

On Contra $b\hat{g}$ – Continuous functions in Topological Spaces

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ABSTRACT

In this paper we introduce a new class of weaker form of continuous function called Contra $b\hat{g}$ -continuous function. Some characterization and several properties concerning Contra $b\hat{g}$ -continuity are obtained.

Keywords: $b\hat{g}$ – Closed sets, $b\hat{g}$ -continuous, Contra $b\hat{g}$ -continuous, Contra $b\hat{g}$ -irresolute.

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1. INTRODUCTION

Levine [4] introduced generalized closed sets in topological spaces. Veerakumar [2] introduced \hat{g} -closed sets in topological spaces. Andrijevic[1] introduced a new class of generalized open sets called b -open sets. R. Subasree and M.Maria Singam [3] introduced $b\hat{g}$ -closed sets in topological spaces.

Dontchev[6] introduced and investigated a new notion of continuity called Contra continuity. The purpose of this paper is to introduce and investigate some of the properties of contra $b\hat{g}$ –continuous functions, contra $b\hat{g}$ –irresolute functions and we obtain some of its characterization.

2. PRELIMINARIES

Throughout this paper (X, τ) (or simply X) represents topological spaces on which no separation axioms are assumed unless otherwise mentioned. For a subset A of X , $cl(A)$, $Int(A)$ and A^c denote the closure of A , interior of A and the complement of A respectively. Let us recall the following definitions.

Definition 2.1: A subset A of a space (X, τ) is called a

- i) Semi-open set [6] if $A \subseteq cl[Int(A)]$
- ii) α -open set[9] if $A \subseteq Int[cl(Int(A))]$
- iii) b -open set[7] if $A \subseteq cl[Int(A)] \cup Int[cl(A)]$

The complement of a semi-open (resp. α -open, b -open) set is called semi-closed (resp. α -closed, b -closed) set.

The intersection of all semi-closed (resp. α -closed, b -closed) sets of X containing A is called the semi-closure (resp. α -closure, b -closure) and is denoted by $scl(A)$ (resp. $\alpha cl(A)$, $bcl(A)$). The family of all semi-open (resp. α -open, b -open) subsets of a space X is denoted by $SO(X)$ (resp. $\alpha O(X)$, $bO(X)$).

Definition 2.2: A subset A of a topological space (X, τ) is called

- i) generalized closed(briefly g -closed) set[4] if $cl(A) \subseteq U$ whenever $A \subseteq U$ and U is open set in (X, τ) .
- ii) \hat{g} -closed set[2] if $cl(A) \subseteq U$ whenever $A \subseteq U$ and U is a semi-open set in (X, τ) .
- iii) $b\hat{g}$ -closed set[3] if $bcl(A) \subseteq U$ whenever $A \subseteq U$ and U is \hat{g} -open set in (X, τ) .

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The complement of a g -closed (resp. \hat{g} -closed and $b\hat{g}$ -closed) set is called g -open (resp. \hat{g} -open and $b\hat{g}$ -open) set .

Definition 2.3: A space (X, τ) is called a $Tb\hat{g}$ – space [3] if every $b\hat{g}$ – closed set in it is b -closed.

Definition 2.4: A function $f: (X, \tau) \longrightarrow (Y, \sigma)$ is called

- i) $b\hat{g}$ – continuous [5] map if $f^{-1}(V)$ is $b\hat{g}$ -closed in (X, τ) for every closed set V in (Y, σ) .
- ii) $b\hat{g}$ – irresolute [5] map if $f^{-1}(V)$ is $b\hat{g}$ -closed in (X, τ) for every $b\hat{g}$ – closed set V in (Y, σ) .

Definition 2.5: A function $f: (X, \tau) \longrightarrow (Y, \sigma)$ is called

- i) contra continuous[10] map if $f^{-1}(V)$ is closed in (X, τ) for every open set V in (Y, σ) .
- ii) contra semi-continuous[6] map if $f^{-1}(V)$ is semi-closed in (X, τ) for every open set V in (Y, σ) .
- iii) contra α – continuous[9] map if $f^{-1}(V)$ is α -closed in (X, τ) for every open set V in (Y, σ) .
- iv) contra b – continuous[12] map if $f^{-1}(V)$ is b -closed in (X, τ) for every open set V in (Y, σ) .
- v) contra g – continuous[11] map if $f^{-1}(V)$ is g -closed in (X, τ) for every open set V in (Y, σ) .

3. Contra $b\hat{g}$ – Continuous function

Definition 3.1: A function $f: (X, \tau) \longrightarrow (Y, \sigma)$ is called contra $b\hat{g}$ – continuous if $f^{-1}(V)$ is $b\hat{g}$ -closed in (X, τ) for every open set V in (Y, σ) .

Example 3.2: Let $X=Y= \{a, b, c\}$

$\tau = \{X, \Phi, \{a\}, \{b\}, \{a, b\}\}$ and $\sigma = \{Y, \Phi, \{a, b\}, \{c\}\}$

Define a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ by $f(a) = a, f(b) = c, f(c) = b$.

$b\hat{g}\text{-}C(X) = \{X, \Phi, \{a\}, \{b\}, \{c\}, \{a, c\}, \{b, c\}\}$

Here the inverse images of open sets $\{a, b\}$ and $\{c\}$ in Y are $\{a, c\}$ and $\{b\}$ respectively which are $b\hat{g}$ – closed sets in X . Hence f is contra $b\hat{g}$ – continuous.

