



ALEKSANDROV-URYSON G_δ COMPACTNESS CRITERION IN MAXIMAL CENTERED SYSTEMS

G. Vasuki*, E. Roja and M. K. Uma

Department of Mathematics, Sri Sarada College for Women, Salem - 636 016, Tamil Nadu, India

E-mail: vasukigj@yahoo.in

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ABSTRACT

In this paper the concepts of G_δ -Hausdorff space, G_δ -extremally disconnected spaces, G_δ - θ continuous mappings are introduced. In this connection, G_δ -Hausdorff extension of spaces and the Aleksandrov-Uryson δ -compactness criterion are established.

Keywords: G_δ -Hausdorff space, G_δ -extremally disconnected spaces, G_δ - θ continuous mappings.

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1. INTRODUCTION:

The method of centered systems was introduced and established by S. Illiadis and S. Fomin [1]. In this paper making use of G_δ -sets, we introduce the concept of G_δ -Hausdorff space, G_δ -extremally disconnected spaces, G_δ - θ -continuous mappings, and Aleksandrov-Uryson G_δ -compactness in the centered systems.

2. PRELIMINARIES:

Definition: 2.1 [3] A set $A \subset X$ in a topological space (X, T) is called a G_δ -set if $A = \bigcap_{n=1}^{\infty} A_n$ where each $A_n \in T$. The complement of G_δ -set is called a F_σ set.

Definition: 2.2 For any set A in (X, T) , define the σ -closure of A denoted by $\sigma\text{-cl } A$, to be the intersection of all F_σ -sets containing A .

That is $\sigma\text{-cl } A = \bigcap \{U : U \text{ is a } F_\sigma\text{-set and } U \supseteq A\}$

Definition: 2.3 For any set A in (X, T) , define the σ -interior of A denoted by $\sigma\text{-int } A$, to be the union of all G_δ -sets contained in A .

That is $\sigma\text{-int } A = \bigcup \{U : U \text{ is a } G_\delta\text{-set and } U \subseteq A\}$

Definition: 2.4 [2] A topological space is a Hausdorff space iff whenever x and y are distinct points of the space there exists disjoint neighbourhoods of x and y .

Definition: 2.5 [1] Let R be a Hausdorff space. A system $p = \{U_\alpha\}$ of open sets of R is called centered if any finite collection of sets of the system has a non-empty intersection. The system p is called a maximal centered system or briefly an end if it cannot be included in any larger centered system of open sets.

Definition: 2.6 [1] Let f be a mapping of a space X into a space Y with $f(x) = y$. The f is called θ -continuous at x if for every neighbourhood O_y of y there exists neighbourhood O_x of x such that $f(\overline{O_x}) \subset \overline{O_y}$. The mapping is called

θ - continuous if it is θ -continuous at every point of X . A mapping that is one-to-one and θ -continuous in both directions is called a θ -homeomorphism.

***Corresponding author: G. Vasuki*, *E-mail: vasukigj@yahoo.in**

It is clear that a continuous mapping is θ -continuous. An example of a θ -continuous mapping that is not continuous. Let I be the interval $[0, 1]$ with the usual topology, and I' the same interval with the following topology: the neighbourhoods of every point $x \neq 0$ are the same as those in the half-open interval $(0, 1]$, but the neighbourhoods of $x = 0$ are the sets of the form $[0, \epsilon) \setminus D$, where D is the set of all points $1/n$ ($n=1, 2, \dots; 0 < \epsilon < 1$). It is easy to see that the space obtained is not regular at 0. Let f be the identity mapping of $[0, 1]$ onto itself. It is easy to verify that this mapping of I onto I' is θ -continuous, we have also obtained a θ -homeomorphism that is not a homeomorphism. It is essential here that the space I' is not regular, since it is easy to show that if the image is regular, then a θ -continuous mapping is automatically continuous.

Remark: 2.1 The canonical open sets (sets of the form $I(\bar{U})$ where U is open) form a base.

