

ON $f_{\lambda,\mu}(2\nu+3,\pm1)$ -STRUCTURE MANIFOLDS

¹Shadab Ahmad Khan* and ²Ram Nivas

¹Assistant Professor, Deptt. of Mathematics, Integral University, Lucknow, India

²Ex. HOD, Deptt. of Mathematics, University of Lucknow, India

E-mail: sakhan.lko@gmail.com

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ABSTRACT

The idea of f-structure on a differentiable manifold was initiated and developed by Yano [6], Ishihara [1], Andreaou [2] and others. In the present paper, we have defined a structure f_{\lambda,\mu}(2\nu+3,\pm1) of rank r on a manifold with a

tensor field f of type (1, 1) satisfying $(f^{2\nu+3} - \lambda^2 f)(f^{2\nu+3} + \mu^2 f) = 0$ Some results on this structure have been proved in this paper.

(1.1) **PRELIMINARIES:**

Let M^n be an n-dimensional differentiable manifold of class C^{∞} and of rank r and $f(\neq 0)$ be a tensor field of type (1, 1), such that

(1.1.1)
$$\left(f^{2\nu+3} - \lambda^2 f \right) \left(f^{2\nu+3} + \mu^2 f \right) = 0$$

where $f^{2\nu+2} \neq \lambda^2$, $f^{2\nu+2} \neq -\mu^2$; $\lambda, \mu \in \mathbb{R}^+$, $\lambda \neq \mu$ and rank of

$$f = \frac{1}{2} \left(\operatorname{rank} f^{2\nu+2} + \dim M^n \right) = r = \operatorname{constant}.$$

Let us define tensor fields 'l' and 'm' of type (1, 1) on M^n , by

(1.1.2)
$$l = -\frac{f^{2\nu+2} - \lambda^2}{\mu^2 + \lambda^2} , \quad m = \frac{f^{2\nu+2} + \mu^2}{\lambda^2 + \mu^2}$$

We have the following theorem:

Theorem 1.1.1: Let M^n be an $f_{\lambda,\mu}(2\nu+3,\pm 1)$ -structure manifold, then

(1.1.3)
$$l+m=I$$
, $l^2=l$, $m^2=m$, $lm=ml=0$

Proof: In view of the equations (1.1.1) and (1.1.2), the proof of the theorem follows in obvious manner.

Thus, the operators l and m when applied to tangent space of M^n at a point are complementary projection operators. Thus there exist complementary distributions L and M corresponding to projection operators l and m respectively. Let us call such a structure as then -structure of rank r.

*Corresponding author: *Dr. Shadab Ahmad Khan, *E-mail: sakhan.lko@gmail.com

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For the manifold M^n equipped with $f_{\lambda,\mu}(2\nu+3,\pm 1)$ -structure of rank r, we have the following theorem:

Theorem 1.1.2: On an $f_{\lambda,\mu}(2\nu+3,\pm 1)$ -structure manifold, we have

(1.1.4)
$$fl = -\frac{f^{2\nu+3} - f\lambda^2}{\lambda^2 + \mu^2} , \quad fm = \frac{f^{2\nu+3} + f\mu^2}{\lambda^2 + \mu^2}$$

(1.1.5)
$$f^{2\nu+2}l = -\mu^2 l$$
, $f^{2\nu+2}m = \lambda^2 m$

(1.1.6)
$$m-l = \frac{2f^{2\nu+2} - \lambda^2 - \mu^2}{\lambda^2 + \mu^2}$$

Proof: In view of the equations (1.1.1), (1.1.2) and (1.1.3), the proof of the theorem follows immediately.

$f_{\lambda,\mu}(2\nu+3,\pm1)$ -structure in local coordinates: (1.2)

We now introduce a local coordinate system in the manifold M^n represented by f_j^i, l_j^i, m_j^i in local components of tensors f, l and m respectively. We also introduce in M^n a positive definite Riemannian metric by taking r mutually orthogonal unit vectors $v_a^j(a,b,c,...,=1,2,3,...,r)$ in L and (n-r) mutually orthogonal unit vectors $v_A^j(A, B, C, = r + 1, r + 2,, n)$ in M, and then we have

(1.2.1)
$$l_{j}^{i}\mathbf{v}_{b}^{j} = \mathbf{v}_{b}^{i}, \ l_{j}^{i}\mathbf{v}_{B}^{j} = 0$$
$$m_{j}^{i}\mathbf{v}_{b}^{j} = 0, \ m_{j}^{i}\mathbf{v}_{B}^{j} = \mathbf{v}_{L}^{i}$$

Let (s_j^a, s_j^A) represents the matrix inverse of (v_b^j, v_B^j) , then s_j^a and s_j^A are both components of linearly independent covariant vectors and satisfy the relations $\frac{1}{R} = 0$

$$s_j^a \mathbf{v}_b^j = \delta_b^a$$
, $s_j^a \mathbf{v}_b^j$

$$s_j^A \mathbf{v}_b^j = 0, \ s_j^A \mathbf{v}_B^j = \boldsymbol{\delta}_B^A$$

and

(1.2.3)
$$s_j^a \mathbf{v}_a^i + s_j^A \mathbf{v}_A^i = \delta_j^i$$

 δ^i_i being the Kronecker delta.