Theorem 3.3: Every contra continuous function is contra $b\hat{g}$ – continuous.

Proof: Let V be any open set in (Y, σ) . Since f is contra continuous, $f^{-1}(V)$ is closed in (X, τ) . Since from [3] Remark 3.23 “Every closed set is $b\hat{g}$ – Closed”. Then $f^{-1}(V)$ is $b\hat{g}$ – Closed in (X, τ) . Hence f is contra $b\hat{g}$ – continuous.

Remark 3.4: The converse of the above theorem need not be true.

(i.e) Every contra $b\hat{g}$ – continuous function need not be contra continuous as shown in the following example.

Example 3.5: Let $X=Y= \{a, b, c, d\}$

$\tau = \{X, \Phi, \{a\}, \{a, c\}, \{a, b, d\}\}$ and $\sigma = \{Y, \Phi, \{b\}, \{a, b\}, \{b, c, d\}\}$

Define a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ by $f(a) = c, f(b) = b, f(c) = a, f(d) = d$.

$b\hat{g}\text{-}C(X) = \{X, \Phi, \{b\}, \{c\}, \{d\}, \{b, c\}, \{c, d\}, \{b, d\}, \{a, b, c\}, \{a, c, d\}, \{a, b, d\}, \{b, c, d\}\}$

Here the inverse images of open sets $\{b\}, \{a, b\}, \{b, c, d\}$ in (Y, σ) are $\{b\}, \{b, c\}, \{a, b, d\}$ respectively which are $b\hat{g}$ – closed but not closed in (X, τ) . Hence f is contra $b\hat{g}$ – continuous function but not contra continuous.

Theorem 3.6: Every contra g -continuous function is contra $b\hat{g}$ – continuous.

Proof: Let V be any open set in (Y, σ) . Since f is contra g -continuous, $f^{-1}(V)$ is g -closed in (X, τ) . From [3] Proposition 3.6, “Every g -closed set is $b\hat{g}$ -Closed”. Then $f^{-1}(V)$ is $b\hat{g}$ – Closed in (X, τ) . Hence f is contra $b\hat{g}$ -continuous.

Remark 3.7: The converse of the above theorem need not be true.

(i.e) Every contra $b\hat{g}$ – continuous need not be contra g -continuous function as shown in the following example.

Example 3.8: Let $X=Y= \{a, b, c, d\}$

$\tau = \{X, \Phi, \{a\}, \{a, c\}, \{a, b, d\}\}$ and $\sigma = \{Y, \Phi, \{b\}, \{a, b\}, \{b, c, d\}\}$

Define a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ by $f(a) = c, f(b) = b, f(c) = a, f(d) = d$.
 $g-C(X) = \{X, \Phi, \{b\}, \{c\}, \{d\}, \{b, c\}, \{c, d\}, \{b, d\}, \{a, b, c\}, \{a, c, d\}, \{b, c, d\}\}$
 $b\hat{g}-C(X) = \{X, \Phi, \{b\}, \{c\}, \{d\}, \{b, c\}, \{c, d\}, \{b, d\}, \{a, b, c\}, \{a, c, d\}, \{a, b, d\}, \{b, c, d\}\}$

Here the inverse images of open set $\{b, c, d\}$ in (Y, σ) is $\{a, b, d\}$ which is $b\hat{g}$ -closed but not g -closed in (X, τ) . Hence f is contra $b\hat{g}$ – continuous, but not contra g -continuous.

Theorem 3.9: Every contra b -continuous function is contra $b\hat{g}$ – continuous.

Proof: Let V be any open set in (Y, σ) . Since f is contra b -continuous, $f^{-1}(V)$ is b -closed in (X, τ) . Since from [3] Proposition 3.3, “Every b -closed set is $b\hat{g}$ -Closed”. Then $f^{-1}(V)$ is $b\hat{g}$ –Closed in (X, τ) . Hence f is contra $b\hat{g}$ -continuous.

Remark 3.10: The converse of the above theorem need not be true.

(i.e) Every contra $b\hat{g}$ – continuous need not be contra b -continuous map as shown in the following example.

Example 3.11: Let $X=Y=\{a, b, c\}$
 $\tau = \{X, \Phi, \{a\}\}$ and $\sigma = \{Y, \Phi, \{a\}, \{b\}, \{a, b\}, \{a, c\}\}$

Define a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ by $f(a) = c, f(b) = a, f(c) = b$.
 $b\hat{g}-C(X) = \{X, \Phi, \{b\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}\}$
 $b-C(X) = \{X, \Phi, \{b\}, \{c\}, \{b, c\}\}$

Here the inverse image of an open set $\{a, c\}$ in (Y, σ) is $\{a, b\}$ which is $b\hat{g}$ -closed but not b -closed in (X, τ) . Hence f is contra $b\hat{g}$ -continuous, but not contra b -continuous.

Theorem 3.12: Every contra α -continuous function is contra $b\hat{g}$ – continuous.