3. THE SPACES OF MAXIMAL CENTERED SYSTEM:

Definition: 3.1 A topological space (X, T) is said to be G_δ -Hausdorff iff for any two distinct points $x_1, x_2 \in X$, there exist G_δ sets U and V with $x_1 \in U$ and $x_2 \in V$ such that $U \cap V = \emptyset$.

Notation: 3.1 G_δ -Hausdorff space is denoted by R .

Definition: 3.2 Let R be a G_δ -Hausdorff space. A system $p^* = \{S_\alpha\}$ of G_δ sets of R is called centered if any finite collection of sets of the system has a non-empty intersection. The system p^* is called a maximal centered system, or briefly, an end if it cannot be included in any larger centered system of G_δ sets.

The following are the properties of maximal centered systems:

1. If $S_i \in p^*$ ($i = 1, 2, \dots, n$) then $\bigcap_{i=1}^n S_i \in p^*$.
2. If $S \subset H$, $S \in p^*$ and H is G_δ -set then $H \in p^*$.
3. If H is G_δ -set, then $H \notin p^*$, iff there exists $S \in p^*$ such that $S \cap H$ is empty.
4. If $S_1 \cup S_2 = S_3 \in p^*$, S_1 and S_2 are G_δ -sets and $S_1 \cap S_2 = \emptyset$, then either $S_1 \in p^*$ or $S_2 \in p^*$.
5. If $\sigma\text{-cl}(S) = R$, then $S \in p^*$ for any end p^* .

Remark: 2.1 Every centered system of G_δ -sets can be extended in atleast one way to a maximal one.

4. MAXIMAL STRUCTURE IN $\theta(R)$:

Definition: 4.1 A set U in a topological space (X, T) is a G_δ -neighbourhood of a point x iff U contains a G_δ -set to which x belongs.

Definition: 4.2 A family \mathcal{A} is a G_δ -cover of a G_δ -set B iff each member of B belongs to some member of \mathcal{A} .

Definition: 4.3 A topological space is G_δ -compact iff each G_δ -cover has a finite subcover.

Notation: 4.1 Let $\theta(R)$ denote the collection of all end belonging to a given space R . We introduce maximal structure $\theta(R)$ in the following way:

Let O_S be the set of all ends that contain S as an element, where S is a G_δ -set of R . Now O_S is to be a G_δ -neighbourhood of each end contained in O_S . Thus to each G_δ -set $S \subset R$ there corresponds a G_δ -neighbourhood O_S in $\theta(R)$.

Proposition: 4.1 If S and T are two G_δ -sets, then

- (a) $O_{S \cup T} = O_S \cup O_T$
- (b) $O_S = \theta(R) \setminus O_{R \setminus \sigma\text{-cl}(S)}$

Proof: (a) Let $p^* \in O_S$, ie., $S \in p^*$. Then by property (2), $S \cup T \in p^*$,

ie., $p^* \in O_{S \cup T}$. Hence $O_S \cup O_T \subset O_{S \cup T}$. Now, let $p^* \in O_{S \cup T}$, ie., $S \cup T \in p^*$. If $p^* \notin O_S$, ie., $S \notin p^*$, then $R \setminus \sigma\text{-cl}(S) \in p^*$ and hence, $(R \setminus \sigma\text{-cl}(S)) \cap (S \cup T) \in p^*$. But $(R \setminus \sigma\text{-cl}(S)) \cap (S \cup T) \subset T$. Hence $T \in p^*$, that is, $p^* \in O_T$. Thus $O_{S \cup T} \subset O_S \cup O_T$. Hence, $O_{S \cup T} = O_S \cup O_T$.

(b) put $T = R \setminus \sigma\text{-cl}(S)$ in (a) then we have $O_{S \cup R \setminus \sigma\text{-cl}(S)} = O_S \cup O_{R \setminus \sigma\text{-cl}(S)}$. By using, $O_{S \cup R \setminus \sigma\text{-cl}(S)} = \theta(R)$. We have $\theta(R) = O_S \cup O_{R \setminus \sigma\text{-cl}(S)}$.
Hence $O_S = \theta(R) \setminus O_{R \setminus \sigma\text{-cl}(S)}$.

