, f(b)=a, f(c)=c. Here, f is b*\(\hat{g}\)-continuous, since the inverse images of C(Y) \{b,c\} and $\{a\}$ are $\{a,c\}$ and $\{b\}$ respectively which are $b*\hat{g}C(X)$.

Definition 3.3: A map $f:(X,\tau)\to (Y,\sigma)$ is said to be b* \hat{g} -irresolute map if the inverse image of every b* \hat{g} -closed set in (Y, σ) is b* \hat{g} -closed in (X, τ) .

That is, $f^{-1}(V)$ is b* \hat{g} -closed of (X, τ) for every b* \hat{g} -closed set V of (Y, σ) .

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Example 3.4: Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{X, \{b\}, \{c\}, \{b, c\}\}$ and $\sigma = \{Y, \phi, \{a, c\}\}$. Define a map $f: (X, \tau) \to (Y, \sigma)$ by f(a) = c, f(b) = a, f(c) = b. Here, f is $b*\hat{g}$ -continuous, since the inverse images of $b*\hat{g}C(Y)$ $\{b, c\}, \{a, b\}$ and $\{b\}$ are $\{a, b\}, \{a, c\}$ and $\{a\}$ respectively which are $b*\hat{g}C(X)$.

Proposition 3.5:

- a) Every continuous map is b*ĝ-continuous.
- b) Every α -continuous map is b* \hat{g} -continuous.
- c) Every semi-continuous map is b*ĝ-continuous.
- d) Every regular-continuous map is b*ĝ-continuous.
- e) Every gr*-continuous map is b*ĝ-continuous.
- f) Every g*s-continuous map is b*ĝ-continuous.
- g) Every (gs)*-continuous map is b*ĝ-continuous.

Proof:

- a) Let $f:(X,\tau)\to (Y,\sigma)$ be continuous. Let V be a closed set in (Y,σ) . Since f is continuous, $f^{-1}(V)$ is closed set in (X,τ) . By proposition 3.4 in [4], $f^{-1}(V)$ is $b*\hat{g}$ -closed in (X,τ) . Hence f is $b*\hat{g}$ -continuous.
- b) Let $f:(X,\tau) \to (Y,\sigma)$ be α -continuous. Let V be a closed set in (Y,σ) . Since f is α -continuous, $f^{-1}(V)$ is α -closed set in (X,τ) . By proposition 3.6 in [4], $f^{-1}(V)$ is $b*\hat{g}$ -closed in (X,τ) . Hence f is $b*\hat{g}$ -continuous.
- c) Let $f:(X,\tau) \to (Y,\sigma)$ be semi-continuous. Let V be a closed set in (Y,σ) . Since f is semi-continuous, $f^{-1}(V)$ is semi-closed set in (X,τ) . By proposition 3.6 in [4], $f^{-1}(V)$ is b* \hat{g} -closed in (X,τ) . Hence f is b* \hat{g} -continuous.
- d) Let $f:(X,\tau) \to (Y,\sigma)$ be regular-continuous. Let V be a closed set in (Y,σ) . Since f is regular-continuous, $f^{-1}(V)$ is regular-closed set in (X,τ) . By proposition 3.6 in [4], $f^{-1}(V)$ is $b*\hat{g}$ -closed in (X,τ) . Hence f is $b*\hat{g}$ -continuous.
- e) Let $f:(X,\tau) \to (Y,\sigma)$ be gr*-continuous. Let V be a closed set in (Y,σ) . Since f is gr*-continuous, $f^{-1}(V)$ is gr*-closed set in (X,τ) . By proposition 3.16 in [4], $f^{-1}(V)$ is b* \hat{g} -closed in (X,τ) . Hence f is b* \hat{g} -continuous.
- f) Let $f:(X,\tau) \to (Y,\sigma)$ be g*s-continuous. Let V be a closed set in (Y,σ) . Since f is g*s-continuous, $f^{-1}(V)$ is g*s-closed set in (X,τ) . By proposition 3.18 in [4], $f^{-1}(V)$ is b* \hat{g} -closed in (X,τ) . Hence f is b* \hat{g} -continuous.
- g) Let $f:(X,\tau) \to (Y,\sigma)$ be (gs)*-continuous. Let V be a closed set in (Y,σ) . Since f is (gs)*-continuous, $f^{-1}(V)$ is (gs)*-closed set in (X,τ) . By proposition 3.20 in [4], $f^{-1}(V)$ is b* \hat{g} -closed in (X,τ) . Hence f is b* \hat{g} -continuous.