Proof: Let V be any open set in (Y, σ) . Since f is contra α -continuous, $f^{-1}(V)$ is α -closed in (X, τ) . From [3] Remark 3.23 “Every α -closed set is $b\hat{g}$ – Closed”. Then $f^{-1}(V)$ is $b\hat{g}$ –Closed in (X, τ) . Hence f is contra $b\hat{g}$ -continuous.

Remark 3.13: The converse of the above theorem need not be true.

(i.e) Every contra $b\hat{g}$ – continuous need not be contra α -continuous function as shown in the following example.

Example 3.14: Let $X=Y=\{a, b, c, d\}$
 $\tau = \{X, \Phi, \{a\}, \{b, c\}, \{a, b, c\}\}$ and $\sigma = \{Y, \Phi, \{a\}, \{a, c\}, \{a, b, d\}\}$

Define a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ by $f(a) = b, f(b) = a, f(c) = c, f(d) = d$.
 $\alpha-C(X) = \{X, \Phi, \{d\}, \{a, d\}, \{b, c, d\}\}$
 $b\hat{g}-C(X) = \{X, \Phi, \{a\}, \{b\}, \{c\}, \{d\}, \{b, c\}, \{c, d\}, \{a, d\}, \{b, d\}, \{a, c, d\}, \{a, b, d\}, \{b, c, d\}\}$

Here the inverse images of open sets $\{a\}, \{a, c\}, \{a, b, d\}$ in (Y, σ) are $\{b\}, \{b, c\}, \{a, b, d\}$ respectively which are $b\hat{g}$ – closed but not α -closed in (X, τ) . Hence f is contra $b\hat{g}$ – continuous, but not contra α -continuous.

Theorem 3.15: Every contra semi-continuous function is contra $b\hat{g}$ - continuous.

Proof: Let V be any open set in (Y, σ) . Since f is contra semi-continuous, $f^{-1}(V)$ is semi-closed in (X, τ) . From [3] Remark 3.23 “Every semi-closed set is $b\hat{g}$ -Closed”. Then $f^{-1}(V)$ is $b\hat{g}$ –Closed in (X, τ) . Hence f is contra $b\hat{g}$ -continuous.

Remark 3.16: The converse of the above theorem need not be true.

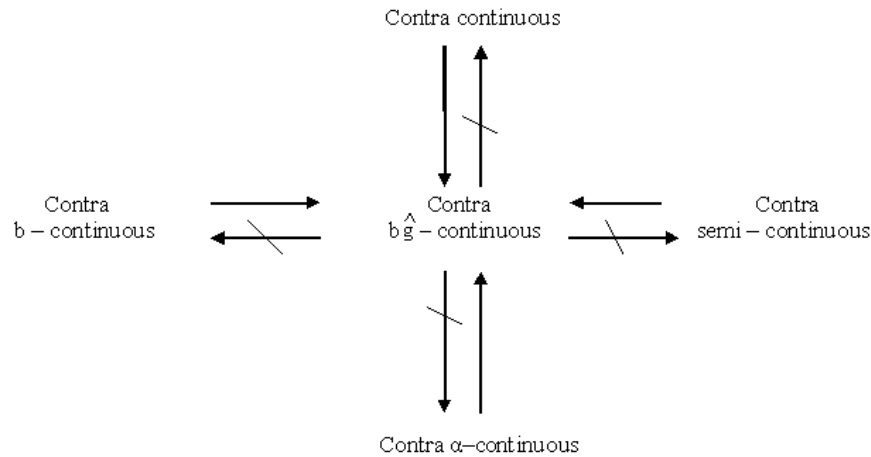
(i.e) Every contra $b\hat{g}$ – continuous need not be contra semi-continuous function as shown in the following example.

Example 3.17: Let $X=Y=\{a, b, c, d\}$
 $\tau = \{X, \Phi, \{b\}, \{a, b\}, \{b, c, d\}\}$ and $\sigma = \{Y, \Phi, \{a\}, \{a, c\}, \{a, b, d\}\}$

Define a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ by $f(a) = a, f(b) = b, f(c) = c, f(d) = d$.
 $\text{semi}-C(X) = \{X, \Phi, \{a\}, \{c\}, \{d\}, \{a, c\}, \{a, d\}, \{c, d\}, \{a, c, d\}\}$
 $b\hat{g}-C(X) = \{X, \Phi, \{a\}, \{c\}, \{d\}, \{a, c\}, \{a, d\}, \{c, d\}, \{a, c, d\}, \{a, b, c\}, \{a, b, d\}\}$

Here the inverse image of an open set $\{a, b, d\}$ in (Y, σ) is $\{a, b, d\}$ which is $b\hat{g}$ – closed but not semi-closed in (X, τ) . Hence f is contra $b\hat{g}$ – continuous, but not contra semi-continuous.

Remark 3.18: From the above discussions and known results, we have the following diagram.



Remark 3.19: The Composition of two contra $b\hat{g}$ – continuous function need not be contra $b\hat{g}$ – continuous.

Example 3.20: Let $X=Y=Z=\{a, b, c, d\}$

$\tau = \{X, \Phi, \{a\}, \{a, c\}, \{a, b, d\}\}$, $\sigma = \{Y, \Phi, \{b\}, \{a, b\}, \{b, c, d\}\}$ and $\eta = \{Z, \Phi, \{a\}, \{b, c\}, \{a, b, c\}\}$

Define a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ by $f(a) = c, f(b) = b, f(c) = a, f(d) = d$ and $g: (Y, \sigma) \longrightarrow (Z, \eta)$ by $g(a) = a, g(b) = d, g(c) = c, g(d) = b$.