Notation: 4.2 $G_\delta F_\sigma$ denote a set which is both G_δ and F_σ

Definition: 4.4 A topological space (X, T) is said to be zero dimensional if X has a base of G_δ -neighbourhoods that are both G_δ and F_σ .

Definition: 4.6 A topological space is a G_δ - T_1 space if for given any two distinct points a and b of X , each has a G_δ -neighbourhood not containing the other.

Proposition: 4.2 The maximal structure $\theta(R)$ described above is a G_δ -compact, G_δ -Hausdorff space and has a base of G_δ -neighbourhoods that are $G_\delta F_\sigma$.

Proof: Each set O_S is G_δ - by definition and by equation (b), of Proposition 4.1 it is also F_σ . Thus $\theta(R)$ has a base of G_δ -neighbourhoods that are $G_\delta F_\sigma$, that is, $\theta(R)$ is zero dimensional. Since $\theta(R)$ has a base of G_δ -neighbourhoods that are $G_\delta F_\sigma$ and G_δ - T_1 space it follows that it is G_δ -Hausdorff. Finally to prove that $\theta(R)$ is G_δ -compact. Suppose that there is a G_δ -covering of $\theta(R)$. By replacing each element of the covering by the union of the appropriate sets O_S , we

may assume that the covering has the form $\left(O_{S_\alpha} \right)$. If it is impossible to take a finite subcovering from this G_δ -

covering, then no set of the form $R \setminus \bigcup_{i=1}^n \sigma\text{-cl} \left(S_{\alpha_i} \right)$ is empty. Since otherwise the G_δ -sets $O_{S_{\alpha_i}}$ would form a

finite G_δ -covering of $\theta(R)$. Hence the G_δ -sets $R \setminus \bigcup_{i=1}^n \sigma\text{-cl} \left(S_{\alpha_i} \right)$ form a centered system. It may be extended to a

maximal system p^* . This maximal system is not contained in any O_{S_α} , since it contains, in particular all the $R \setminus \sigma\text{-cl}$

(S_α) . This contradiction proves that $\theta(R)$ is G_δ -compact. Thus with each G_δ -Hausdorff space R we have associated a G_δ -Hausdorff space $\theta(R)$ -the space of maximal centered systems of G_δ -sets.

5. G_δ -EXTREMALLY DISCONNECTED SPACES:

Definition: 5.1 A G_δ -Hausdorff space R is called G_δ -extremally disconnected if the σ -closure of any G_δ -set is G_δ . It is clear that a space is G_δ -extremally disconnected iff two disjoint G_δ -sets have disjoint σ -closures.

Proposition: 5.1 An everywhere G_δ -dense subset R' of G_δ -extremally disconnected space R is itself G_δ -extremally disconnected.

Proof: We prove this by contradiction. Suppose that there exists two G_δ -sets S_1 and S_2 in R' such that $S_1 \cap S_2 = \emptyset$. But $\sigma\text{-cl}(S_1) \cap \sigma\text{-cl}(S_2) \neq \emptyset$. Let T_1 and T_2 be any two G_δ -sets in R such that $T_1 \cap R' = S_1$ and $T_2 \cap R' = S_2$. Then $T_1 \cap T_2 = \emptyset$ for if $T \subset T_1 \cap T_2$, then $T \cap R' \neq \emptyset$ and T is contained in $S_1 \cap S_2$ which is impossible. On the otherhand, $\sigma\text{-cl}(T_1) \cap \sigma\text{-cl}(T_2) \supset \sigma\text{-cl}(S_1) \cap \sigma\text{-cl}(S_2) \neq \emptyset$, contradicting the fact that R is G_δ -extremally disconnected. Hence the Lemma.

Proposition: 5.2 The space $\theta(R)$ of maximal centered systems of an arbitrary G_δ -Hausdorff space R is G_δ -extremally disconnected.

Proof: The proof of this theorem follows from the following equation: $O_{\bigcup_\alpha S_\alpha} = \sigma\text{-cl} \left(\bigcup_\alpha O_{S_\alpha} \right)$. To verify this, if

$S \subset T$, it follows that $O_S \subset O_T$ and therefore $\bigcup_{\alpha} O_{S_{\alpha}} \subset O_{\bigcup_{\alpha} S_{\alpha}}$, and since $O_{\bigcup_{\alpha} S_{\alpha}}$ is F_σ , $\sigma\text{-cl} \left(\bigcup_{\alpha} O_{S_{\alpha}} \right) \subset O_{\bigcup_{\alpha} S_{\alpha}}$.