The following examples show that the converse of the above proposition need not be true.

Example 3.6:

- a) Let $X = Y = \{a, b, c\}$ with topologies $= \{X, \{a\}\}$ and $\sigma = \{Y, \phi, \{a\}, \{a, b\}, \{a, c\}\}$. Define a function $f: (X, \tau) \to (Y, \sigma)$ by f(a) = a, f(b) = c, f(c) = b. Here, f is b* \hat{g} -continuous but not continuous, since the inverse image of C(Y) {b, c}, {c} and {b} are {b, c}, {b} and {c} which are b* $\hat{g}C(X)$ but not C(X).
- b) Let $X=Y=\{a, b, c\}$ with topologies $\tau=\{X,\phi,\{a\},\{c\},\{a,c\},\{b,c\}\}\}$ and $\sigma=\{Y,\phi,\{a\},\{b,c\}\}\}$. Define a function $f:(X,\tau)\to (Y,\sigma)$ by f(a)=b, f(b)=a, f(c)=b. $\alpha C(X)=\{X,\phi,\{a\},\{a,b\},\{b,c\}\}\}$. Here, f is $b*\hat{g}$ -continuous but not α -continuous, since the inverse image of C(Y) {b, c} and {a} are {a, b} and {b} which are $b*\hat{g}C(X)$ but not $\alpha C(X)$.
- c) Let $X=Y=\{a, b, c\}$ with topologies $\tau=\{X,\phi,\{a,c\}\}$ and $\sigma=\{Y,\phi,\{a\}\}$. Define a function $f:(X,\tau)\to (Y,\sigma)$ by f(a)=c, f(b)=a, f(c)=b. $sC(X)=\{X,\phi,\{b\}\}$. Here, f is $b*\hat{g}$ -continuous but not semi-continuous, since the inverse image of C(Y) {b,c} is {a,b} which is $b*\hat{g}C(X)$ but not sC(X).
- d) Let $X=Y=\{a, b, c\}$ with topologies $\tau=\{X, \phi, \{a\}, \{b\}, \{a, b\}\}$ and $\sigma=\{Y, \phi, \{a\}, \{a, b\}, \{a, c\}\}\}$. Define a function $f:(X,\tau)\to (Y,\sigma)$ by f(a)=b, f(b)=c, f(c)=a. $rC(X)=\{X,\phi, \{a, c\}, \{b, c\}\}\}$. Here, f is $b*\hat{g}$ -continuous but not regular continuous, since the inverse image of C(Y) $\{b, c\}$, $\{c\}$ and $\{b\}$ are $\{a, c\}$, $\{a\}$ and $\{c\}$ which are $b*\hat{g}C(X)$ but not rC(X).
- e) Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{X, \{b\}\}$ and $\sigma = \{Y, \phi, \{c\}, \{a, b\}\}$. Define a function $f: (X, \tau) \to (Y, \sigma)$ by (a) = c, f(b) = b, f(c) = a. gr*C(X) = $\{X, \phi, \{a, c\}\}$. Here, f is b* \hat{g} -continuous but not gr*-continuous, since the inverse image of C(Y) $\{a, b\}$ and $\{c\}$ are $\{b, c\}$ and $\{a\}$ which are b* \hat{g} C(X) but not gr*C(X).
- f) Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{X, \{b\}\}$ and $\sigma = \{Y, \phi, \{c\}, \{a, b\}\}$. Define a function $f: (X, \tau) \to (Y, \sigma)$ by (a) = c, f(b) = b, f(c) = a. $g*sC(X) = \{X, \phi, \{a, c\}\}$. Here, f is $b*\hat{g}$ -continuous but not g*s-continuous, since the inverse image of C(Y) $\{a,b\}$ and $\{c\}$ are $\{b, c\}$ and $\{a\}$ which are $b*\hat{g}C(X)$ but not g*sC(X).
- g) Let $X = Y = \{a, b, c\}$ with topologies $= \{X, \{b\}, \{c\}, \{b, c\}\}\}$ and $\sigma = \{Y, \phi, \{a, c\}\}\}$. Define a function $f: (X, \tau) \to (Y, \sigma)$ by f(a) = b, f(b) = c, f(c) = a. (gs)*C(X)= $\{X, \phi, \{a\}, \{a, b\}, \{a, c\}\}\}$. Here, f is b* \hat{g} -continuous but not (gs)*-continuous, since the inverse image of C(Y) $\{b\}$ is $\{c\}$ which is b* \hat{g} C(X) but not (gs)*C(X).