If we put

then g_{kj} is globally well defined positive Riemannian metric such that

$$s_k^a = g_{kj} \mathbf{v}_a^j , \quad s_k^A = g_{kj} \mathbf{v}_A^j$$

In view of the equations (1.2.1) and (1.2.2), we get

$$\left(l_{j}^{i}\mathbf{s}_{i}^{a}\right)\mathbf{v}_{b}^{j}=\boldsymbol{\delta}_{b}^{a},\ \left(l_{j}^{i}\mathbf{s}_{i}^{a}\right)\mathbf{v}_{B}^{j}=0$$

(1.2.5)
$$\begin{pmatrix} m_j^i \mathbf{s}_i^A \end{pmatrix} \mathbf{v}_b^j = \mathbf{0}, \begin{pmatrix} m_j^i \mathbf{s}_i^A \end{pmatrix} \mathbf{v}_B^j = \boldsymbol{\delta}_B^A$$

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Thus we have,

(1.2.6)

$$l_j^i \mathbf{s}_i^a = s_j^a , \ m_j^i \mathbf{s}_i^A = \mathbf{s}_j^A$$
$$l_j^i \mathbf{s}_i^A = 0, \ m_j^i \mathbf{s}_i^a = 0$$

Using $l_j^i \mathbf{v}_a^j = \mathbf{v}_a^i$ in equation (1.2.6), we have

$$l_k^i \mathbf{s}_j^a \mathbf{v}_a^k = \mathbf{s}_j^a \mathbf{v}_a^i, \ l_k^i \left(\boldsymbol{\delta}_j^k - \mathbf{s}_j^A \mathbf{v}_A^k \right) = \mathbf{s}_j^a \mathbf{v}_a^i$$

Hence

 $(1.2.7) l_j^i = s_j^a v_a^i$

Similarly, we get

(1.2.8)
$$m_j^i = s_j^B v_B^i$$

Let us now put

(1.2.9)
$$l_{kj} = l_k^r g_{rj} \text{ and } m_{kj} = m_k^r g_{rj}$$

In view of the equations (1.2.4), (1.2.7) and (1.2.8), we have

(1.2.10)
$$l_{kj} = \mathbf{s}_k^a \mathbf{s}_j^a , \quad m_{kj} = \mathbf{s}_k^A \mathbf{s}_j^A$$

and
(1.2.11)
$$l_{kj} = l_{jk} , \quad m_{kj} = m_{jk}$$

Consequently, we have

(1.2.12)
$$l_{jk} + m_{jk} = g_{jk}$$

and

and

The following equations can be proved easily:

(i)
$$l_k^r l_j^p g_{rp} = l_{kj}$$

(ii) $l_k^r m_j^p g_{rp} = 0$

(1.2.13)

(iii)
$$m_k^r m_j^p g_{\rm rp} = m_{\rm kj}$$

For any two vectors X and Y with components X^{i} and Y^{i} , let us put $m(X, Y) = m_{rp}X^{r}Y^{p}$

(1.2.14)

$$g(\mathbf{X},\mathbf{Y}) = g_{rp}\mathbf{X}^{r}\mathbf{X}^{p}$$

(1.2.15)

$$\tilde{g}(X,Y) = \frac{1}{2} \frac{1}{(\nu+1)} \left[g(X,Y) + g(fX,fY) + g(f^2X,f^2Y) + \dots + g(f^{2\nu+1}X,f^{2\nu+1}Y) + m(X,Y) \right]$$

Thus we have

$$m(v_{A},v_{A}) = g(v_{A},v_{A}) = g(fv_{A},fv_{A}) = g(f^{2}v_{A},f^{2}v_{A}) = = g(f^{2\nu+1}v_{A},f^{2\nu+1}v_{A}) = 0$$

and

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$$\tilde{g}(v_{A},v_{A}) = \frac{1}{2} \frac{1}{(\nu+1)} \Big[g(v_{A},v_{A}) + g(fv_{A},fv_{A}) + g(f^{2}v_{A},f^{2}v_{A}) + \dots + g(f^{2\nu+1}v_{A},f^{2\nu+1}v_{A}) + m(v_{A},v_{A}) \Big] = 0$$

By virtue of the fact that the distributions L and M are orthogonal with respect to the Riemannian metric g, the distributions L and M are orthogonal with respect to \tilde{g} also. Hence, we have the following theorem:

Theorem 1.2.1: Let M^n be an n-dimensional differentiable manifold equipped with $f_{\lambda,\mu}(2\nu+3,\pm 1)$ - structure of rank r. Then there exist complementary distributions L and M and a positive definite Riemannian metric \tilde{g} with respect to which distributions are orthogonal.