To prove the opposite inclusion, let q be an arbitrary element of $O_{\bigcup_{\alpha} S_{\alpha}}$, i.e., $\bigcup_{\alpha} S_{\alpha} \in q$ and let S be an arbitrary G_δ -

set of q . Then $S \cap \bigcup_{\alpha} S_{\alpha} \neq \emptyset$, and hence there exists α such that $S \cap S_{\alpha} \neq \emptyset$. But then $O_S \cap O_{S_{\alpha}} \neq \emptyset$, and since $S \in q$

is arbitrary, This means that $q \in \sigma\text{-cl} \left(\bigcup_{\alpha} O_{S_{\alpha}} \right)$. That is, $O_{\bigcup_{\alpha} S_{\alpha}} \subset \sigma\text{-cl} \left(\bigcup_{\alpha} O_{S_{\alpha}} \right)$. Hence $O_{\bigcup_{\alpha} S_{\alpha}} = \sigma\text{-cl} \left(\bigcup_{\alpha} O_{S_{\alpha}} \right)$.

Hence the theorem.

Proposition: 5.3 The equation $R = \theta(R)$ holds iff R is a G_δ -compact, G_δ -extremally disconnected and G_δ -Hausdorff space.

Proof: The necessary condition follows from Proposition 5.1 and Proposition 5.2. To prove sufficiency, let R satisfy the condition of the theorem. Now, we construct a homeomorphism π of $\theta(R)$ onto R . Let $p = \{ S_{\alpha} \} \in \theta(R)$. Then the system of F_σ -sets $\sigma\text{-cl} \{ S_{\alpha} \}$ is centered and has a non-empty intersection. This intersection consists of a single point.

For suppose that there are two distinct points r_1 and r_2 in $\bigcap \sigma\text{-cl} (S_{\alpha})$. Let O_{r_1} and O_{r_2} be two disjoint G_δ -

neighbourhoods of these points. Since $O_{r_1} \cap S_{\alpha} \neq \emptyset$ and $O_{r_2} \cap S_{\alpha} \neq \emptyset$ for all $S_{\alpha} \in p$, which gives that

$O_{r_1} \in p$ and $O_{r_2} \in p$ which is impossible. Thus $\bigcap \sigma\text{-cl} (S_{\alpha})$ consists of a single point r . Let $\pi(p) = r$. We shall prove

that the mapping π is one-one and continuous. Since $\theta(R)$ is G_δ -compact, this will prove the theorem. The mapping is onto. For let $r \in R$ and let $\{V_{\alpha}\}$ be the system of all G_δ -neighbourhoods of r in R . This system can be extended uniquely to a maximal one. For, if $\{V_{\alpha}\}$ is contained in two different maximal systems then there would be two G_δ -sets S_1 and S_2 in R such that $S_1 \cap S_2 = \emptyset$, each of them would intersect every V_{α} , that is, $r \in ((\sigma\text{-cl}(S_1)) \cap (\sigma\text{-cl}(S_2)))$

but which contradicts the fact that R is extremally G_δ -disconnected. Extending the system $\{V_{\alpha}\}$ to a maximal one, there is a point $p = \{S_{\alpha}\}$ in $\theta(R)$. But $\pi(p) = r$. Already we have proved that π is one-one. Hence from the definition of π it follows that $\pi(O_S) = \sigma\text{-cl}(S)$.

Let O_r' be any G_δ -neighbourhood of r . Let S be a G_δ -neighbourhood such that $\sigma\text{-cl}(S) \subset O_r'$. Then O_S is a G_δ F_σ neighbourhood of p such that $\pi(O_S) \subset \sigma\text{-cl}(S) \subset O_r'$. Thus π is continuous and hence the proof.