Proposition: 3.7

- a) Every b*ĝ-continuous is gb-continuous.
- b) Every b*ĝ-continuous is gs-continuous.
- c) Every b*ĝ-continuous is bĝ-continuous.

Proof:

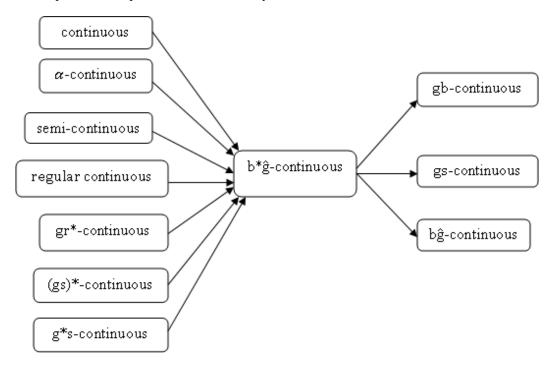
- a) Let $f:(X,\tau) \to (Y,\sigma)$ be b* \hat{g} -continuous. Let V be a closed set in (Y,σ) . Since f is b* \hat{g} -continuous, $f^{-1}(V)$ is b* \hat{g} -closed set in (X,τ) . By proposition 3.12 in [4], $f^{-1}(V)$ is gb-closed in (X,τ) . Hence f is gb-continuous.
- b) Let $f: (X, \tau) \to (Y, \sigma)$ be b* \hat{g} -continuous. Let V be a closed set in (Y, σ) . Since f is b* \hat{g} -continuous, $f^{-1}(V)$ is b* \hat{g} -closed set in (X, τ) . By proposition 3.8 in [4], $f^{-1}(V)$ is gs-closed in (X, τ) . Hence f is gs-continuous.
- c) Let $f:(X,\tau) \to (Y,\sigma)$ be b* \hat{g} -continuous. Let V be a closed set in (Y,σ) . Since f is b* \hat{g} -continuous, $f^{-1}(V)$ is b* \hat{g} -closed set in (X,τ) . By proposition 3.10 in [4], $f^{-1}(V)$ is b \hat{g} -closed in (X,τ) . Hence f is b \hat{g} -continuous.

The following examples show that the converse of the above proposition need not be true.