Clearly f and g are contra $b\hat{g}$ – continuous. But their composition is not contra $b\hat{g}$ – continuous function, since $(f \circ g)^{-1}$ of an open set $\{b, c\}$ in (Z, η) is $\{a, d\}$ which is not $b\hat{g}$ – closed in (X, τ) . Hence $f \circ g$ is not contra $b\hat{g}$ – continuous.

Theorem 3.21: The following are equivalent for a function $f: (X, \tau) \longrightarrow (Y, \sigma)$

- (a) f is contra $b\hat{g}$ – continuous.
- (b) For every closed subset F of Y , $f^{-1}(F)$ is $b\hat{g}$ – open in X .
- (c) For each $x \in X$ and each closed subset F of Y with $f(x) \in F$, there exists a $b\hat{g}$ – open set U of X with $x \in U$, $f(U) \subseteq F$.

Proof:

(a) \implies (b) Obviously follows from the definition.

(b) \implies (c) Let F be any Closed subset of Y and let $f(x) \in F$ where $x \in X$. Then by (b), $f^{-1}(F)$ is $b\hat{g}$ – open in X . Also $x \in f^{-1}(F)$. Take $U = f^{-1}(F)$. Then U is a $b\hat{g}$ – open set containing x and $f(U) \subseteq F$.

(c) \implies (b) Let F be any Closed subset of Y . If $x \in f^{-1}(F)$ then $f(x) \in F$. By (c), there exists a $b\hat{g}$ – open set U_x of X with $x \in U_x$ such that $f(U_x) \subseteq F$. Then $f^{-1}(F) = \bigcup \{U_x : x \in f^{-1}(F)\}$. Hence $f^{-1}(F)$ is $b\hat{g}$ – open in X .

Theorem 3.22: If a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ is contra $b\hat{g}$ – continuous and X is $Tb\hat{g}$ – space, then f is contra b – continuous.

Proof: Let V be any open set in Y . Since f is contra $b\hat{g}$ – continuous, $f^{-1}(V)$ is $b\hat{g}$ – closed in X . Also since X is $Tb\hat{g}$ – space, $f^{-1}(V)$ is b – closed in X . Hence f is contra b – continuous.

Corollary 3.23: If X is $Tb\hat{g}$ – space, then for the function $f: (X, \tau) \longrightarrow (Y, \sigma)$, the following statements are equivalent.

- i) f is contra b – continuous.
- ii) f is contra $b\hat{g}$ – continuous.

Proof:

(i) \implies (ii) Let V be any open set in Y . Since f is contra b –continuous, $f^{-1}(V)$ is b –closed in X . From [3] proposition 3.3, “Every b –closed is $b\hat{g}$ –closed”. Therefore, $f^{-1}(V)$ is $b\hat{g}$ –closed in X . Hence f is contra $b\hat{g}$ – continuous.

(ii) \implies (i) Let V be any open set in Y . Since f is contra $b\hat{g}$ –continuous, $f^{-1}(V)$ is $b\hat{g}$ –closed in X . Since X is $Tb\hat{g}$ –space, $f^{-1}(V)$ is b –closed in X . Hence f is contra b – continuous.

Theorem 3.24: Let $f: (X, \tau) \longrightarrow (Y, \sigma)$ be a function, then the following statements are equivalent.

1. f is $b\hat{g}$ – continuous.
2. For each point $x \in X$ and each open set of Y with $f(x) \in V$, there exists a $b\hat{g}$ –open set U of X such that $x \in U$, $f(U) \subseteq V$.

Proof:

(i) \implies (ii) Let $f(x) \in V$, then $x \in f^{-1}(V)$. Since f is $b\hat{g}$ – continuous, $f^{-1}(V)$ is $b\hat{g}$ –open in X . Let $U = f^{-1}(V)$, then $x \in U$ and $f(U) \subseteq V$.

(ii) \implies (i) Let V be any open set in Y and $x \in f^{-1}(V)$, then $f(x) \in V$. From (ii), there exists a $b\hat{g}$ – open set U_x of X such that $x \in U_x \subseteq f^{-1}(V)$ and $f^{-1}(V) = \cup \{U_x\}$. Then $f^{-1}(V)$ is $b\hat{g}$ –open in X . Hence f is $b\hat{g}$ – continuous.

Theorem 3.25: If a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ is contra $b\hat{g}$ – continuous and Y is regular, then f is $b\hat{g}$ – continuous.

Proof: Let $x \in X$ and V be an open set in Y with $f(x) \in V$. Since Y is regular, there exists an open set W in Y such that $f(x) \in W$ and $Cl(W) \subseteq V$. Since f is contra $b\hat{g}$ – continuous and $Cl(W)$ is a closed subset of Y with $f(x) \in Cl(W)$. By theorem 3.21, there exists a $b\hat{g}$ –open set U of X with $x \in U$ such that $f(U) \subseteq Cl(W)$. That is $f(U) \subseteq V$. By theorem 3.24, f is $b\hat{g}$ – continuous.