6. G_δ - θ CONTINUOUS MAPPINGS:

Definition: 6.1 Let f be a mapping of a space X into a space Y with $f(x) = y$. Then f is called G_δ - θ continuous at x iff for every G_δ -neighbourhood O_y of y there exists a G_δ -neighbourhood O_x of x such that $f(\sigma\text{-cl}(O_x)) \subset \sigma\text{-cl}(O_y)$. The mapping is called G_δ - θ continuous if it is G_δ - θ continuous at every point of X . A mapping that is one-one and G_δ - θ continuous in both directions is called a G_δ - θ homeomorphism. It is clear that a continuous mapping is G_δ - θ continuous.

The Realization of R in $\theta(R)$:

Consider a G_δ -Hausdorff space R and its space $\theta(R)$. Let $r \in R$ and $x(r)$ denote the set of all ends p^* of R that contain all the G_δ -neighbourhoods of r . Now, the set $x(r)$ is G_δ F_σ in $\theta(R)$. Since $\theta(R)$ is G_δ -compact, $x(r)$ is G_δ -compact.

Now define a space R^* constructed as follows: Its points are the F_σ -sets $x(r)$ and its structure is defined as, let V be a G_δ -set of $\theta(R)$. Let V^* denote the set of all F_σ -sets $x(r)$ that are completely contained in V . By definition, the set of all V^* is to form a base of R^* .

Definition: 6.2 A topological space is G_δ -regular iff for each point x and each G_δ -neighbourhood U and x there is a F_σ -neighbourhood V of x such that $V \subset U$.

Definition: 6.3 If there exists a G_δ - θ homeomorphism of one space onto another, the two spaces are said to be G_δ - θ -homeomorphic.

Proposition: 6.1 R^* is G_δ - θ homeomorphic to R . If R is G_δ -regular, then R^* is homeomorphic to R .

Proof: Let π be the mapping of R^* onto R in which $\pi(x(r)) = r$. We shall show that π is the required G_δ - θ homeomorphism. To prove this the equivalence of the following inclusions are established.

Now, $x(r) \subset O_H = O_{\sigma\text{-int}(\sigma\text{-cl}(H))}$ and $r \in \sigma\text{-int}(\sigma\text{-cl}(H))$.

If $r \in \sigma\text{-int}(\sigma\text{-cl}(H))$, it is clear that $x(r) \subset O_H$. If $x(r) \subset O_{\sigma\text{-int}(\sigma\text{-cl}(H))}$, but $r \notin O_{\sigma\text{-int}(\sigma\text{-cl}(H))}$ then there would be end p^* in $x(r)$ not containing $\sigma\text{-int}(\sigma\text{-cl}(H))$. But then $p^* \notin O_{\sigma\text{-int}(\sigma\text{-cl}(H))}$, which is impossible. From this equivalence it follows that π^{-1} is continuous. For let V^* be a G_δ -neighbourhood of the set $x(r)$ in R^* . Since $x(r)$ is G_δ -compact, assume that V has the form O_H where H is G_δ -in R . Then $\pi^{-1}(\sigma\text{-int}(\sigma\text{-cl}(H))) \subset O_H = V^*$. This proves the continuity of π^{-1} . To prove that π is G_δ - θ continuous, it is easy to see that if $x(r') \cap O_H \neq \emptyset$, then $r' \in \sigma\text{-cl}(H)$. From the construction of V^* , it is clear that if $x(r') \in (\sigma\text{-cl}(V^*)) = \sigma\text{-cl}(O_H)$ then $x(r') \cap O_H \neq \emptyset$. Let H be an arbitrary G_δ -neighbourhood of r , and let $V = O_H$. Then $\pi(\sigma\text{-cl}(V^*)) \subset \sigma\text{-cl}(H)$, which proves that π is G_δ - θ continuous, since V^* is a G_δ -neighbourhood of $x(r)$ in R^* . Thus the spaces R^* and R are G_δ - θ homeomorphic. If R is G_δ -regular, then π is G_δ - θ continuous and so π a homeomorphism. Hence the lemma.