Example: 3.8

- a) Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{X, \phi, \{a, c\}\}$ and $\sigma = \{Y, \phi, \{a\}, \{b\}, \{a, b\}, \{a, c\}\}\}$. Define a function $f: (X, \tau) \to (Y, \sigma)$ by f(a) = c, f(b) = a, f(c) = b. b* $\hat{g}C(X) = \{X, \phi, \{b\}, \{a, b\}, \{b, c\}\}\}$ and $gbC(X) = \{X, \phi, \{a\}, \{b\}, \{c\}, \{a, b\}, \{b, c\}\}\}$. Here, f is gb-continuous but not b* \hat{g} -continuous, since the inverse image of C(Y) {b, c}, {a, c}, {c} and {b} are {a, b}, {b, c}, {b} and {a} which are gbC(X) but not b* $\hat{g}C(X)$.
- b) Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{X, \{a\}, \{b, c\}\}$ and $\sigma = \{Y, \phi, \{a\}\}$. Define a function $f: (X, \tau) \to (Y, \sigma)$ by f(a) = c, f(b) = a, f(c) = b. $b*\hat{g}C(X)=\{X,\phi,\{a\},\{b, c\}\}$ and $gsC(X)=\{X,\phi,\{a\},\{b\}, \{c\},\{a, b\}, \{b, c\},\{a, c\}\}$. Here, f is gs-continuous but not $b*\hat{g}$ -continuous, since the inverse image of C(Y) $\{b, c\}$ is $\{a, b\}$ which is gsC(X) but not $b*\hat{g}C(X)$.
- c) Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{X, \{c\}, \{a, b\}\}$ and $\sigma = \{Y, \phi, \{a\}\}$. Define a function $f: (X, \tau) \to (Y, \sigma)$ by f(a) = b, f(b) = a, f(c) = c. $b*\hat{g}C(X)=\{X, \phi, \{c\}, \{a, b\}\}$ and $b\hat{g}C(X)=\{X, \phi, \{a\}, \{b\}, \{c\}, \{a, b\}, \{b, c\}, \{a, c\}\}$. Then f is $b\hat{g}$ -continuous but not $b*\hat{g}$ -continuous, since the inverse image of C(Y) $\{b, c\}$ is $\{a, c\}$ which is $b\hat{g}C(X)$ but not $b*\hat{g}C(X)$.

Remark: 3.9 The following diagram shows the relationships of $b*\hat{g}$ -continuous functions with other known existing functions. A \rightarrow B represents A implies B but not conversely.



Proposition 3.10: Every b*ĝ-irresolute is b*ĝ-continuous.

Proof: Let $f:(X,\tau) \to (Y,\sigma)$ be b* \hat{g} -irresolute. Let V be closed in (Y,σ) . By proposition 3.4 in [4], V is b* \hat{g} -closed in (Y,σ) . Since f is b* \hat{g} -irresolute, $f^{-1}(V)$ is a b* \hat{g} -closed set in (X,τ) . Hence f is b* \hat{g} -continuous.

The following example shows that the converse of the above proposition need not be true.

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Example 3.11: Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{X, \{a, c\}\}$ and $\sigma = \{Y, \phi, \{b\}\}$. Define a function $f: (X, \tau) \to (Y, \sigma)$ by f(a) = b, f(b) = a, f(c) = c. b* $\hat{g}C(X) = \{X, \phi, \{b\}, \{a, b\}, \{b, c\}\}$ and b* $\hat{g}C(Y) = \{Y, \phi, \{a\}, \{c\}, \{a, b\}, \{b, c\}, \{a, c\}\}$. Here, f is b* \hat{g} -continuous but not b* \hat{g} -irresolute, since the inverse image of C(Y) {a,c} is {b, c} which is b* $\hat{g}C(X)$ but the inverse image of b* $\hat{g}C(Y)$ {a},{c}, {a, b},{b, c} and {a, c} are {b},{c},{a, b},{a, c} and {b, c} which are not b* $\hat{g}C(X)$.

Proposition 3.12: Let $f:(X,\tau) \to (Y,\sigma)$ be a b* \hat{g} -continuous map. If (X,τ) is $T_{b*\hat{g}}$ -space then f is continuous.

Proof: Let $f:(X,\tau) \to (Y,\sigma)$ be b* \hat{g} -continuous. Let V be a closed set in (Y,σ) . Since f is b* \hat{g} -continuous, $f^{-1}(V)$ is b* \hat{g} -closed set in (X,τ) . Since (X,τ) is $T_{b*\hat{g}}$ -space, $f^{-1}(V)$ is closed set in (X,τ) . Hence f is continuous.