Definition 3.26: A function $f: (X, \tau) \longrightarrow (Y, \sigma)$ is said to be strongly $b\hat{g}$ –continuous if $f^{-1}(V)$ is closed in (X, τ) for every $b\hat{g}$ –closed set V in (Y, σ) .

Definition 3.27: A function $f: (X, \tau) \longrightarrow (Y, \sigma)$ is said to be perfectly $b\hat{g}$ –continuous if $f^{-1}(V)$ is clopen in (X, τ) for every $b\hat{g}$ –closed set V in (Y, σ) .

Definition 3.28: A topological space (X, τ) is said to be $b\hat{g}$ –Hausdorff if for each pair of distinct points x and y in X , there exists $b\hat{g}$ –open subsets U and V of X containing x and y respectively such that $U \cap V = \emptyset$.

Definition 3.29: A topological space (X, τ) is said to be $b\hat{g}$ –ultra Hausdorff if for each pair of distinct points x and y in X , there exists $b\hat{g}$ –clopen subsets U and V of X containing x and y respectively such that $U \cap V = \emptyset$.

Definition 3.30: A space (X, τ) is said to be locally indiscrete if every open subset of X is closed.

Definition 3.31: A Topological space (X, τ) is said to be $b\hat{g}$ –connected if X cannot be written as the disjoint union of nonempty $b\hat{g}$ –open sets.

Definition 3.32: A Topological space (X, τ) is said to be Urysohn space if for each pair of distinct points x and y in X , there exists two open sets U and V in X such that $x \in U$, $y \in V$ and $cl(U) \cap cl(V) = \emptyset$.

Definition 3.33: A Topological space (X, τ) is said to be $Tb\hat{g}^*$ –space if every $b\hat{g}$ –closed set in it is closed.

Example 3.34: Let $X = \{a, b, c\}$
 $\tau = \{X, \Phi, \{a\}, \{b\}, \{a, b\}, \{a, c\}\}$
 $b\hat{g}\text{-}C(X) = \{X, \Phi, \{b\}, \{c\}, \{a, c\}, \{b, c\}\}$
 $C(X) = \{X, \Phi, \{b\}, \{c\}, \{a, c\}, \{b, c\}\}$
 Clearly X is $Tb\hat{g}^*$ –space.

Theorem 3.35: Let $f: (X, \tau) \longrightarrow (Y, \sigma)$ be surjective, closed and contra $b\hat{g}$ –continuous. If X is $Tb\hat{g}^*$ –space, then Y is locally indiscrete.

Proof: Let V be any open set in (Y, σ) . Since f is contra $b\hat{g}$ –continuous, $f^{-1}(V)$ is $b\hat{g}$ –closed in (X, τ) . Also since X is $Tb\hat{g}^*$ –space, $f^{-1}(V)$ is closed in (X, τ) . By hypothesis, f is closed and surjective, $f(f^{-1}(V)) = V$ is closed in Y . Hence Y is locally indiscrete.

Theorem 3.36: If a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ is continuous and (X, τ) is locally indiscrete space, then f is contra $b\hat{g}$ – continuous.

Proof: Let V be any open set in (Y, σ) . Since f is continuous, $f^{-1}(V)$ is open in (X, τ) . Since X is locally indiscrete, $f^{-1}(V)$ is closed in (X, τ) . Now from [3] Remark 3.23, $f^{-1}(V)$ is $b\hat{g}$ –closed in X . Hence f is contra $b\hat{g}$ –continuous.

Theorem 3.37: If a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ is contra $b\hat{g}$ –continuous, injective and Y is $b\hat{g}$ –ultra Hausdorff, then the topological space X is $b\hat{g}$ – Hausdorff.

Proof: Let x_1 and x_2 be two distinct points of X . Since f is injective, $f(x_1) \neq f(x_2)$ and since Y is $b\hat{g}$ –ultra Hausdorff, there exists $b\hat{g}$ –copen sets U and V in Y such that $f(x_1) \in U$ and $f(x_2) \in V$ where $U \cap V = \emptyset$. Also $x_1 \in f^{-1}(U)$ and $x_2 \in f^{-1}(V)$ where $f^{-1}(U) \cap f^{-1}(V) = \emptyset$. Hence X is $b\hat{g}$ – Hausdorff.

Theorem 3.38: If a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ is strongly $b\hat{g}$ –continuous function and $g: (Y, \sigma) \longrightarrow (Z, \eta)$ is contra $b\hat{g}$ –continuous function then $g \circ f: (X, \tau) \longrightarrow (Z, \eta)$ is contra continuous.

Proof: Let V be any open set in (Z, η) . Since g is contra $b\hat{g}$ –continuous, then $g^{-1}(V)$ is $b\hat{g}$ –closed in (Y, σ) . Since f is strongly $b\hat{g}$ –continuous, then $f^{-1}(g^{-1}(V)) = (g \circ f)^{-1}(V)$ is closed in (X, τ) . Hence $g \circ f$ is contra continuous.

Theorem 3.39: If a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ is contra $b\hat{g}$ –continuous, injective and Y is Urysohn space, then the topological space X is $b\hat{g}$ – Hausdorff.