The absolute $\omega^*(R)$ of a space R :

In $\omega^*(R)$ each point $r \in R$ is represented by ends containing all G_δ -neighbourhoods of R . It is obvious that

$\omega^*(R) = \bigcup_{r \in R} x(r)$ where $x(r)$ are the sets defined above. The subset $\omega^*(R)$ is mapped in a natural way onto R .

If $p \in \omega^*(R)$, then by definition $\pi_R(p) = r$, where r is the point whose G_δ -neighbourhoods all belong to p . π_R is called the natural mapping of $\omega^*(R)$ onto R .

Proposition: 6.2 $\omega^*(R)$ is everywhere G_δ -dense in $\theta(R)$.

Proof: Let p be an arbitrary end of R and O_U be a G_δ -neighbourhood of it. Then O_U contains the sets $x(r)$ corresponding to any point $r \in U$ and so has a non-empty intersection with $\omega^*(R)$,

Proposition: 6.3 $\omega^*(R)$ is G_δ -extremally disconnected.

Proof: From Proposition 6.2 $\omega^*(R)$ is everywhere G_δ -dense in $\theta(R)$. And also from Proposition 5.1 and Proposition 5.2, $\omega^*(R)$ is G_δ -extremally disconnected.

Proposition: 6.4 $\omega^*(R)$ is G_δ - θ homeomorphic to R iff R is G_δ -extremally disconnected.

Proof: Let $\omega^*(R)$ be G_δ - θ homeomorphic to R and from Proposition 6.3, $\omega^*(R)$ is G_δ -extremally disconnected. Now to prove the sufficiency, let $\{U_\alpha(r)\}$ be the collection of all G_δ -sets in R containing r . The system $\{U_\alpha(r)\}$ can be extended to a maximal one in a unique way, for otherwise there exist G_δ -disjoint sets G_1 and G_2 meeting $U_\alpha(r)$, that is, $r \in (\sigma\text{-cl}(G_1)) \cap (\sigma\text{-cl}(G_2)) \neq \emptyset$, which is impossible for G_δ -extremally disconnected space. Thus, for each point $r \in R$ the set $x(r)$ consists of a single point. But then the space R constructed above coincides with $\omega^*(R)$. Hence R is G_δ - θ homeomorphic to $\omega^*(R)$.

Proposition: 6.5 If R is a G_δ -regular, G_δ -extremally disconnected space, then R is a G_δ -homeomorphic to $\omega^*(R)$.

Proof: From Proposition 6.1, if R is a G_δ -regular, G_δ -extremally disconnected space, then it is G_δ -homeomorphic to R and hence to $\omega^*(R)$.

7. G_δ -HAUSDORFF EXTENSION OF SPACES:

Definition: 7.1A G_δ -Hausdorff space $\delta(R)$ is called an extension of G_δ -Hausdorff space R if R is contained in $\delta(R)$ as an everywhere G_δ -dense subset. R is called G_δ -H closed if every extension $\delta(R)$ coincides with R itself. An extension $\delta(R)$ is called G_δ -H-closed if $\delta(R)$ is G_δ -H-closed and G_δ -compact if $\delta(R)$ is G_δ -compact.

Proposition: 7.1 The space R is G_δ -H-closed if and only if any centered system $\{U_\alpha\}$ of G_δ -sets of R satisfies the condition $\bigcap_\alpha \sigma - \text{cl} (U_\alpha) \neq \emptyset$.

Proof: Necessary: If $p = \{U_\alpha\}$ were a centered system with $\bigcap \sigma - \text{cl} (U_\alpha) = \emptyset$, then we would construct the extension $\delta(R)$ which does not coincide with R itself. The points of $\sigma(R)$ are those of R and a new point p . The G_δ -neighbourhoods of each point $r \in R$ in $\delta(R)$ are the same as in R . Any set U_α together with the point p is a G_δ -neighbourhood of p . Because of the condition $\bigcap \sigma - \text{cl} (U_\alpha) = \emptyset$, the space $\delta(R)$ is G_δ -Hausdorff and because $\{U_\alpha\}$ is a centered system, it contains R as an everywhere G_δ -dense subset, that is, R is not G_δ -H closed.