Proposition 3.13: Let $f:(X,\tau) \to (Y,\sigma)$ be a b* \hat{g} -continuous map. If (X,τ) is $T_{b\hat{g}}$ -space then f is b-continuous.

Proof: Let $f:(X,\tau) \to (Y,\sigma)$ be b* \hat{g} -continuous. Let V be a closed set in (Y,σ) . Since f is b* \hat{g} -continuous, $f^{-1}(V)$ is b* \hat{g} -closed set in (X,τ) . By proposition 3.10 in [4], $f^{-1}(V)$ is b \hat{g} -closed set in (X,τ) . Since (X,τ) is $T_{b\hat{g}}$ -space, $f^{-1}(V)$ is b-closed set in (X,τ) . Hence f is b-continuous.

Proposition 3.14: Let $f:(X,\tau) \to (Y,\sigma)$ be a b* \hat{g} -continuous map. If (X,τ) is T_{gs} -space then f is b-continuous.

Proof: Let $f:(X,\tau) \to (Y,\sigma)$ be b* \hat{g} -continuous. Let V be a closed set in (Y,σ) . Since f is b* \hat{g} -continuous, $f^{-1}(V)$ is b* \hat{g} -closed set in (X,τ) . By proposition 3.12 in [4], $f^{-1}(V)$ is gb-closed set in (X,τ) . Since (X,τ) is T_{gs} -space, $f^{-1}(V)$ is b-closed set in (X,τ) . Hence f is b-continuous.

Proposition 3.15: Let $f:(X,\tau) \to (Y,\sigma)$ be a b* \hat{g} -continuous map. If (X,τ) is T_b -space then f is continuous.

Proof: Let $f:(X,\tau) \to (Y,\sigma)$ be b* \hat{g} -continuous. Let V be a closed set in (Y,σ) . Since f is b* \hat{g} -continuous, $f^{-1}(V)$ is b* \hat{g} -closed set in (X,τ) . By proposition 3.8 in [4], $f^{-1}(V)$ is gs-closed set in (X,τ) . Since (X,τ) is T_b -space, $f^{-1}(V)$ is closed set in (X,τ) . Hence f is continuous.

Proposition 3.16: Let $f:(X,\tau) \to (Y,\sigma)$ be a b* \hat{g} -continuous map. If (X,τ) is $T^*_{b\hat{g}}$ -space then f is continuous.

Proof: Let $f:(X,\tau) \to (Y,\sigma)$ be b* \hat{g} -continuous. Let V be a closed set in (Y,σ) . Since f is b* \hat{g} -continuous, $f^{-1}(V)$ is b* \hat{g} -closed set in (X,τ) . By proposition 3.10 in [4], $f^{-1}(V)$ is b \hat{g} -closed set in (X,τ) . Since (X,τ) is $T^*_{b\hat{g}}$ -space, $f^{-1}(V)$ is closed set in (X,τ) . Hence f is continuous.

4. b*g-OPEN MAPS and b*g-CLOSED MAPS

We introduce the following definitions.

Definition 4.1: Let X and Y be two topological spaces. A map $f:(X,\tau)\to (Y,\sigma)$ is called b* \hat{g} -open map if for each open set Y of Y, Y open set in Y.

That is, image of every open set in (X, τ) is b* \hat{g} -open in (Y, σ) .

Definition 4.2: Let X and Y be two topological spaces. A map $f:(X,\tau) \to (Y,\sigma)$ is called b* \hat{g} -closed map if for each closed set Y of X, f(Y) is b* \hat{g} -closed set in Y.

That is, image of every closed set in (X, τ) is b* \hat{g} -closed in (Y, σ) .

