A NOTE ON INVARIANT SUBSPACES OF SOME OPERATORS IN HILBERT SPACE

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ABSTRACT

In this paper, we show that if M is a nontrivial invariant for both T and S, then M is ST —invariant or TS — invariant. An example is provided to illustrate that if M is TS —invariant, then it is not necessarily invariant for either T and S. However if TS, S and T have same structure and M is invariant for TS, then it is also invariant for T and S.

Keywords: Invariant subspaces, Nilpotent operators.

1. INTRODUCTION

The invariant subspaces of an operator plays a central role in operator they as they give information on the structure of the operator. They are a direct analogue of the eigen-vectors of a linear operator. The motivation behind the study of invariant subspaces come from the interest of structure of operators and from approximation theory. Let H be a Hilbert space and B(H) denotes all bounded linear operators on H. A subspace M of H is a invariant under operator T if $T(M) \subseteq M$, that is, $x \in M$ for every $Tx \in M$ or $TM \subset M$. If T is any subset of B(H), we denote by $\{T\}$ the commutant of T, that is $\{T\}' = \{T \in B(H): ST = TS\}$.

A subspace $M \subset H$ is said to be nontrivial hyper-invariant subspace (n.h.s) for a fixed operator in $T \in B(H)$ if $0 \neq M \neq H$ and $SM \subset M$ for each $S \in \{T\}$. An operator $T \in B(H)$ is nilpotentif $T^n = 0$.

Theorem 1.1: If $T \in B(H)$, then the following subspaces are invariant under T:

- (i) $\{0\}$.
- (ii) *H*.
- (iii) Ker (T)
- (iv) Ran (T)

Proof:

- (i) If $x \in \{0\}$, then x = 0 hence $Tx = 0 \in \{0\}$. Thus $\{0\}$ is invariant under T.
- (ii) If $x \in H$, then $Tx \in H$ since T on Hilbert space H is bounded, then it is bounded below and hence its range is closed. Thus H is invariant under T.
- (iii) If $x \in Ker(T)$, then Tx = 0 and hence $Tx \in Ker(T)$. Thus Ker(T) is invariant under T.
- (iv) Note that, since the operators T on a Hilbert space H is bounded below and hence its range is closed subspace of H. Thus T(Ran(T)) is contained in Ran(T). Let $x \in Ran(T)$, then $Tx \in Ran(T)$. Thus Ran(T) is invariant under T.

Lemma 1.2: Let $U_1, U_2 \subset H$ be invariant subspaces. Then $U_1 \cap U_2$ and $U_1 + U_2$ are invariant subspaces.

Proof: Suppose U_1 and U_2 are both under T, and $u \in U_1 \cap U_2$. Since U_1 is invariant under T, then $T(u) \in U_1$.

Similarly, since U_2 is invariant under T, then T (u) $\in U_2$ and so

 $T(u) \in U_1 \cap U_2$. Thus $U_1 \cap U_2$ is invariant under T.

Suppose $u \in U_1 + U_2$. Then $u = u_1 + u_2$ where $u_i \in U_i$ for i = 1, 2. Applying the linear operator on both sides of the equation we have

$$T(u) = T(u_1 + u_2) = T(u_1) + T(u_2).$$

Irene M. Muteti*, Bernard M. Nzimbi, Stanley K. Imagiri and Jairus M. Khalagai / A Note on Invariant subspaces of some operators in Hilbert Space / IJMA- 12(4), April-2021.

Because U_1, U_2 are all invariant subspace under T, and since $u_i \in U_i$ we have $T(u_i) \in U_i$

For i = 1,2. Hence T (u) is contained in $U_1 + U_2$ and therefore $U_1 + U_2$ is invariant under T.

Proposition 1.3: Let T and L be nonzero on a Hilbert space H. If LT = 0, then Ker(L) and Ran(T) are nontrivial invariant subspaces for both T and L.

Proof: If LT=0, then Ran (T) \subseteq Ker (L). Hence $T(Ker(L)) \subseteq T(H) = Ran(T) \subseteq Ker(L)$. Since $T \neq 0$, $Ran(T) \neq 0$, so that $Ker(L) \neq 0$. Since $L \neq 0$ Ker(L) $\neq H$. Therefore Ker(L) is nontrivial invariant subspace for T. Dually since $T^*L^*=0$, $L^*\neq 0$ it follows that $Ker(T^*)^{\perp}$ is nontrivial invariant subspace for L^* , and hence $Ran(T) = Ker(T^*)^{\perp}$ is a nontrivial invariant subspace for L.

Remark 1.1: Ker(L) and $\overline{Ran(T)}$ are invariant subspaces for L and T.

Proposition 1.3 leads to the following result.

Corollary 1.1: Every nilpotent operator has a nontrivial invariant subspace.

Proof: Recall that, an operator is nilpotent if $T^n = 0$. Thus $T^n = T(T^{n-1})$ which can be written as a product of two operators and by Proposition 1.3 Ker(T) and $\overline{Ran(T^{n-1})}$ are nontrivial invariant subspaces.

Proposition 1.4: Let $T \in B(H)$ and M be subspace of a Hilbert space H. If M is T –invariant, Then $(T|_M)^* = PT^*|_M$ where P is the orthogonal projection of H onto M.

Proof: Let M be an invariant subspace for T so that $T(M) \subseteq M$, and let P be the orthogonal projection onto M.

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Since P \ v = v for every v \in M and using the fact that P is self-adjoint, we have \langle (T|_M)^* u, v \rangle = \langle u, T|_M v \rangle = \langle u, Tv \rangle = \langle u, TPv \rangle = \langle PT^* u, v \rangle = \langle PT^*|_M u, v \rangle forevery u, v \in M, hence (T|_M)^* = PT^*|_M.
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Proposition 1.5: Let $T, S \in B(H)$ and M be a nontrivial invariant subspace for both T and S. Then M is TS — invariant.

Proof: If *M* is invariant for both *T* and *S* then we have $T(M) \subseteq M$ and $S(M) \subseteq M$. Thus we have $TSM = T(SM) \subseteq T(M) \subseteq M$. Therefore *M* is TS – invariant.

Proposition 1.6: Let $T, S \in B(H)$ and M be a nontrivial invariant subspace for both T and S. Then M is ST –invariant

Proof: If *M* is invariant for both *T* and *S*, then we have $T(M) \subseteq M$ and $S(M) \subseteq M$. Thus we have $STM = S(TM) \subseteq S(M) \subseteq M$. Therefore *M* is ST — invariant.

Question: If M is TS —invariant, is it true that M is T —invariant or S — invariant?

Answer: We answer this question with the following example.

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Let TS = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}. We observe that Lat(TS) = \left\{ \{0\}, \begin{bmatrix} 1 \\ 0 \end{bmatrix}, R^2 \right\}. However TS can be written, not uniquely, as a product of T = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} and S = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}. We notice that M = span\begin{bmatrix} 1 \\ 0 \end{bmatrix} is invariant for TS but it is not invariant for T and S. This leads to the following remarks:
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Remark 1.2: Let M be subspace of a Hilbert space H and $T, S \in B(H)$. If M is TS – invariant, then M is not necessarily T – or S –invariant.

However if TS, T and S have the same structure, then if M is TS — invariant the M is also invariant for both T and S.

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