Further, by virtue of equations (1.2.9), (1.2.11) and (1.2.12) it is easy to verify that

$$g(\mathbf{fv}_{a}, \mathbf{fv}_{b}) = l_{rp} \mathbf{f}_{h}^{r} \mathbf{f}_{j}^{p} \mathbf{v}_{a}^{h} \mathbf{v}_{b}^{j}$$

$$g(\mathbf{fv}_{a}, \mathbf{fv}_{b}) + m(\mathbf{fv}_{a}, \mathbf{fv}_{b}) = g_{rp} \mathbf{f}_{h}^{r} \mathbf{f}_{j}^{p} \mathbf{v}_{a}^{h} \mathbf{v}_{b}^{j}$$

$$g(\mathbf{f}^{2} \mathbf{v}_{a}, \mathbf{f}^{2} \mathbf{v}_{b}) = g_{rp} \mathbf{v}_{a}^{r} \mathbf{v}_{b}^{p}$$

These relations lead to the following:

(1.2.16)
$$\widetilde{g}(\mathbf{fX},\mathbf{fY}) = g(\mathbf{X},\mathbf{Y}) \; ; \; \text{ for all } \mathbf{X},\mathbf{Y} \text{ in } \mathbf{L}.$$

Let M_1 be a space such that $X \in M_1$, $f(X) = \lambda X$ and let M_2 be the distribution orthogonal to M_1 in M with respect to \tilde{g} . We choose an orthogonal basis u_{n-r+1} ,..., $u_{2(n-r)}$ with respect to \tilde{g} for M_2 . Further, let $e_1, e_2, \ldots, e_{2r-n}$ be an orthogonal basis for L with respect to \tilde{g} . Using \tilde{g} , we can define a Riemannian metric g on M^n by

$$g(e_{i}, e_{k}) = \tilde{g}(e_{i}, e_{k})$$

$$g(e_{i}, u_{\alpha}) = \tilde{g}(e_{i}, u_{\alpha})$$

$$g(u_{\alpha}, u_{\beta}) = \tilde{g}(u_{\alpha}, u_{\beta})$$

$$g(e_{i}, f(u_{\alpha})) = \tilde{g}(e_{i}, f(u_{\alpha}))$$

$$g(f(u_{\alpha}), u_{\beta}) = 0$$

$$g(f(u_{\alpha}), f(u_{\beta})) = \delta_{\alpha\beta}$$

where,

$$1 \le i, k \le 2r - n$$
, $n - r + 1 \le \alpha, \beta \le 2n - r$

then g is well defined because if $\tilde{u}_{n-r+1},\ldots,\tilde{u}_{2(n-r)}$ is another orthonormal basis for M_2 , then for $\tilde{u}_{\alpha} = z_{\alpha}^{\beta} u_{\beta}$, we have

$$\widetilde{g}(\widetilde{u}_{\alpha}, \widetilde{u}_{\gamma}) = \widetilde{g}(z_{\alpha}^{\beta} u_{\beta}, z_{\gamma}^{\varepsilon} u_{\varepsilon})$$
$$= z_{\alpha}^{\beta} z_{\gamma}^{\varepsilon} \delta_{\beta\varepsilon}$$
$$= z_{\alpha}^{\beta} z_{\gamma}^{\beta}$$
$$= \delta_{\alpha\gamma}$$

 $g(f(\tilde{u}_{\alpha}), f(\tilde{u}_{\gamma})) = g(z_{\alpha}^{\beta}f(u_{\beta}), z_{\gamma}^{\varepsilon}f(u_{\varepsilon}))$

and,

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¹Shadab Ahmad Khan* and ²Ram Nivas / ON $f_{\lambda,\mu}(2\nu + 3, \pm 1)$ -STRUCTURE MANIFOLDS//IJMA- 2(10), Oct.-2011, Page: 1849-1853 $= z_{\alpha}^{\beta} z_{\gamma}^{\varepsilon} g(f(u_{\beta}), f(u_{\varepsilon}))$ $= z_{\alpha}^{\beta} z_{\gamma}^{\beta}$ $= \delta_{\alpha\gamma}$

This signifies that there is a Riemannian metric g with respect to which L, M_1 , M_2 are mutually orthogonal and

$$g(\mathbf{fX}, \mathbf{fY}) = -\mu^2 \mathbf{f}$$
; for all X, Y in L
 $g(\mathbf{fX}, \mathbf{fY}) = \lambda^2 \mathbf{f}$; for all X, Y in M

Thus, we have:

Theorem 1.2.2: Let M^n be an n-dimensional differentiable manifold with $f_{\lambda,\mu}(2\nu+3,\pm1)$ -structure of rank r. Then there exists complementary distribution L of dimension (2r-n) and distribution M of dimension 2(n-r) and a positive definite Riemannian metric g with respect to which L and M are orthogonal and furthermore

$$g(fX, fY) = -\mu^2 f \quad ; \quad \forall X, Y \in L$$
$$g(fX, fY) = \lambda^2 f \quad ; \quad \forall X, Y \in L.$$

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