Example 4.3: Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{X, \{a\}, \{b, c\}\}$ and $\sigma = \{Y, \phi, \{a\}\}$. Define a function $f: (X, \tau) \to (Y, \sigma)$ by f(a) = b, f(b) = a, f(c) = c. Then f is $b*\hat{g}$ -open map, since the image of O(X) $\{a\}, \{b, c\}$ are $\{b\}, \{a, c\}$ which are $b*\hat{g}O(Y)$. Also, f is $b*\hat{g}$ -closed map.

Proposition 4.4:

- a) Every open map is b*ĝ-open map.
- b) Every α -open map is b* \hat{g} -open map.
- c) Every semi-open map is b*ĝ-open map.
- d) Every regular open map is b*ĝ-open map.
- e) Every gr*-open map is b*ĝ-open map.
- f) Every g*s-open map is b*ĝ-open map.
- g) Every (gs)*-open map is b*ĝ-open map.

Proof:

- a) Let $f:(X,\tau) \to (Y,\sigma)$ be an open map and V be an open set in (X,τ) . Since f is an open map, f(V) is an open set in (Y,σ) . By proposition 3.4 in [4], f(V) is an b* \hat{g} -open set in (Y,σ) . Hence f is b* \hat{g} -open map.
- b) Let $f: (X, \tau) \to (Y, \sigma)$ be an α -open map and V be an open set in (X, τ) . Since f is an α -open map, f(V) is an α -open set in (Y, σ) . By proposition 3.6 in [4], f(V) is an b* \hat{g} -open set in (Y, σ) . Hence f is b* \hat{g} -open map.
- c) Let $f:(X,\tau) \to (Y,\sigma)$ be an semi-open map and V be an open set in (X,τ) . Since f is an semi-open map, f(V) is an semi-open set in (Y,σ) . By proposition 3.6 in [4], f(V) is an b* \hat{g} -open set in (Y,σ) . Hence f is b* \hat{g} -open map.
- d) Let $f:(X,\tau) \to (Y,\sigma)$ be an regular open map and V be an open set in (X,τ) . Since f is an regular open map, f(V) is an regular open set in (Y,σ) . By proposition 3.6 in [4], f(V) is an b* \hat{g} -open set in (Y,σ) . Hence f is b* \hat{g} -open map.
- e) Let $f: (X, \tau) \to (Y, \sigma)$ be an gr*-open map and V be an open set in (X, τ) . Since f is an gr*-open map, f(V) is an gr*-open set in (Y, σ) . By proposition 3.16 in [4], f(V) is an b* \hat{g} -open set in (Y, σ) . Hence f is b* \hat{g} -open map.
- f) Let $f: (X, \tau) \to (Y, \sigma)$ be an g*s-open map and V be an open set in (X, τ) . Since f is an g*s-open map, f(V) is an g*s-open set in (Y, σ) . By proposition 3.18 in [4], f(V) is an b* \hat{g} -open set in (Y, σ) . Hence f is b* \hat{g} -open map.
- g) Let $f:(X,\tau) \to (Y,\sigma)$ be an $(gs)^*$ -open map and V be an open set in (X,τ) . Since f is an $(gs)^*$ -open map, f(V) is an $(gs)^*$ -open set in (Y,σ) . By proposition 3.20 in [4], f(V) is an $b^*\hat{g}$ -open set in (Y,σ) . Hence f is $b^*\hat{g}$ -open map.

The following example shows that the converse of the above proposition need not be true.

Example 4.5:

- a) Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{X, \{a\}, \{b\}, \{a, b\}, \{a, c\}\}\}$ and $= \{Y, \phi, \{a\}\}$. Define a function $f: (X, \tau) \to (Y, \sigma)$ by f(a) = a, f(b) = c, f(c) = b. $b*\hat{g}O(Y) = \{Y, \phi, \{a\}, \{b\}, \{c\}, \{a, b\}, \{a, c\}\}\}$. Here, f is $b*\hat{g}$ -open map but not open map, since the image of O(X) $\{a\}, \{b\}, \{a, b\}\}$ and $\{a, c\}$ are $\{a\}, \{c\}, \{a, c\}$ and $\{a, b\}$ which are $b*\hat{g}O(Y)$ but not O(Y).
- b) Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{X, \phi, \{a\}, \{b\}, \{a, b\}\}$ and $\sigma = \{Y, \phi, \{a, b\}\}$. Define a function $f: (X, \tau) \to (Y, \sigma)$ by f(a) = b, f(b) = a, f(c) = c. $b*\hat{g}O(Y) = \{Y, \phi, \{a\}, \{b\}, \{a, b\}\}$ and $\alpha O(Y) = \{Y, \phi, \{a\}, \{b\}\}$. Here, f is $b*\hat{g}$ -open map but not α -open map, since the image of O(X) $\{a\}, \{b\}$ and $\{a, b\}$ are $\{b\}, \{a\}$ and $\{a, b\}$ which are $b*\hat{g}O(Y)$ but not $\alpha O(Y)$.
- c) Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{X, \phi, \{a\}, \{b\}, \{a, b\}\}\}$ and $\sigma = \{Y, \phi, \{a\}\}\}$. Define a function $f: (X, \tau) \to (Y, \sigma)$ by f(a) = c, f(b) = a, f(c) = b. $b*\hat{g}O(Y) = \{Y, \phi, \{a\}, \{b\}, \{c\}, \{a, b\}, \{a, c\}\}\}$ and $sO(Y) = \{Y, \phi, \{a\}, \{a, b\}, \{a, c\}\}\}$. Here, f is $b*\hat{g}$ -open map but not semi-open map, since the image of O(X) $\{a\}, \{b\}$ and $\{a, b\}$ are $\{c\}, \{a\}$ and $\{a, c\}$ which are $b*\hat{g}O(Y)$ but not sO(Y).
- d) Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{X, \{a\}, \{b, c\}\}$ and $\sigma = \{Y, \phi, \{a\}, \{b\}, \{a, b\}\}$. Define a function $f: (X, \tau) \to (Y, \sigma)$ by f(a) = b, f(b) = a, f(c) = c. b* \hat{g} O(Y)= $\{Y, \phi, \{a\}, \{b\}, \{a, b\}, \{b, c\}, \{a, c\}\}$ and rO(Y)= $\{Y, \phi, \{a\}, \{b\}\}$. Here, f is b* \hat{g} -open map but not regular open map, since the image of O(X) $\{a\}$ and $\{b, c\}$ are $\{b\}$ and $\{a, c\}$ which are b* \hat{g} O(Y) but not rO(Y).
- f) Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{X, \phi, \{a\}, \{b\}, \{a, b\}\}$ and $\sigma = \{Y, \phi, \{b\}\}$. Define a function $f: (X, \tau) \to (Y, \sigma)$ by f(a) = c, f(b) = b, f(c) = a. $b*\hat{g}O(Y) = \{Y, \phi, \{a\}, \{b\}, \{c\}, \{a, b\}, \{b, c\}\}$ and $g*sO(Y) = \{Y, \phi, \{b\}, \{a, b\}, \{b, c\}\}$. Here, f is $b*\hat{g}$ -open map but not g*s-open map, since the image of O(X) $\{a\}, \{b\}$ and $\{a, b\}$ are $\{c\}, \{b\}$ and $\{b, c\}$ which are $b*\hat{g}O(Y)$ but not g*sO(Y).
- g) Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{X, \phi, \{c\}, \{a, b\}\}$ and $\sigma = \{Y, \phi, \{b\}, \{c\}, \{b, c\}\}\}$. Define a function $f: (X, \tau) \to (Y, \sigma)$ by f(a) = a, f(b) = c, f(c) = b. $b*\hat{g}O(Y) = \{Y, \phi, \{b\}, \{c\}, \{a, b\}, \{b, c\}, \{a, c\}\}\}$ and $(gs)*O(Y) = \{Y, \phi, \{b\}, \{c\}, \{b, c\}\}\}$. Here, f is $b*\hat{g}$ -open map but not (gs)*-open map, since the image of O(X) $\{c\}$ and $\{a, b\}$ are $\{b\}$ and $\{a, c\}$ which are $b*\hat{g}O(Y)$ but not (gs)*O(Y).