Sufficiency: Let R be a proper everywhere G_δ -dense subset of $\delta(R)$. Consider in $\delta(R)$ all the G_δ -neighbourhoods of some point $p \in \delta(R)/R$. Let this be the system $\{U_\alpha\}$. This is centered, for otherwise p would be an isolated point in $\delta(R)$ and R would not be everywhere G_δ -dense in $\delta(R)$. Since $\delta(R)$ is a G_δ -Hausdorff, we have $\bigcap \sigma - \text{cl} (U_\alpha) = p$. But then the system $\{V_\alpha = U_\alpha \cap R\}$ is centered and $\bigcap \sigma - \text{cl} (V_\alpha) = \emptyset$, which contradicts the condition of the lemma.

8. THE ALEKSANDROV – URYSON G_δ -COMPACTNESS CRITERION:

Let R be a G_δ -Hausdorff space, $\omega^*(R)$ its absolute and π_R the natural mapping of $\omega^*(R)$ onto R . Also Let F be any subset of R^* . We associate it with a certain subset \tilde{F} of $\omega^*(R)$, defined by saying that the point $p \in \pi_R^{-1}(x)$, $x \in R$, belongs to \tilde{F} if $p \in O_U$ for every U satisfying the condition $x \in \sigma - \text{int} (\sigma - \text{cl}(U \cap F))$. By construction, \tilde{F} is contained in the complete inverse image $\pi_R^{-1}(F)$ of F in $\omega^*(R)$. Then we call \tilde{F} the G_δ -reduced inverse image of F in $\omega(R)$.

Proposition: 8.1 (Aleksandrov-Uryson G_δ -compactness) A G_δ -Hausdorff space R is G_δ -compact iff each of its F_σ -subsets is G_δ -H closed.

Proof: Since in a G_δ -compact space every F_σ -subset is G_δ -compact and hence G_δ -H closed. The proof of sufficiency, based on the following properties of G_δ -reduced inverse images.

Property: I If $F_1 \subset F_2 \subset \dots \subset F_n = R$, with F_1 non-empty, then $\bigcap_{i=1}^n \tilde{F}_i \neq \emptyset$.

Let $x \in F_1^*$ and let $q' = \{G^1\}$ be a end of F_1 containing a centered system of G_δ -sets G^1 in F such that $x \in \sigma - \text{int} (\sigma - \text{cl}(G^1))$. Assume that we have constructed systems $q^i = \{G^i\}$ of F_i such that q^i contains all the G_δ -sets $G^i \subset F_i$ for which $x \in \sigma - \text{int} (\sigma - \text{cl}(G^i))$ and all the sets whose intersection with F_{i-1} is some G^{i-1} . By definition q^{i+1} is to consist of all sets $G^{i+1} \subset F_{i+1}$ for which $x \in \sigma - \text{int} (\sigma - \text{cl} (G^{i+1}))$ and of all sets whose intersection with F_i is some G^i . Clearly q^{i+1} is a centered system. Thus, for each i , we construct a centred system q^i . Let $p = \{H\}$ denote the end of R containing q^n . We have to prove that $p \in \bigcap_{i=1}^n \tilde{F}_i$. It follows from the construction of p , that if we have $H \cap F_i \in q^i$ for some i and some G_δ -set H in R , then $H \in p$. We prove that $p \in \tilde{F}_1$. Let H be a G_δ -set of R such that $x \in \sigma - \text{int} (\sigma - \text{cl} (H \cap F_1))$. Then $H \cap F_1 \in q^1$ and hence $H \in p$, that is, $p \in \tilde{F}_1$ which proves property I.

Remark: 8.1 If O_H is a G_δ -neighbourhood of $\pi_R^{-1}(x) \cap \sigma - \text{cl} F$, where H is the largest of the G_δ -sets H' with the property $O_{H'} = O_H$ then $x \in \sigma - \text{int} (\sigma - \text{cl} (H \cap F))$. For, otherwise $R \setminus \sigma - \text{cl} (H) = V \neq \emptyset$, with $x \in \sigma - \text{cl} (V \cap F)$. If some set G , G_δ in R , has the property $x \in \sigma - \text{int} (\sigma - \text{cl} (G \cap F))$, then $V \cap G$ is non-empty. Hence we may consider system q consisting of all G_δ -neighbourhoods. But, on the otherhand, since $p \in O_V$ and $O_V \cap O_H = \emptyset$ since $V \cap H = \emptyset$, then $p \in \tilde{F} \subset O_H$, which is a contradiction. Hence $x \in \sigma - \text{int} (\sigma - \text{cl} (H \cap F))$.