Proof: Let x_1 and x_2 be two distinct points of X . Suppose $y_1 = f(x_1)$ and $y_2 = f(x_2)$. Since f is injective, $x_1 \neq x_2$ then $y_1 \neq y_2$. Since Y is Urysohn, there exists open sets V_1 and V_2 containing y_1 and y_2 respectively in Y such that $Cl(V_1) \cap Cl(V_2) = \emptyset$. Since f is contra $b\hat{g}$ –continuous, by theorem 3.21 there exists $b\hat{g}$ –open sets U_1 and U_2 containing x_1 and x_2 respectively in X such that $f(U_1) \subseteq Cl(V_1)$ and $f(U_2) \subseteq Cl(V_2)$. Since $Cl(V_1) \cap Cl(V_2) = \emptyset$, then $U_1 \cap U_2 = \emptyset$. Hence X is $b\hat{g}$ – Hausdorff.

Theorem 3.40: Let $f: (X, \tau) \longrightarrow (Y, \sigma)$ be a function and $g: X \longrightarrow X \times Y$ be a graph function defined by $g(x) = (x, f(x))$ for every $x \in X$. If g is contra $b\hat{g}$ –continuous, then f is contra $b\hat{g}$ – continuous.

Proof: Let V be a closed subset of Y . Then $X \times V$ is a closed subset of $X \times Y$. Since g is contra $b\hat{g}$ –continuous, $g^{-1}(X \times V)$ is $b\hat{g}$ –open subset of X . Also $g^{-1}(X \times V) = f^{-1}(V)$. Hence f is contra $b\hat{g}$ – continuous.

4. Contra $b\hat{g}$ – Irresolute

Definition 4.1: A function $f: (X, \tau) \longrightarrow (Y, \sigma)$ is called contra $b\hat{g}$ –irresolute if $f^{-1}(V)$ is $b\hat{g}$ –closed in (X, τ) for every $b\hat{g}$ –open set V in (Y, σ) .

Example 4.2: Let $X=Y= \{a, b, c, d\}$
 $\tau = \{X, \Phi, \{a\}, \{b, c\}, \{a, b, c\}\}$ and $\sigma = \{Y, \Phi, \{b\}, \{a, b\}, \{b, c, d\}\}$

Define a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ by $f(a) = c, f(b) = a, f(c) = d, f(d) = b$.
 $b\hat{g}\text{--}C(X) = \{X, \Phi, \{a\}, \{b\}, \{c\}, \{d\}, \{b, c\}, \{c, d\}, \{b, d\}, \{a, d\}, \{a, c, d\}, \{a, b, d\}, \{b, c, d\}\}$
 $b\hat{g}\text{--}O(Y) = \{Y, \Phi, \{b\}, \{c\}, \{d\}, \{b, c\}, \{a, b\}, \{b, d\}, \{a, b, c\}, \{a, b, d\}, \{b, c, d\}\}$

Clearly f is contra $b\hat{g}$ – irresolute.

Remark 4.3: The following example show that the concepts of $b\hat{g}$ – irresolute and contra $b\hat{g}$ –irresolute are independent of each other.

Example 4.4: Let $X=Y= \{a, b, c, d\}$
 $\tau = \{X, \Phi, \{a\}, \{b, c\}, \{a, b, c\}\}$ and $\sigma = \{Y, \Phi, \{b\}, \{a, b\}, \{b, c, d\}\}$

Define a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ by $f(a) = c, f(b) = a, f(c) = d, f(d) = b$.
 $b\hat{g}\text{-}C(X) = \{X, \Phi, \{a\}, \{b\}, \{c\}, \{d\}, \{b, c\}, \{c, d\}, \{b, d\}, \{a, d\}, \{a, c, d\}, \{a, b, d\}, \{b, c, d\}\}$
 $b\hat{g}\text{-}O(Y) = \{Y, \Phi, \{b\}, \{c\}, \{d\}, \{b, c\}, \{a, b\}, \{b, d\}, \{a, b, c\}, \{a, b, d\}, \{b, c, d\}\}$

Clearly f is contra $b\hat{g}$ – irresolute, but not $b\hat{g}$ –irresolute. Since the inverse images of $b\hat{g}$ – closed sets $\{c, d\}, \{a, c\}, \{a, c, d\}$ in (Y, σ) are $\{a, c\}, \{a, b\}, \{a, b, c\}$ respectively which are not $b\hat{g}$ – closed in (X, τ) .

Example 4.5: Let $X=Y=\{a, b, c\}$
 $\tau = \{X, \Phi, \{a\}, \{b\}, \{a, b\}, \{a, c\}\}$ and $\sigma = \{Y, \Phi, \{a\}, \{a, b\}, \{a, c\}\}$

Define a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ by $f(a) = a, f(b) = b, f(c) = c$.
 $b\hat{g}\text{-}C(X) = \{X, \Phi, \{b\}, \{c\}, \{a, c\}, \{b, c\}\}$
 $b\hat{g}\text{-}C(Y) = \{Y, \Phi, \{b\}, \{c\}, \{b, c\}\}$

Clearly f is $b\hat{g}$ – irresolute, but not contra $b\hat{g}$ – irresolute. Since the inverse images of $b\hat{g}$ – closed sets $\{a\}$ and $\{a, b\}$ in (Y, σ) are $\{a\}$ and $\{a, b\}$ respectively which are not $b\hat{g}$ – closed in (X, τ) .