Proposition 4.6:

- a) Every b*ĝ-open map is gs-open map.
- b) Every b*ĝ-open map is gb-open map.
- c) Every b*ĝ-open map is bĝ-open map.

Proof:

a) Let $f:(X,\tau) \to (Y,\sigma)$ be a b* \hat{g} -open map and V be an open set in X. Since f is b* \hat{g} -open map, f(V) is b* \hat{g} -open set in Y. By proposition 3.8 in [4], f(V) is gs-open set in Y. Hence f is gs-open map.

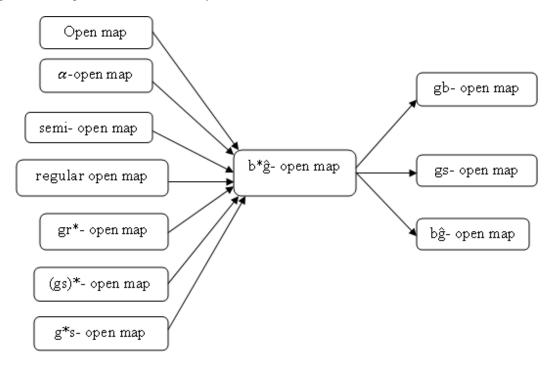
- b) Let $f:(X,\tau) \to (Y,\sigma)$ be a b* \hat{g} -open map and V be an open set in X. Since f is b* \hat{g} -open map, f(V) is b* \hat{g} -open set in Y. By proposition 3.12 in [4], f(V) is gb-open set in Y. Hence f is gb-open map.
- c) Let $f:(X,\tau) \to (Y,\sigma)$ be a b* \hat{g} -open map and V be an open set in X. Since f is b* \hat{g} -open map, f(V) is b* \hat{g} -open set in Y. By proposition 3.10 in [4], f(V) is b \hat{g} -open set in Y. Hence f is b \hat{g} -open map.

The following example shows that the converse of the above proposition need not be true.

Example 4.7:

- a) Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{X, \phi, \{a\}, \{b\}, \{a, b\}\}$ and $\sigma = \{Y, \phi, \{a\}, \{b, c\}\}$. Define a function $f: (X, \tau) \to (Y, \sigma)$ by f(a) = c, f(b) = a, f(c) = b. $b*\hat{g}O(Y) = \{Y, \phi, \{a\}, \{b, c\}\}\}$ and $gsO(Y) = \{Y, \phi, \{a\}, \{b\}, \{c\}, \{a, b\}, \{b, c\}, \{a, c\}\}\}$. Here, f is gs-open map but not $b*\hat{g}$ -open map, since the image of O(X) $\{a\}, \{b\}$ and $\{a, b\}$ are $\{c\}, \{a\}$ and $\{a, c\}$ which are gsO(Y) but not $b*\hat{g}O(Y)$.
- c) Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{X, \phi, \{a\}, \{b\}, \{a, b\}\}$ and $\sigma = \{Y, \phi, \{c\}, \{a, b\}\}$. Define a function $f: (X, \tau) \to (Y, \sigma)$ by f(a) = b, f(b) = c, f(c) = a. b*g O(Y)= $\{Y, \phi, \{a, b\}, \{c\}\}$ and bgO(Y)= $\{Y, \phi, \{a\}, \{b\}, \{c\}, \{a, b\}, \{b, c\}, \{a, c\}\}$. Here, f is bg-open map but not b*g-open map, since the image of O(X) $\{a\}, \{b\}$ and $\{a, b\}$ are $\{b\}, \{c\}$ and $\{b, c\}$ which are bgO(Y) but not b*gO(Y).

Remark 4.8: The following diagram shows the relationships of $b*\hat{g}$ -open map with other known existing open maps. $A \rightarrow B$ represents A implies B but not conversely.



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