We now prove that $\pi_R^{-1}(x) \cap \tilde{F}$ is G_δ -compact. Let q be the system of all the G_δ -sets G in R such that $x \in \sigma\text{-int}(\sigma\text{-cl}(G \cap F))$ and all the G_δ -neighbourhoods of x in r . It is clear that $\pi_R^{-1}(x) \cap \tilde{F}$, consists of all ends p^* containing q . If p' is an end belonging to $\pi_R^{-1}(x)$ and such that any of its G_δ -neighbourhoods O_H contains some point $p \in \pi_R^{-1}(x) \cap \tilde{F}$ then any $H \in p'$ meets an arbitrary element of q , and hence $p' \in \pi_R^{-1}(x) \cap \tilde{F}$, that is the latter set F_σ in $\pi_R^{-1}(x)$ and so is G_δ -compact.

Property: II If F is G_δ -H closed, then \tilde{F} is G_δ -compact.

Proof: Let $\{H_\alpha\}$ be any G_δ -covering of \tilde{F} by G_δ -sets in \tilde{F} . They may be extended to G_δ -sets in $\omega^*(R)$. Assume that each of the extended sets has the form O_U , where U is a G_δ -set in R . Otherwise $\{H_\alpha\}$ may be replaced by a finer G_δ -covering for which this condition holds. So we may assume that $\{H_\alpha\}$ is a G_δ -covering of F by G_δ -sets in $\omega^*(R)$ of the form O_{U_α} , where U_α is G_δ -in R . Let $x \in F$. Let H_β^x denote the union of a finite number of sets H_α G_δ -covering the

G_δ -compact set $\pi_R^{-1}(x)$. Clearly H_β^x has the form $O_{U_\beta^x}$, where U_β^x is G_δ -set in R and is maximal among the sets H

for which $O_H = O_{U_\beta^x}$. Hence it follows that the system $\sigma\text{-int} \{ \bigcup_\beta U_\beta^x \cap F \}$ is a G_δ -covering of F .

Since F is G_δ -H closed, choose a finite number of elements of this G_δ -covering such that $\bigcup_{i=1}^n \sigma\text{-cl}(\sigma\text{-int}(\sigma\text{-cl}(\bigcup_{\beta_i} U_{\beta_i}^x \cap F))) = F$. We prove that $\bigcup_{i=1}^n O_{U_{\beta_i}^x} \supset \tilde{F}$. Since the union $\bigcup_{i=1}^n U_{\beta_i}^x = U$ has the property that $x \in \sigma\text{-int}(\sigma\text{-cl}(F \cap U))$ for any x , then an arbitrary end $p^* \in \tilde{F}$ contains U , and hence belongs to some $O_{U_\beta^x}$. Thus, if

we choose only those H_α that make $O_{U_{\beta_i}^x}$ and take their intersections with \tilde{F} , we obtain the required finite covering. Hence property II.

Proposition: 8.2 The G_δ -Hausdorff space R is G_δ -compact iff every well-ordered decreasing sequence of non-empty F_σ -sets has a non-empty intersection.

Proof: Suppose that the conditions of the theorem are satisfied and that $\{F_\alpha\}$ is a well-ordered decreasing system of F_σ -sets of R . Then by property I, the G_δ -set \tilde{F} form a centered system in $\omega^*(R)$. Also since all the F_α are G_δ -H closed, by property II, \tilde{F} are G_δ -compact. Hence $\bigcap_\alpha \tilde{F}_\alpha \neq \emptyset$. Let $y \in \tilde{F}_\alpha$. Then $\pi_R(y) \in F_\alpha$ for every α , that is $\bigcap_\alpha F_\alpha \neq \emptyset$.

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