Theorem 4.6: Every contra $b\hat{g}$ –irresolute function is contra $b\hat{g}$ – continuous.

Proof: Let V be any open set in (Y, σ) . From [3] Remark 3.23, V is also $b\hat{g}$ –open in (Y, σ) . Since f is contra $b\hat{g}$ – irresolute, $f^{-1}(V)$ is $b\hat{g}$ –Closed in (X, τ) . Hence f is contra $b\hat{g}$ –continuous.

Remark 4.7: The converse of the above theorem need not be true.

(i.e) Every contra $b\hat{g}$ – continuous function need not be contra $b\hat{g}$ –irresolute as shown in the following example.

Example 4.8: Let $X=Y=\{a, b, c\}$
 $\tau = \{X, \Phi, \{a\}, \{b\}, \{a, b\}\}$ and $\sigma = \{Y, \Phi, \{a, b\}, \{c\}\}$

Define a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ by $f(a) = a, f(b) = c, f(c) = b$.
 $b\hat{g}\text{-}C(X) = \{X, \Phi, \{a\}, \{b\}, \{c\}, \{a, c\}, \{b, c\}\}$
 $b\hat{g}\text{-}O(Y) = \{Y, \Phi, \{a\}, \{b\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}\}$

Clearly f is contra $b\hat{g}$ –continuous but not contra $b\hat{g}$ –irresolute. Since the inverse image of a $b\hat{g}$ –open set $\{a, c\}$ in (Y, σ) is $\{a, b\}$ which is not $b\hat{g}$ –closed in (X, τ) .

Remark 4.9: The following example show that the concepts of $b\hat{g}$ – continuous and contra $b\hat{g}$ –continuuous are independent of each other.

Example 4.10: Let $X=Y=\{a, b, c, d\}$
 $\tau = \{X, \Phi, \{b\}, \{a, b\}, \{b, c, d\}\}$ and $\sigma = \{Y, \Phi, \{a\}, \{a, c\}, \{a, b, d\}\}$

Define a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ by $f(a) = a, f(b) = b, f(c) = c, f(d) = d$.
 $b\hat{g}\text{-}C(X) = \{X, \Phi, \{a\}, \{c\}, \{d\}, \{a, c\}, \{c, d\}, \{a, d\}, \{a, c, d\}, \{a, b, c\}, \{a, b, d\}\}$

Clearly f is contra $b\hat{g}$ – continuous, but not $b\hat{g}$ – continuous. Since the inverse images of closed sets $\{b, d\}$ and $\{b, c, d\}$ in (Y, σ) are $\{b, d\}$ and $\{b, c, d\}$ respectively which are not $b\hat{g}$ – closed in (X, τ) .

Example 4.11: Let $X=Y= \{a, b, c, d\}$
 $\tau = \{X, \Phi, \{b\}, \{a, b\}, \{b, c, d\}\}$ and $\sigma = \{Y, \Phi, \{a\}, \{a, c\}, \{a, b, d\}\}$

Define a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ by $f(a) = b, f(b) = a, f(c) = d, f(d) = c$.
 $b\hat{g}\text{-}C(X) = \{X, \Phi, \{a\}, \{c\}, \{d\}, \{a, c\}, \{c, d\}, \{a, d\}, \{a, c, d\}, \{a, b, c\}, \{a, b, d\}\}$

Clearly f is $b\hat{g}$ – continuous, but not contra $b\hat{g}$ – continuous. Since the inverse images of open sets $\{a\}$ and $\{a, c\}$ in (Y, σ) are $\{b\}$ and $\{b, d\}$ respectively which are not $b\hat{g}$ – closed in (X, τ) .

Theorem 4.12: If a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ is contra $b\hat{g}$ –irresolute function and $g: (Y, \sigma) \longrightarrow (Z, \eta)$ is $b\hat{g}$ –irresolute function then $g \circ f: (X, \tau) \longrightarrow (Z, \eta)$ is contra $b\hat{g}$ –irresolute.

Proof: Let V be any $b\hat{g}$ –open set in (Z, η) . Since g is $b\hat{g}$ –irresolute, then $g^{-1}(V)$ is $b\hat{g}$ –open in (Y, σ) . Since f is contra $b\hat{g}$ –irresolute, then $f^{-1}(g^{-1}(V)) = (gof)^{-1}(V)$ is also $b\hat{g}$ –closed in (X, τ) . Hence gof is contra $b\hat{g}$ –irresolute.

Theorem 4.13: If a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ is contra $b\hat{g}$ –irresolute function and $g: (Y, \sigma) \longrightarrow (Z, \eta)$ is $b\hat{g}$ –continuous then $gof: (X, \tau) \longrightarrow (Z, \eta)$ is contra $b\hat{g}$ –continuous.

Proof: Let V be any open set in (Z, η) . Since g is $b\hat{g}$ – continuous, then $g^{-1}(V)$ is $b\hat{g}$ –open in (Y, σ) . Since f is contra $b\hat{g}$ –irresolute, then $f^{-1}(g^{-1}(V)) = (gof)^{-1}(V)$ is $b\hat{g}$ –closed in (X, τ) . Hence gof is contra $b\hat{g}$ – continuous.

5. Perfectly Contra $b\hat{g}$ – Irresolute

Definition 5.1: A function $f: (X, \tau) \longrightarrow (Y, \sigma)$ is called perfectly contra $b\hat{g}$ –irresolute if $f^{-1}(V)$ is $b\hat{g}$ –clopen in (X, τ) for every $b\hat{g}$ –open set V in (Y, σ) .

Example 5.2: Let $X=Y=\{a, b, c\}$
 $\tau = \{X, \Phi, \{a\}, \{b, c\}\}$ and $\sigma = \{Y, \Phi, \{a, c\}\}$

Define a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ by $f(a) = a, f(b) = b, f(c) = c$.

$b\hat{g}\text{-}O(X) = \{X, \Phi, \{a\}, \{b\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}\}$

$b\hat{g}\text{-}C(X) = \{X, \Phi, \{a\}, \{b\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}\}$

$b\hat{g}\text{-}O(Y) = \{Y, \Phi, \{a\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}\}$

Clearly f is perfectly contra $b\hat{g}$ –irresolute, since the inverse images of all $b\hat{g}$ –open sets in Y are $b\hat{g}$ –clopen in X .

Theorem 5.3: Every perfectly contra $b\hat{g}$ –irresolute map is contra $b\hat{g}$ –irresolute

Proof: It directly follows from the definition.

Remark 5.4: The converse of the above theorem need not be true.

(i.e) Every contra $b\hat{g}$ –irresolute map need not be perfectly contra $b\hat{g}$ –irresolute map as shown in the following example.

Example 5.5: Let $X=Y=\{a, b, c\}$
 $\tau = \{X, \Phi, \{a\}\}$ and $\sigma = \{Y, \Phi, \{a, c\}\}$

Define a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ by $f(a) = b, f(b) = a, f(c) = c$.

$b\hat{g}\text{-}O(X) = \{X, \Phi, \{a\}, \{b\}, \{c\}, \{a, b\}, \{a, c\}\}$

$b\hat{g}\text{-}C(X) = \{X, \Phi, \{b\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}\}$

$b\hat{g}\text{-}O(Y) = \{Y, \Phi, \{a\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}\}$

Clearly f is contra $b\hat{g}$ –irresolute but not perfectly contra $b\hat{g}$ –irresolute. Since the inverse image of $b\hat{g}$ –open set $\{a, c\}$ in Y is $\{b, c\}$ which is not $b\hat{g}$ –clopen in X .

Theorem 5.6: Every perfectly contra $b\hat{g}$ –irresolute map is $b\hat{g}$ –irresolute

Proof: It directly follows from the definition.

Remark 5.7: The converse of the above theorem need not be true.

(i.e) Every $b\hat{g}$ –irresolute map need not be perfectly contra $b\hat{g}$ –irresolute map as shown in the following example.

Example 5.8: Let $X=Y=\{a, b, c, d\}$
 $\tau = \{X, \Phi, \{a\}, \{a, c\}, \{a, b, d\}\}$ and $\sigma = \{Y, \Phi, \{b\}, \{a, b\}, \{b, c, d\}\}$

Define a function $f: (X, \tau) \longrightarrow (Y, \sigma)$ by $f(a) = b, f(b) = a, f(c) = c, f(d) = d$.

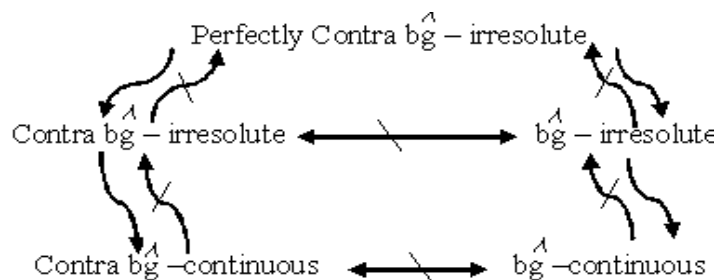
$b\hat{g}\text{-}O(X) = \{X, \Phi, \{a\}, \{b\}, \{c\}, \{d\}, \{a, b\}, \{a, c\}, \{a, d\}, \{a, c, d\}, \{a, b, c\}, \{a, b, d\}\}$

$b\hat{g}\text{-}C(X) = \{X, \Phi, \{b\}, \{c\}, \{d\}, \{b, c\}, \{c, d\}, \{b, d\}, \{a, c, d\}, \{a, b, c\}, \{a, b, d\}, \{b, c, d\}\}$

$b\hat{g}\text{-}O(Y) = \{Y, \Phi, \{b\}, \{c\}, \{d\}, \{a, b\}, \{b, c\}, \{b, d\}, \{b, c, d\}, \{a, b, c\}, \{a, b, d\}\}$

Clearly f is $b\hat{g}$ -irresolute, but not perfectly contra $b\hat{g}$ -irresolute. Since the inverse images of $b\hat{g}$ –open sets $\{b\}$, $\{a, b\}$, $\{b, c\}$ and $\{b, d\}$ in Y are $\{a\}$, $\{a, b\}$, $\{a, c\}$ and $\{a, d\}$ respectively which are not $b\hat{g}$ – clopen in (X, τ) .

Remark 5.9: From the above discussions and known results, we have the following diagram.



In this diagram, $A \rightarrow B$ means A implies B but not conversely. $A \leftrightarrow B$ means A and B are independent of each other.

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